

DeepWalk and node2vec: Implementation details

Gabriele Santin¹

MobS¹ Lab, Fondazione Bruno Kessler, Trento, Italy



Recap **01**

Biased random walks
Code and examples **02**

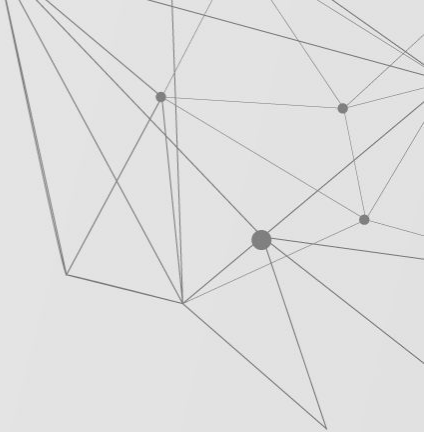
TABLE OF CONTENTS

03

Simplifying the loss
node2vec vs DeepWalk

04

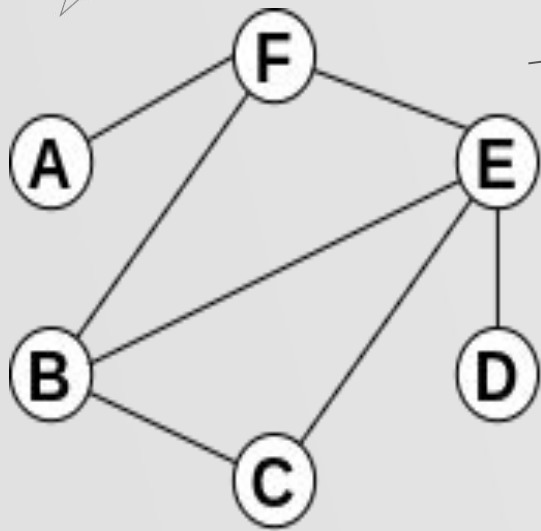
node2vec
Full implementation



01 Learning graph representations

Goal:

- Find a good representation of a graph $G = (V, E)$



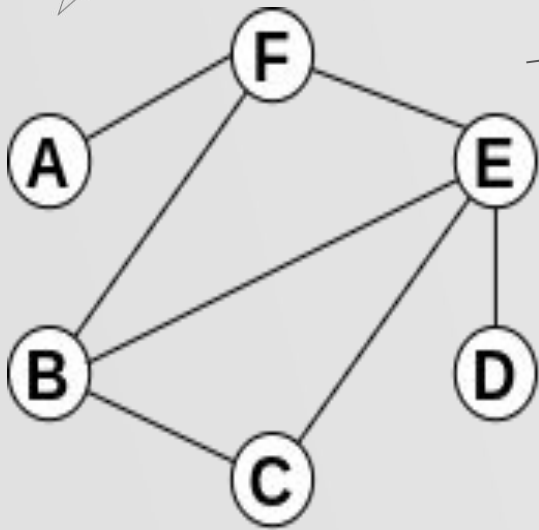
Node embedding:

$$v \mapsto [f_1(v), \dots, f_d(v)]$$

01 Learning graph representations

Goal:

- Find a good representation of a graph $G = (V, E)$



Node embedding:

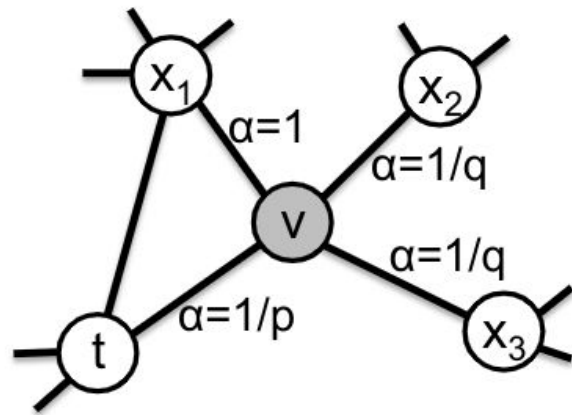
$$v \mapsto [f_1(v), \dots, f_d(v)]$$

Strategy:

- Optimize embedding to **preserve similarities**
- Similarities defined as a “**neighborhood**” notion
- Use (biased) **random walks** to define neighborhood

02 Biased random walks

$$P(N_{i+1} = v | N_i = u) = \begin{cases} \frac{\pi_{vu}}{Z} & \text{if } (v, u) \in E \\ 0 & \text{otherwise} \end{cases}$$



02 Biased random walks

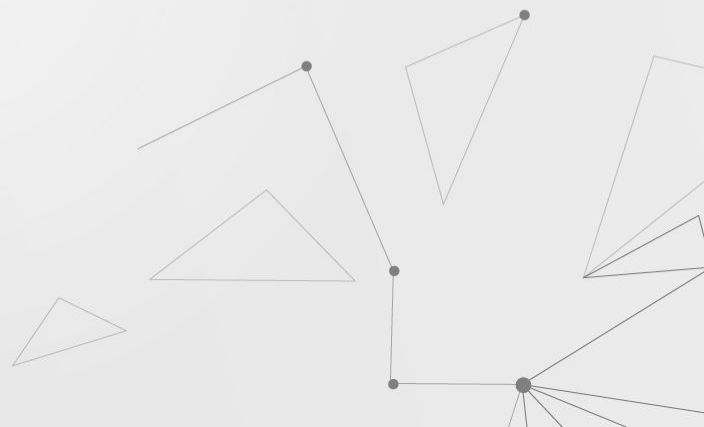
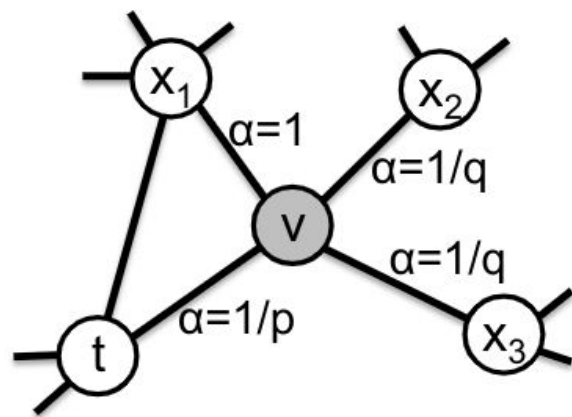
Unbiased random walk

$$P(N_{i+1} = v | N_i = u) = \begin{cases} \frac{\pi_{vu}}{Z} & \text{if } (v, u) \in E \\ 0 & \text{otherwise} \end{cases}$$

