

Supplementary Material

Appendix I.

1. Definition of the cost function.

Input: $solution_1 . . . solution_N$

Output: $cost$ (Total cost of the solution)

function $fitness_function(solution[], dest)$

$total_{price} = 0, last_{arrival} = 0$ # 0:00 time

$first_{departure} = 1439$ # 23:59 for initialization

$flight_{id} = -1$

for $i \leftarrow 1$ *to* $\frac{length(solution)}{2}$ *do*

$origin = people[i][1]$

$flight_{id} += 1$

$going = flights[(origin, dest)][solution[flight_{id}]]$

$flight_{id} += 1$

$returning = flights[(dest, origin)][solution[flight_{id}]]$

$total_{price} += going[2]$

$total_{price} += returning[2]$

if $last_{arrival} < get_minutes(going[1])$ *then* # Find last arrival

$last_{arrival} = get_minutes(going[1])$

end if

if $first_{departure} < get_minutes(returning[0])$ *then* # Find first departure

$first_{departure} = get_minutes(returning[0])$

end if

end for

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    totalwait = 0

    flightid = - 1

    for i ← 1 to  $\frac{\text{length}(\text{solution})}{2}$  do

        origin = people[i][1]

        flightid += 1

        going = flights[(origin, dest)][solution[flightid]]

        flightid += 1

        returning = flights[(dest, origin)][solution[flightid]]

        # Waiting time for all arrived

        totalwait += lastarrival - get_minutes(going[1])

        # Waiting time for all to depart and reach location

        totalwait += get_minutes(returning[0]) - first_departure

    end for

    # 3PM - 10AM

    # 11AM - 3PM

    if lastarrival > firstdeparture then

        # Penalize if arrival and departure are not on same days

        totalprice += 50

    end if

    return totalprice + totalwait # The total cost associated

end function

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Appendix II.

1.Time Complexity Derivations

In the following Appendix we derive the Time Complexity of our algorithms, by first calculating the running time and then derive the upper bounds(worst case) by setting maximum values of N.

1.1 Cost Function

$S \rightarrow$ Length of initial Solution/Individual

Time Complexity Derivation:

$$T(S) = S/2 + S/2;$$

\therefore Time Complexity is $O(N)$

1.2 OnePoint Mutation and Crossover

By ignoring the operation of copying N elements $O(N)$, gene selection then takes $O(1)$, as random.randint uses the **Mersenne-Twister** algorithm which is $O(1)$.

\therefore Time Complexity is **$O(1)$** .

1.3 Random Search

$E \rightarrow$ Epochs

$D \rightarrow$ Length of Domain

$S \rightarrow$ Length of initial Population/Solution

Time Complexity:

$$T(N) = D + E * (S/2) + (E - 1) * D; O(T(N)) = O(ES/2 + E - 1 * D) ;$$

$$T(N) = N^2/2$$

\therefore Time complexity is $O(N^2)$

1.4 Hill Climbing

$E \rightarrow$ Epochs

$D \rightarrow$ Length of Domain

$S \rightarrow$ Length of initial Population/Solution

$n \rightarrow$ Number of neighboring solutions

$$T(N) = D + S/2 + n * (S/2) ;$$

\therefore Time Complexity is $O(N^2)$

1.5 Standard GA Configuration

$P \rightarrow$ Population Size

$G \rightarrow$ Number of Generations'

$D \rightarrow$ Length of Domain

$S \rightarrow$ Length of Solution/Individual

$C \rightarrow$ Length of array of Costs

$P_m \rightarrow$ Probability of Mutation

$P_c \rightarrow$ Probability of Crossover, $P_c = 1 - P_m$

$$T(N) = P * D + G * ((P + 1) * S/2 + C \log C + P * (P_m * 1 + P_c * 1))$$

this can be simplified to $T(N) = N^3/2 + N^3 \log N$,

\therefore Time Complexity is $O(N^3 \log N)$

The choice of sorting function is responsible for $\log N$. Python's default *Tim Sort* instead of doing Heapify operations which reduces worst case complexity from $O(N^3 \log N)$ to $O(N^3)$.

1.6 GA with Reverse Operations

$P \rightarrow$ Population Size

$G \rightarrow$ Number of Generations

$D \rightarrow$ Length of Domain

$S \rightarrow$ Length of Solution/Individual

$C \rightarrow$ Length of array of Costs

$P_c \rightarrow$ Probability of Crossover

$P_m \rightarrow$ Probability of Mutation $P_m = 1 - P_c$

$$T(N) = P * D + G * ((P + 1) * S/2 + C \log C + P * (P_c * 1 + P_m * 1))$$

this is of the form

$$O(N) = N^3/2 + N^3 \log N,$$

$$\therefore O(N) = N^3 \log N$$

1.7 GAs with Reversals

$P \rightarrow$ Population Size

$R \rightarrow$ Number of Reversals.

$G \rightarrow$ Number of Generations

$step_{length} \rightarrow$ The number of reverse steps/epochs

The number of reversals is calculated as follows:

$$R = G/n_k - 1$$

$$T_R(N) = C; \text{ if } step_{length} = 1 \text{ else}$$

$$T_R(N) = (step_{length-1}) * (C + S/2 + P * (Pc * 1 + Pm * 1))$$

Now actual Time Complexity of GA with Reversals is,

$$T(N) = T(N) + T_R(N)$$

$$T(N) = P * D + G * ((P + 1) * S/2 + C \log C + R * C + P * (Pm * 1 + Pc * 1));$$

$$\text{if } step_{length} = 1 \text{ else}$$

$$T(N) = P * D + G * ((P + 1) * S/2 + C \log C + R * ((step_{length-1}) * (C + S/2 + P * (Pc * 1 + Pm * 1)))$$

$$+ P * (Pm * 1 + Pc * 1))$$

This further reduces to these 2 forms:

$$T(N) = N^3/2 + N^3 = 3/2 N^3 = N^3; \text{ if } step_{length} = 1 \text{ else}$$

$$T(N) = N^3/2 + N^4, \text{ therefore Time Complexity is } O(N^4);$$

1.8 Iterated Chaining

Rounds → The number of iterated Chaining rounds

$$T(N) = Rounds - 1 * T_{algo_1}(N) + Rounds * T_{algo_2}(N)$$

The authors chose $algo_1$ as *Random Search* and $algo_2$ as *HillClimbing*, thus:

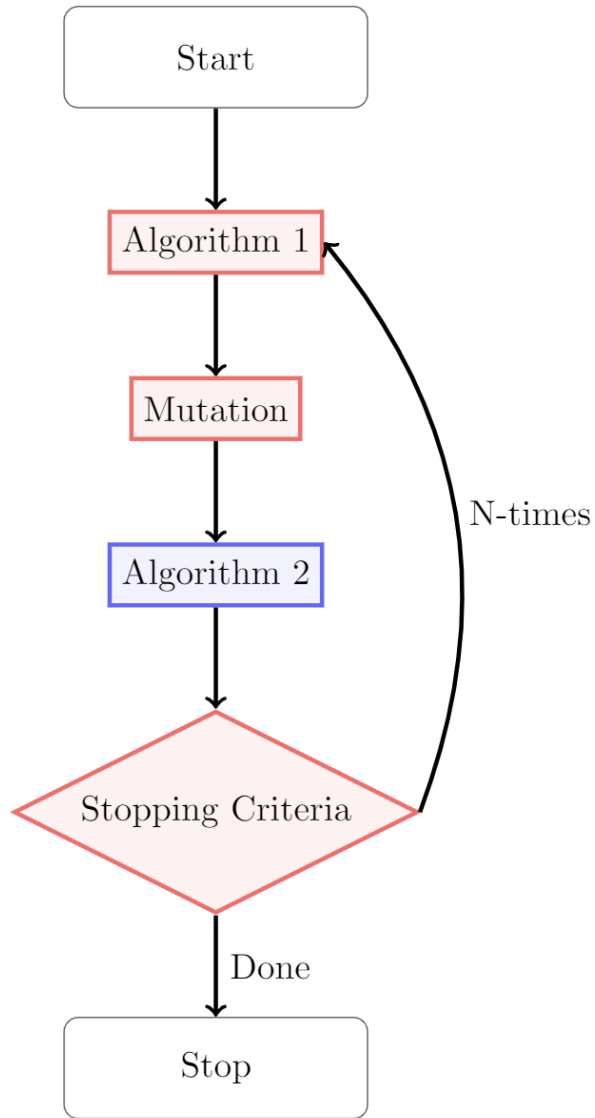
$$T(N) = Rounds - 1 * T_{RS}(N) + Rounds * T_{algo_2}(N)$$

$$T(N) = Rounds - 1 * D + E * (S/2) + (E - 1) * D + Rounds * D + S/2 + n * (S/2)$$

$$T(N) = N^3 - 1 + N^3$$

$$\therefore \text{Time Complexity is } O(N^3)$$

Appendix III.