π_{uv}

Transition probability, e.g.

$$\pi_{uv} = w_{vu}$$



02 Biased random walks

Unbiased random walk

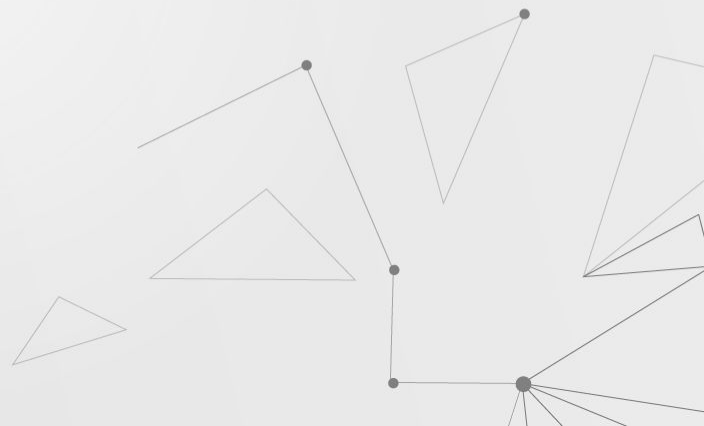
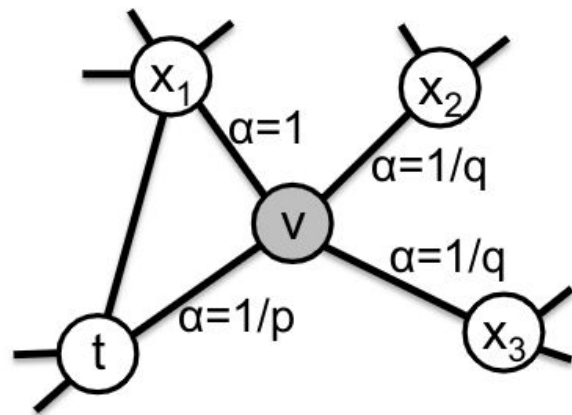
$$P(N_{i+1} = v | N_i = u) = \begin{cases} \frac{\pi_{vu}}{Z} & \text{if } (v, u) \in E \\ 0 & \text{otherwise} \end{cases}$$

Z Normalization factor

π_{uv}

Transition probability, e.g.

$$\pi_{uv} = w_{vu}$$



02 Biased random walks

Unbiased random walk

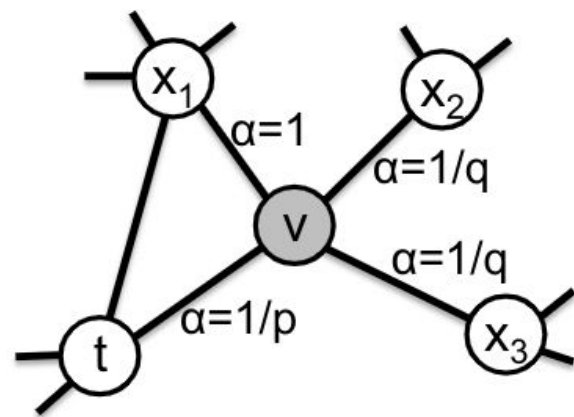
$$P(N_{i+1} = v | N_i = u) = \begin{cases} \frac{\pi_{vu}}{Z} & \text{if } (v, u) \in E \\ 0 & \text{otherwise} \end{cases}$$

Z Normalization factor

π_{uv}

Transition probability, e.g.

$$\pi_{uv} = w_{vu}$$



Biased random walk

$$\alpha_{pq}(t, x) = \begin{cases} \frac{1}{p} & \text{if } d_{tx} = 0 \\ 1 & \text{if } d_{tx} = 1 \\ \frac{1}{q} & \text{if } d_{tx} = 2 \end{cases}$$

Biased transition probability

$$\pi_{vx} = \alpha_{pq}(t, x) \cdot w_{vx}$$

02 Biased random walks

Unbiased random walk

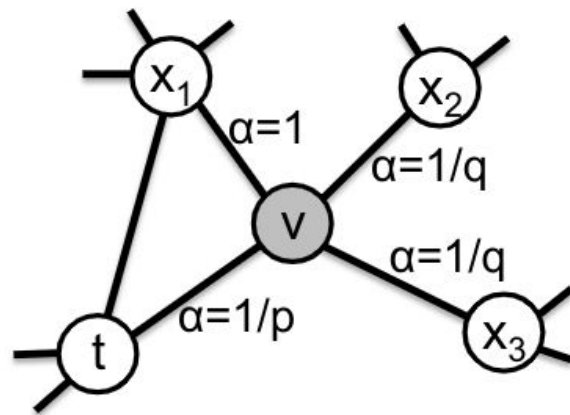
$$P(N_{i+1} = v | N_i = u) = \begin{cases} \frac{\pi_{vu}}{Z} & \text{if } (v, u) \in E \\ 0 & \text{otherwise} \end{cases}$$

Z Normalization factor

π_{uv}

Transition probability, e.g.