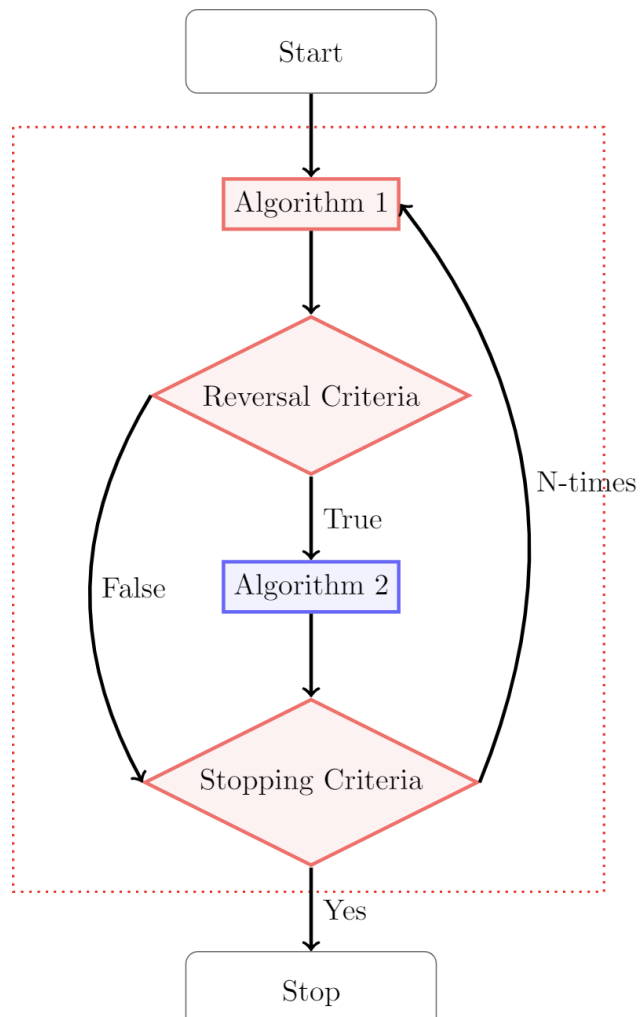


Iterated Chaining Algorithm

ALGORITHM : ITERATED CHAINING WITH EARLY STOPPING
Input: Domain D_1, \dots, D_N , rounds, fitness_function, n_{obs} , tolerance
Output: $soln_{final}, best_{cost}, scores, NFE, nfe, seed$

1	<i>scores</i> ← [], <i>NFE</i> ← 0 //Global record of cost and no. of function evaluations
2	for <i>i</i> ← rounds do
3	if <i>i</i> ==0 then
4	<i>soln</i> , <i>cost</i> , <i>scores</i> , <i>nfe</i> , <i>seed</i> ← <i>algorithm_1</i> (<i>domain</i> , <i>fitness_function</i> , <i>seed</i>)
5	<i>soln</i> ← <i>OnePointMutation</i> (<i>domain</i> , <i>random.randint</i> (0, 1), <i>soln</i>)
6	<i>scores</i> ← append <i>cost</i> to list
7	<i>NFE</i> ← <i>nfe</i> +1
8	end if
9	else if <i>i</i> == rounds – 1 then
10	<i>soln_{final}</i> , <i>cost</i> , <i>scores</i> , <i>nfe</i> , <i>seed</i> ← <i>algorithm_2</i> (<i>domain</i> , <i>fitness_function</i> , <i>seed</i>)
11	<i>scores</i> ← append <i>cost</i> to list
12	return <i>soln_{final}</i> , <i>scores</i> [-1], <i>scores</i> , <i>NFE</i>
13	<i>NFE</i> ← <i>nfe</i> +1
14	end if
15	else
16	<i>soln</i> , <i>cost</i> , <i>scores</i> , <i>nfe</i> , <i>seed</i> ← <i>algorithm_1</i> (<i>domain</i> , <i>fitness_function</i> , <i>seed</i>)
17	<i>soln</i> ← <i>OnePointMutation</i> (<i>domain</i> , <i>random.randint</i> (0, 1), <i>soln</i>)
18	<i>scores</i> ← append <i>cost</i> to list
19	<i>NFE</i> ← <i>nfe</i> +1
20	end else
21	<i>soln_{final}</i> , <i>cost</i> , <i>scores</i> , <i>nfe</i> , <i>seed</i> ← <i>algorithm_2</i> (<i>domain</i> , <i>fitness_function</i> , <i>seed</i>)
22	<i>scores</i> ← append <i>cost</i> to list
23	<i>NFE</i> ← <i>nfe</i> + 1
24	
25	if rounds ==1 then
26	return <i>soln</i> , <i>scores</i> [-1], <i>scores</i> , <i>NFE</i>
27	end if
28	if <i>cost</i> - <i>random.randint</i> (tolerance, 100) > <i>int</i> (<i>sum</i> (<i>scores</i> [- <i>n_{obs}</i> :]) / <i>n_{obs}</i>) then
29	return <i>soln_{final}</i> , <i>scores</i> [-1], <i>scores</i> , <i>NFE</i>
30	end if

Where *scores*[-1] is *best_{cost}*, i.e the final cost; *NFE* is the global list of costs



ALGORITHM : GENETIC ALGORITHM WITH REVERSALS

Input: Domain D_1, \dots, D_N , P_{mutation} , $P_{\text{crossover}}$, n_k , $\text{step}_{\text{length}}$, $\text{num}_{\text{generations}}$, fitness_function , n_{obs}

$\text{population}_{\text{size}}$

Output: $\text{soln}_{\text{final}}$, $\text{best}_{\text{cost}}$, scores , nfe , seed

for $i \leftarrow \text{num}_{\text{generations}}$ **then**

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1  population ← Initialize population randomly
2  if  $i/n_k == 0$  and  $i \neq 0$  then
3      if  $\text{step}_{\text{length}} == 1$  then
4          Sort costs list in descending order instead
5           $\text{rev} \leftarrow \text{rev} + 1$ 
6      end if
7      else
8           $\text{rev} \leftarrow \text{rev} + 1$ 
9          while  $i \leftarrow \text{step}_{\text{length}}$  do
10             costs.sort(reverse=True) //Decreasing order of costs
11             ordered_individuals = [individual for (cost, individual) in costs]
12             population ← Get to a list of top  $n_{\text{elitism}}$  from ordered_individuals
13             scores ← fitness_function(population[0])
14              $\text{nfe} \leftarrow \text{nfe} + 1$ 
15             while length of population list < population_size do
16                 if random.random() <  $P_{\text{mutation}}$  then
17                     :
18                     population ← Append result of Crossover of 2 randomly
19                     chosen individuals from ordered_individuals
20                 end if
21                 else
22                     population ← Append result of OnePointMutation of a randomly
23                     chosen individual from ordered_individuals
24                 end else
25             end while
26         end while
27     end if
28     else
29         costs.sort() //Increasing order of costs
30         ordered_individuals = [individual for (cost, individual) in costs]
31         population ← Get to a list of top  $n_{\text{elitism}}$  from ordered_individuals
32         scores ← fitness_function(population[0])
33          $\text{nfe} \leftarrow \text{nfe} + 1$ 
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34	while length of population list < population_size do
35	if random.random() < $P_{mutation}$ then
36	population \leftarrow Append result of Crossover of 2 randomly
37	chosen individuals from ordered_individuals
38	end if
39	else
40	population \leftarrow Append result of OnePointMutation of a randomly
41	chosen individual from ordered_individuals
42	end else
43	end while
44	end else
45	end for
46	return soln _{final} , best _{cost} scores, nfe, seed

ALGORITHM : GENETIC ALGORITHM WITH RANDOM SEARCH REVERSALS	
Input: Domain D_1, \dots, D_N , $P_{mutation}$, $P_{crossover}$, n_k , step _{length} , num _{generations} , fitness_function, n_{obs}	
, population _{size}	
Output: soln _{final} , best _{cost} scores, nfe, seed	
for i \leftarrow num _{generations} then 1 population \leftarrow Initialize population randomly 2 if $i/n_k == 0$ and $i \neq 0$ then 3 if step _{length} == 1 then 4 Sort costs list in descending order instead 5 rev \leftarrow rev+1 6 end if 7 else 8 rev \leftarrow rev+1 9 while i \leftarrow step _{length} do 10 costs.sort(reverse=True) //Decreasing order of costs 11 soln \leftarrow Randomly initialize within U.B and L.B of D 12 population \leftarrow Get to a list of top $n_{eltisim}$ from ordered_individuals 13 scores \leftarrow fitness_function(population [0])	

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14         nfe ← nfe+1
15         if cost > best_cost then
16             :
17             | best_cost ← cost
18             | best_solution ← solution
19         end if
20         scores ← Append best_cost
21         population ← Append best_soln
22     end while
23 end else
24 end if
25 else
26     costs.sort() //Increasing order of costs
27     ordered_individuals = [individual for (cost, individual) in costs]
28     population ← Get to a list of top  $n_{elitisim}$  from ordered_individuals
29     scores ← fitness_function(population [0])
30     nfe ← nfe+1
31     while length of population list < population_size do
32         if random.random() <  $P_{mutation}$  then
33             | population ← Append result of Crossover of 2 randomly
34             | chosen individuals from ordered_individuals
35         end if
36         else
37             | population ← Append result of OnePointMutation of a randomly
38             | chosen individual from ordered_individuals
39         end else
40     end while
41 end else
42 end for
43 return solnfinal, bestcost, scores, nfe, seed

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