$$\pi_{uv} = w_{vu}$$



Biased random walk

$$\alpha_{pq}(t, x) = \begin{cases} \frac{1}{p} & \text{if } d_{tx} = 0 \\ 1 & \text{if } d_{tx} = 1 \\ \frac{1}{q} & \text{if } d_{tx} = 2 \end{cases}$$

Search bias

Biased transition probability

$$\pi_{vx} = \alpha_{pq}(t, x) \cdot w_{vx}$$

02 Biased random walks

Unbiased random walk

$$P(N_{i+1} = v | N_i = u) = \begin{cases} \frac{\pi_{vu}}{Z} & \text{if } (v, u) \in E \\ 0 & \text{otherwise} \end{cases}$$

π_{uv}

Transition probability, e.g.

$$\pi_{uv} = w_{vu}$$

return parameter p:

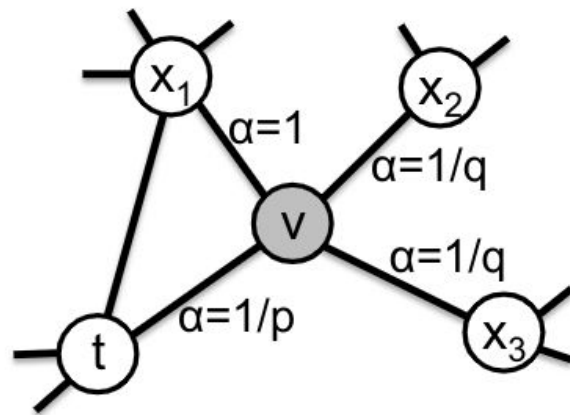
- large -> exploration
- small -> backtrack, local

in-out parameter q:

- large -> stay close to t
- small -> exploration

DeepWalk: $q=p=1$

Z Normalization factor



Biased random walk

$$\alpha_{pq}(t, x) = \begin{cases} \frac{1}{p} & \text{if } d_{tx} = 0 \\ 1 & \text{if } d_{tx} = 1 \\ \frac{1}{q} & \text{if } d_{tx} = 2 \end{cases}$$

Search bias

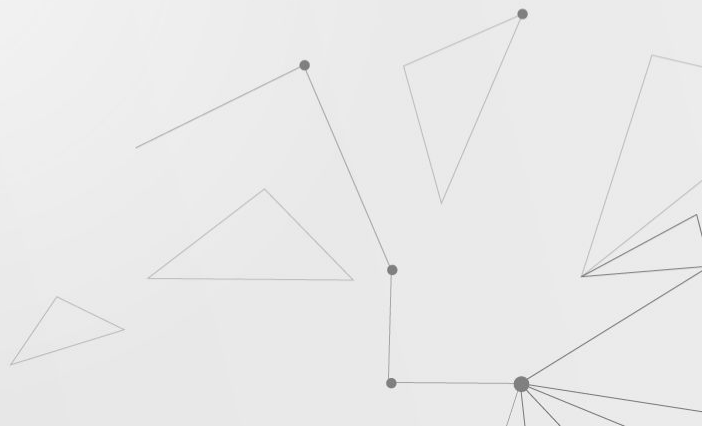
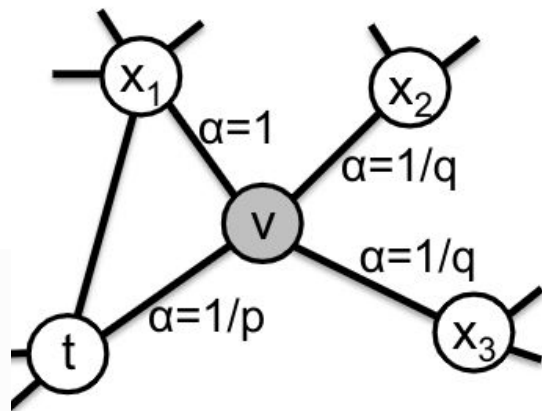
Biased transition probability

$$\pi_{vx} = \alpha_{pq}(t, x) \cdot w_{vx}$$

02 Biased random walks

```
CLASS Node2Vec ( edge_index, embedding_dim, walk_length, context_size, walks_per_node=1, p=1, q=1,
num_negative_samples=1, num_nodes=None, sparse=False ) \[source\]
```

The Node2Vec model from the “[node2vec: Scalable Feature Learning for Networks](#)” paper where random walks of length `walk_length` are sampled in a given graph, and node embeddings are learned via negative sampling optimization.

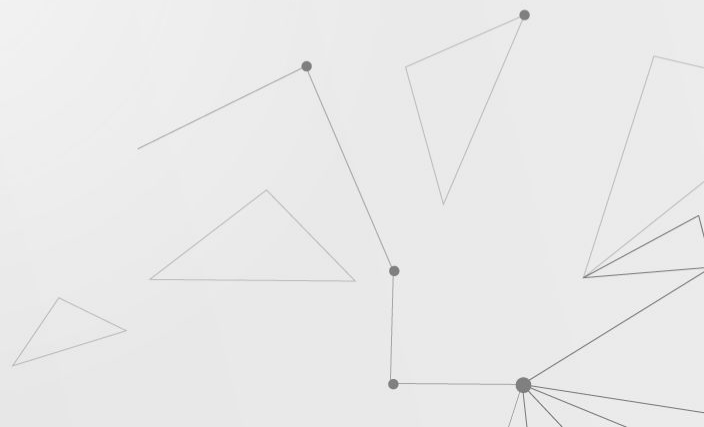
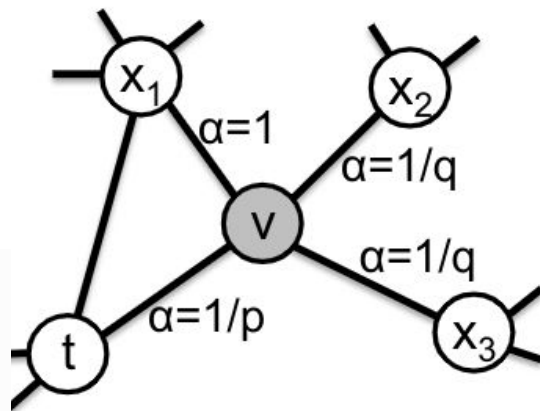


02 Biased random walks

Length

```
CLASS Node2Vec ( edge_index, embedding_dim, walk_length, context_size, walks_per_node=1, p=1, q=1,  
num_negative_samples=1, num_nodes=None, sparse=False ) [source]
```

The Node2Vec model from the “[node2vec: Scalable Feature Learning for Networks](#)” paper where random walks of length `walk_length` are sampled in a given graph, and node embeddings are learned via negative sampling optimization.



02 Biased random walks

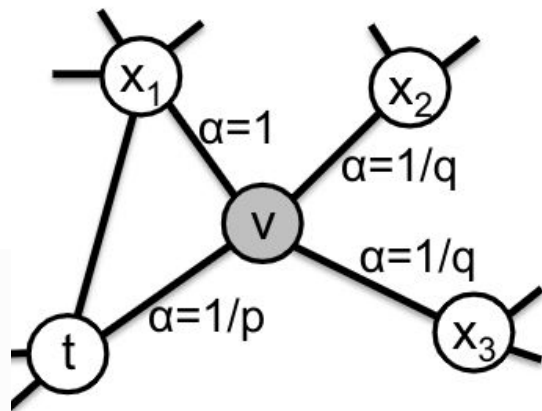
Length

```
CLASS Node2Vec ( edge_index, embedding_dim, walk_length, context_size, walks_per_node=1, p=1, q=1,  
num_negative_samples=1, num_nodes=None, sparse=False ) [source]
```

The Node2Vec model from the “[node2vec: Scalable Feature Learning for Networks](#)” paper where random walks of length `walk_length` are sampled in a given graph, and node embeddings are learned via negative sampling optimization.

Return parameter

In-out parameter



02 Biased random walks

Length

```
CLASS Node2Vec ( edge_index, embedding_dim, walk_length, context_size, walks_per_node=1, p=1, q=1,  
num_negative_samples=1, num_nodes=None, sparse=False ) [source]
```

The Node2Vec model from the “node2vec: Scalable Feature Learning for Networks” paper where random walks of length `walk_length` are sampled in a given graph, and node embeddings are learned via negative sampling optimization.

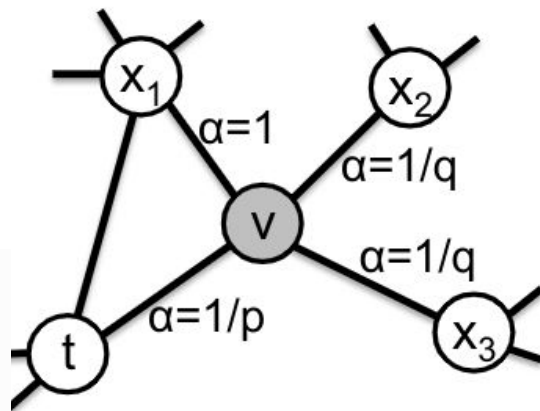
Return parameter

In-out parameter

Length of the RW to extract from a long sample

Sample **$l=6, k=3$** : {u, s4, s5, s6, s8, s9}

1. **u**: s4,s5,s6
2. **s4**: s5,s6,s8
3. **s5**: s6,s8,s9



02 Biased random walks

Length

```
CLASS Node2Vec ( edge_index, embedding_dim, walk_length, context_size, walks_per_node=1, p=1, q=1,  
num_negative_samples=1, num_nodes=None, sparse=False ) [source]
```

The Node2Vec model from the “node2vec: Scalable Feature Learning for Networks” paper where random walks of length `walk_length` are sampled in a given graph, and node embeddings are learned via negative sampling optimization.

```
loader ( **kwargs )
```

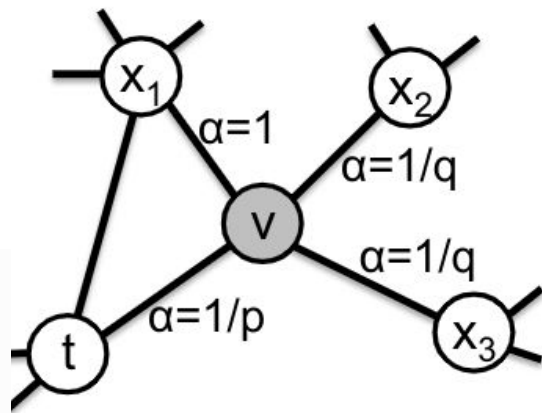
Return parameter

In-out parameter

Length of the RW to extract from a long sample

Sample **$l=6$** , **$k=3$** : {u, s4, s5, s6, s8, s9}

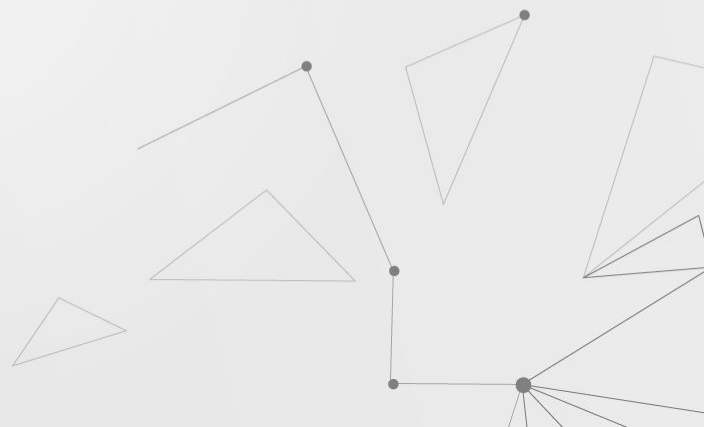
1. **u**: s4,s5,s6
2. **s4**: s5,s6,s8
3. **s5**: s6,s8,s9



02 Biased random walks

```
def loader(self, **kwargs):  
    return DataLoader(range(self.adj.sparse_size(0)),  
                      collate_fn=self.sample, **kwargs)
```

Loader over list of nodes



02 Biased random walks

```
def loader(self, **kwargs):  
    return DataLoader(range(self.adj.sparse_size(0)),  
                      collate_fn=self.sample, **kwargs)
```

Loader over list of nodes

```
def sample(self, batch):  
    if not isinstance(batch, torch.Tensor):  
        batch = torch.tensor(batch)  
    return self.pos_sample(batch), self.neg_sample(batch)
```

02 Biased random walks

```
def loader(self, **kwargs):  
    return DataLoader(range(self.adj.sparse_size(0)),  
                      collate_fn=self.sample, **kwargs)
```

Loader over list of nodes

```
def sample(self, batch):  
    if not isinstance(batch, torch.Tensor):  
        batch = torch.tensor(batch)  
    return self.pos_sample(batch), self.neg_sample(batch)
```

A batch of indices

02 Biased random walks

```
def loader(self, **kwargs):  
    return DataLoader(range(self.adj.sparse_size(0)),  
                      collate_fn=self.sample, **kwargs)
```

Loader over list of nodes

```
def sample(self, batch):  
    if not isinstance(batch, torch.Tensor):  
        batch = torch.tensor(batch)  
    return self.pos_sample(batch), self.neg_sample(batch)
```

A batch of indices

```
def pos_sample(self, batch):  
    batch = batch.repeat(self.walks_per_node)  
  
    rowptr, col, _ = self.adj.csr()  
    rw = random_walk(rowptr, col, batch, self.walk_length, self.p, self.q)  
    if not isinstance(rw, torch.Tensor):  
        rw = rw[0]  
  
    walks = []  
    num_walks_per_rw = 1 + self.walk_length + 1 - self.context_size  
    for j in range(num_walks_per_rw):  
        walks.append(rw[:, j:j + self.context_size])  
    return torch.cat(walks, dim=0)
```

102
103
104
105
106
107
108
109
110
111
112
113
114

```
def neg_sample(self, batch):  
    batch = batch.repeat(self.walks_per_node * self.num_negative_samples)  
  
    rw = torch.randint(self.adj.sparse_size(0),  
                      (batch.size(0), self.walk_length))  
    rw = torch.cat([batch.view(-1, 1), rw], dim=-1)  
  
    walks = []  
    num_walks_per_rw = 1 + self.walk_length + 1 - self.context_size  
    for j in range(num_walks_per_rw):  
        walks.append(rw[:, j:j + self.context_size])  
    return torch.cat(walks, dim=0)
```

02 Biased random walks

```
def loader(self, **kwargs):  
    return DataLoader(range(self.adj.sparse_size()),  
                      collate_fn=self.sample, **kwargs)
```

Loader over list of nodes

```
def sample(self, batch):  
    if not isinstance(batch, torch.Tensor):  
        batch = torch.tensor(batch)  
    return self.pos_sample(batch), self.neg_sample(batch)
```

As before

A batch of indices

```
def pos_sample(self, batch):  
    batch = batch.repeat(self.walks_per_node)  
  
    rowptr, col, _ = self.adj.csr()  
    rw = random_walk(rowptr, col, batch, self.walk_length, self.p, self.q)  
    if not isinstance(rw, torch.Tensor):  
        rw = rw[0]  
  
    walks = []  
    num_walks_per_rw = 1 + self.walk_length + 1 - self.context_size  
    for j in range(num_walks_per_rw):  
        walks.append(rw[:, j:j + self.context_size])  
    return torch.cat(walks, dim=0)
```

102
103
104
105
106
107
108
109
110
111
112
113
114

```
def neg_sample(self, batch):  
    batch = batch.repeat(self.walks_per_node * self.num_negative_samples)  
  
    rw = torch.randint(self.adj.sparse_size(),  
                      (batch.size(0), self.walk_length))  
    rw = torch.cat([batch.view(-1, 1), rw], dim=-1)  
  
    walks = []  
    num_walks_per_rw = 1 + self.walk_length + 1 - self.context_size  
    for j in range(num_walks_per_rw):  
        walks.append(rw[:, j:j + self.context_size])  
    return torch.cat(walks, dim=0)
```

Initial nodes

torch.ops.torch_cluster.random_walk

02 Biased random walks

```
def loader(self, **kwargs):  
    return DataLoader(range(self.adj.sparse_size(0)),  
                      collate_fn=self.sample, **kwargs)
```

Loader over list of nodes

```
def sample(self, batch):  
    if not isinstance(batch, torch.Tensor):  
        batch = torch.tensor(batch)  
    return self.pos_sample(batch), self.neg_sample(batch)
```

As before

A batch of indices

```
def pos_sample(self, batch):  
    batch = batch.repeat(self.walks_per_node)  
  
    rowptr, col, _ = self.adj.csr()  
    rw = random_walk(rowptr, col, batch, self.walk_length, self.p, self.q)  
    if not isinstance(rw, torch.Tensor):  
        rw = rw[0]  
  
    walks = []  
    num_walks_per_rw = 1 + self.walk_length + 1 - self.context_size  
    for j in range(num_walks_per_rw):  
        walks.append(rw[:, j:j + self.context_size])  
    return torch.cat(walks, dim=0)
```

102
103
104
105
106
107
108
109
110
111
112
113
114

```
def neg_sample(self, batch):  
    batch = batch.repeat(self.walks_per_node * self.num_negative_samples)  
  
    rw = torch.randint(self.adj.sparse_size(0),  
                      (batch.size(0), self.walk_length))  
    rw = torch.cat([batch.view(-1, 1), rw], dim=-1)  
  
    walks = []  
    num_walks_per_rw = 1 + self.walk_length + 1 - self.context_size  
    for j in range(num_walks_per_rw):  
        walks.append(rw[:, j:j + self.context_size])  
    return torch.cat(walks, dim=0)
```

Initial nodes

`torch.ops.torch_cluster.random_walk`

A fake RW



02 Biased random walks

... notebook ...



03 Simplifying the loss

Definition of the embedding $f(v)$

```
self.embedding = Embedding(N, embedding_dim, sparse=sparse)
```

torch.nn.Embedding

03 Simplifying the loss

Definition of the embedding $f(v)$

```
self.embedding = Embedding(N, embedding_dim, sparse=sparse)
```

torch.nn.Embedding

```
CLASS torch.nn.Embedding(num_embeddings, embedding_dim, padding_idx=None, max_norm=None,  
                          norm_type=2.0, scale_grad_by_freq=False, sparse=False, _weight=None)
```

[SOURCE]

A simple lookup table that stores embeddings of a fixed dictionary and size.

This module is often used to store word embeddings and retrieve them using indices. The input to the module is a list of indices, and the output is the corresponding word embeddings.

03 Simplifying the loss

Definition of the embedding $f(v)$

```
self.embedding = Embedding(N, embedding_dim, sparse=sparse)
```

torch.nn.Embedding

```
CLASS torch.nn.Embedding(num_embeddings, embedding_dim, padding_idx=None, max_norm=None,  
                          norm_type=2.0, scale_grad_by_freq=False, sparse=False, _weight=None)
```

[SOURCE]

A simple lookup table that stores embeddings of a fixed dictionary and size.

This module is often used to store word embeddings and retrieve them using indices. The input to the module is a list of indices, and the output is the corresponding word embeddings.

- **sparse** (*bool, optional*) – If `True`, gradient w.r.t. `weight` matrix will be a sparse tensor. See Notes for more details regarding sparse gradients.

03 Simplifying the loss

The loss maximizes the
probability of a neighborhood given u

$$P_f(v|u) := \frac{\exp(f(v)^T f(u))}{\sum_{w \in V} \exp(f(w)^T f(u))}$$

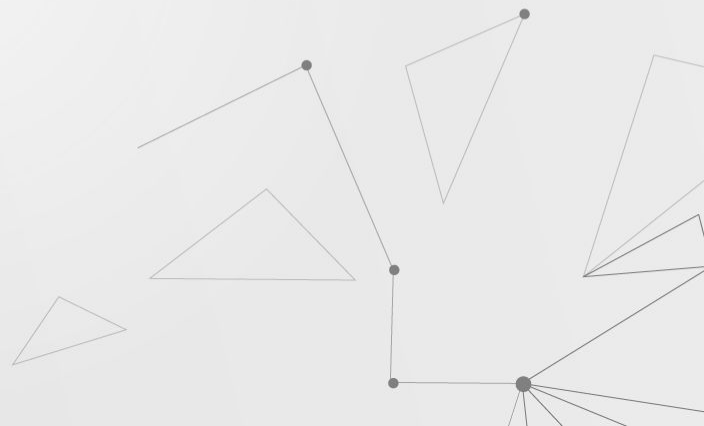
03 Simplifying the loss

The loss maximizes the
probability of a neighborhood given u

$$P_f(v|u) := \frac{\exp(f(v)^T f(u))}{\sum_{w \in V} \exp(f(w)^T f(u))}$$

$$P_f(N_s(u)|u) := \prod_{v \in N_s(u)} P_f(v|u)$$

Random walk



03 Simplifying the loss

The loss maximizes the **probability of a neighborhood given u**

$$P_f(v|u) := \frac{\exp(f(v)^T f(u))}{\sum_{w \in V} \exp(f(w)^T f(u))}$$

Expensive

$$P_f(N_s(u)|u) := \prod_{v \in N_s(u)} P_f(v|u)$$

Random walk

03 Simplifying the loss

The loss maximizes the **probability of a neighborhood given u**

$$P_f(v|u) := \frac{\exp(f(v)^T f(u))}{\sum_{w \in V} \exp(f(w)^T f(u))}$$

Expensive

$$P_f(N_s(u)|u) := \prod_{v \in N_s(u)} P_f(v|u)$$

Random walk

Negative sampling

(deepwalk uses hierarchical softmax)

- Manipulate the loss to $f(v)^T f(u) + \mathbb{E}_{w \sim p}(f(w)^T f(u))$

03 Simplifying the loss

The loss maximizes the **probability of a neighborhood given u**

$$P_f(v|u) := \frac{\exp(f(v)^T f(u))}{\sum_{w \in V} \exp(f(w)^T f(u))}$$

Expensive

$$P_f(N_s(u)|u) := \prod_{v \in N_s(u)} P_f(v|u)$$

Random walk

Negative sampling

(deepwalk uses hierarchical softmax)

- Manipulate the loss to $f(v)^T f(u) + \mathbb{E}_{w \sim p}(f(w)^T f(u))$
- Approximate **p** by defining a **positive/negative class**

03 Simplifying the loss

The loss maximizes the **probability of a neighborhood given u**

$$P_f(v|u) := \frac{\exp(f(v)^T f(u))}{\sum_{w \in V} \exp(f(w)^T f(u))}$$

Expensive

$$P_f(N_s(u)|u) := \prod_{v \in N_s(u)} P_f(v|u)$$

Random walk

Negative sampling

(deepwalk uses hierarchical softmax)

- Manipulate the loss to $f(v)^T f(u) + \mathbb{E}_{w \sim p}(f(w)^T f(u))$
- Approximate **p** by defining a **positive/negative class**
- Sample +/- by sampling **true/fake RW**

03 Simplifying the loss

The loss maximizes the **probability of a neighborhood given u**

$$P_f(v|u) := \frac{\exp(f(v)^T f(u))}{\sum_{w \in V} \exp(f(w)^T f(u))}$$

Expensive

$$P_f(N_s(u)|u) := \prod_{v \in N_s(u)} P_f(v|u)$$

Random walk

Negative sampling

(deepwalk uses hierarchical softmax)

- Manipulate the loss to $f(v)^T f(u) + \mathbb{E}_{w \sim p}(f(w)^T f(u))$
- Approximate **p** by defining a **positive/negative class**
- Sample +/- by sampling **true/fake RW**

Details of math: *On word embeddings - Part 2: Approximating the Softmax*

<https://ruder.io/word-embeddings-softmax/>

03 Simplifying the loss

```
CLASS Node2Vec ( edge_index, embedding_dim, walk_length, context_size, walks_per_node=1, p=1, q=1,  
num_negative_samples=1, num_nodes=None, sparse=False ) \[source\]
```

The Node2Vec model from the “[node2vec: Scalable Feature Learning for Networks](#)” paper where random walks of length `walk_length` are sampled in a given graph, and node embeddings are learned via negative sampling optimization.

- **num_negative_samples** (*int, optional*) – The number of negative samples to use for each positive sample. (default: **1**)

03 Simplifying the loss

```
def loss(self, pos_rw, neg_rw):
    r"""Computes the loss given positive and negative random walks."""

    # Positive loss.
    start, rest = pos_rw[:, 0], pos_rw[:, 1:].contiguous()

    h_start = self.embedding(start).view(pos_rw.size(0), 1,
                                         self.embedding_dim)
    h_rest = self.embedding(rest.view(-1)).view(pos_rw.size(0), -1,
                                                self.embedding_dim)

    out = (h_start * h_rest).sum(dim=-1).view(-1)
    pos_loss = -torch.log(torch.sigmoid(out) + EPS).mean()

    # Negative loss.
    start, rest = neg_rw[:, 0], neg_rw[:, 1:].contiguous()

    h_start = self.embedding(start).view(neg_rw.size(0), 1,
                                         self.embedding_dim)
    h_rest = self.embedding(rest.view(-1)).view(neg_rw.size(0), -1,
                                                self.embedding_dim)

    out = (h_start * h_rest).sum(dim=-1).view(-1)
    neg_loss = -torch.log(1 - torch.sigmoid(out) + EPS).mean()

    return pos_loss + neg_loss
```

03 Simplifying the loss

Divide first node from the rest of the RW

```
def loss(self, pos_rw, neg_rw):
    r"""Computes the loss given positive and negative random walks."""

    # Positive loss.
    start, rest = pos_rw[:, 0], pos_rw[:, 1:].contiguous()

    h_start = self.embedding(start).view(pos_rw.size(0), 1,
                                         self.embedding_dim)
    h_rest = self.embedding(rest.view(-1)).view(pos_rw.size(0), -1,
                                                self.embedding_dim)

    out = (h_start * h_rest).sum(dim=-1).view(-1)
    pos_loss = -torch.log(torch.sigmoid(out) + EPS).mean()

    # Negative loss.
    start, rest = neg_rw[:, 0], neg_rw[:, 1:].contiguous()

    h_start = self.embedding(start).view(neg_rw.size(0), 1,
                                         self.embedding_dim)
    h_rest = self.embedding(rest.view(-1)).view(neg_rw.size(0), -1,
                                                self.embedding_dim)

    out = (h_start * h_rest).sum(dim=-1).view(-1)
    neg_loss = -torch.log(1 - torch.sigmoid(out) + EPS).mean()

    return pos_loss + neg_loss
```

03 Simplifying the loss

Divide first node from the rest of the RW

Compute the embeddings

```
def loss(self, pos_rw, neg_rw):
    r"""Computes the loss given positive and negative random walks."""

    # Positive loss.
    start, rest = pos_rw[:, 0], pos_rw[:, 1:].contiguous()

    h_start = self.embedding(start).view(pos_rw.size(0), 1,
                                         self.embedding_dim)
    h_rest = self.embedding(rest.view(-1)).view(pos_rw.size(0), -1,
                                                self.embedding_dim)

    out = (h_start * h_rest).sum(dim=-1).view(-1)
    pos_loss = -torch.log(torch.sigmoid(out) + EPS).mean()

    # Negative loss.
    start, rest = neg_rw[:, 0], neg_rw[:, 1:].contiguous()

    h_start = self.embedding(start).view(neg_rw.size(0), 1,
                                         self.embedding_dim)
    h_rest = self.embedding(rest.view(-1)).view(neg_rw.size(0), -1,
                                                self.embedding_dim)

    out = (h_start * h_rest).sum(dim=-1).view(-1)
    neg_loss = -torch.log(1 - torch.sigmoid(out) + EPS).mean()

    return pos_loss + neg_loss
```

03 Simplifying the loss

Divide first node from the rest of the RW

Compute the embeddings

Loss for the **positive class**: true RW

```
def loss(self, pos_rw, neg_rw):
    r"""Computes the loss given positive and negative random walks."""

    # Positive loss.
    start, rest = pos_rw[:, 0], pos_rw[:, 1:].contiguous()

    h_start = self.embedding(start).view(pos_rw.size(0), 1,
                                         self.embedding_dim)
    h_rest = self.embedding(rest.view(-1)).view(pos_rw.size(0), -1,
                                                self.embedding_dim)

    out = (h_start * h_rest).sum(dim=-1).view(-1)
    pos_loss = -torch.log(torch.sigmoid(out) + EPS).mean()

    # Negative loss.
    start, rest = neg_rw[:, 0], neg_rw[:, 1:].contiguous()

    h_start = self.embedding(start).view(neg_rw.size(0), 1,
                                         self.embedding_dim)
    h_rest = self.embedding(rest.view(-1)).view(neg_rw.size(0), -1,
                                                self.embedding_dim)

    out = (h_start * h_rest).sum(dim=-1).view(-1)
    neg_loss = -torch.log(1 - torch.sigmoid(out) + EPS).mean()

    return pos_loss + neg_loss
```


03 Simplifying the loss

Divide first node from the rest of the RW

Compute the embeddings

Loss for the **positive class**: true RW

The same, but for the
negative class (fake RW)

```
def loss(self, pos_rw, neg_rw):
    r"""Computes the loss given positive and negative random walks."""

    # Positive loss.
    start, rest = pos_rw[:, 0], pos_rw[:, 1:].contiguous()

    h_start = self.embedding(start).view(pos_rw.size(0), 1,
                                         self.embedding_dim)
    h_rest = self.embedding(rest.view(-1)).view(pos_rw.size(0), -1,
                                                self.embedding_dim)

    out = (h_start * h_rest).sum(dim=-1).view(-1)
    pos_loss = -torch.log(torch.sigmoid(out) + EPS).mean()

    # Negative loss.
    start, rest = neg_rw[:, 0], neg_rw[:, 1:].contiguous()

    h_start = self.embedding(start).view(neg_rw.size(0), 1,
                                         self.embedding_dim)
    h_rest = self.embedding(rest.view(-1)).view(neg_rw.size(0), -1,
                                                self.embedding_dim)

    out = (h_start * h_rest).sum(dim=-1).view(-1)
    neg_loss = -torch.log(1 - torch.sigmoid(out) + EPS).mean()

    return pos_loss + neg_loss
```

03 Simplifying the loss

Divide first node from the rest of the RW

Compute the embeddings

Loss for the **positive class**: true RW

The same, but for the
negative class (fake RW)

Total loss

```
def loss(self, pos_rw, neg_rw):  
    r"""Computes the loss given positive and negative random walks."""  
  
    # Positive loss.  
    start, rest = pos_rw[:, 0], pos_rw[:, 1:].contiguous()  
  
    h_start = self.embedding(start).view(pos_rw.size(0), 1,  
                                         self.embedding_dim)  
    h_rest = self.embedding(rest.view(-1)).view(pos_rw.size(0), -1,  
                                                self.embedding_dim)  
  
    out = (h_start * h_rest).sum(dim=-1).view(-1)  
    pos_loss = -torch.log(torch.sigmoid(out) + EPS).mean()  
  
    # Negative loss.  
    start, rest = neg_rw[:, 0], neg_rw[:, 1:].contiguous()  
  
    h_start = self.embedding(start).view(neg_rw.size(0), 1,  
                                         self.embedding_dim)  
    h_rest = self.embedding(rest.view(-1)).view(neg_rw.size(0), -1,  
                                                self.embedding_dim)  
  
    out = (h_start * h_rest).sum(dim=-1).view(-1)  
    neg_loss = -torch.log(1 - torch.sigmoid(out) + EPS).mean()  
  
    return pos_loss + neg_loss
```


03 Simplifying the loss

Mean over the batch of RWs

Divide first node from the rest of the RW

Compute the embeddings

Loss for the **positive class**: true RW

The same, but for the
negative class (fake RW)

Total loss

```
def loss(self, pos_rw, neg_rw):  
    r"""Computes the loss given positive and negative random walks."""  
  
    # Positive loss.  
    start, rest = pos_rw[:, 0], pos_rw[:, 1:].contiguous()  
  
    h_start = self.embedding(start).view(pos_rw.size(0), 1,  
                                         self.embedding_dim)  
    h_rest = self.embedding(rest.view(-1)).view(pos_rw.size(0), -1,  
                                                self.embedding_dim)  
  
    out = (h_start * h_rest).sum(dim=-1).view(-1)  
    pos_loss = -torch.log(torch.sigmoid(out) + EPS).mean()  
  
    # Negative loss.  
    start, rest = neg_rw[:, 0], neg_rw[:, 1:].contiguous()  
  
    h_start = self.embedding(start).view(neg_rw.size(0), 1,  
                                         self.embedding_dim)  
    h_rest = self.embedding(rest.view(-1)).view(neg_rw.size(0), -1,  
                                                self.embedding_dim)  
  
    out = (h_start * h_rest).sum(dim=-1).view(-1)  
    neg_loss = -torch.log(1 - torch.sigmoid(out) + EPS).mean()  
  
    return pos_loss + neg_loss
```

04 `node2vec`: Full implementation

```
def forward(self, batch=None):  
    """Returns the embeddings for the nodes in :obj:`batch`."""  
    emb = self.embedding.weight  
    return emb if batch is None else emb[batch]
```

04 node2vec: Full implementation

```
def forward(self, batch=None):  
    """Returns the embeddings for the nodes in :obj:`batch`."""  
    emb = self.embedding.weight  
    return emb if batch is None else emb[batch]
```

```
def test(self, train_z, train_y, test_z, test_y, solver='lbfgs',  
        multi_class='auto', *args, **kwargs):  
    r"""Evaluates latent space quality via a logistic regression downstream  
    task."""  
    clf = LogisticRegression(solver=solver, multi_class=multi_class, *args,  
                            **kwargs).fit(train_z.detach().cpu().numpy(),  
                                          train_y.detach().cpu().numpy())  
    return clf.score(test_z.detach().cpu().numpy(),  
                    test_y.detach().cpu().numpy())
```



04 `node2vec`: Full implementation

... notebook ...

