

# Graph Autoencoders (GAE) & Graph Variational Autoencoders (VGAE)

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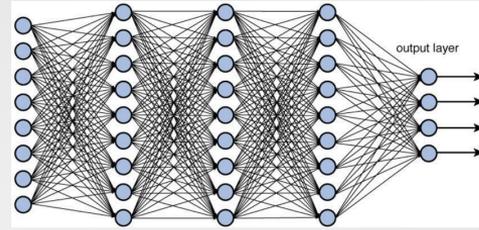
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# 01 Autoencoders

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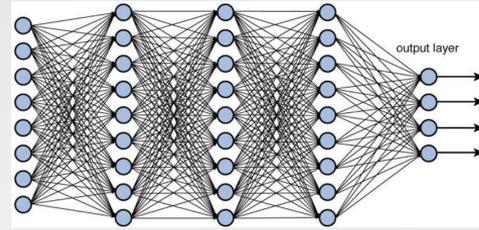
What does a Deep neural network do?



# 01 Autoencoders

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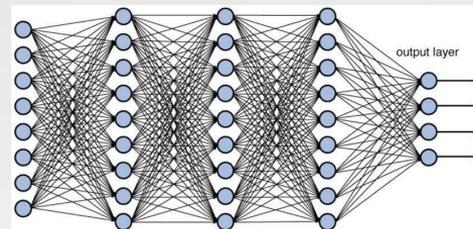


It learns **important features** from the input.

# 01 Autoencoders

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What does a Deep neural network do?



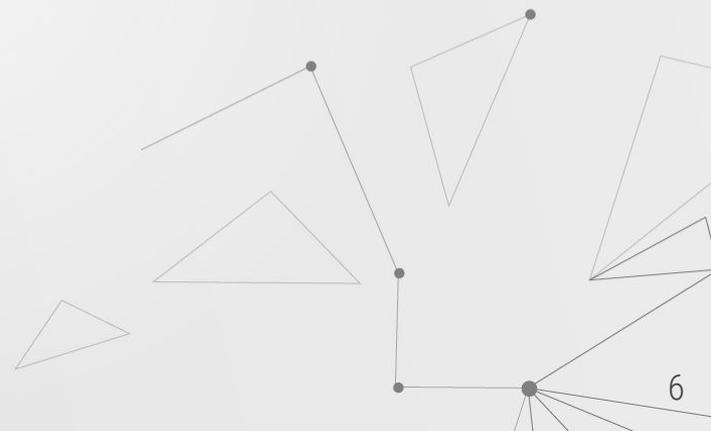
It learns **important features** from the input.

Features that allow to do a specific task on the data.  
I.e classification, regression, generalization etc

# 01 Autoencoders

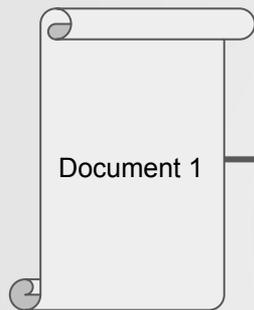
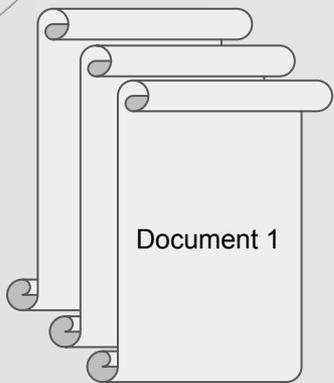
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Can we compress our input data?



# 01 Autoencoders

Can we compress our input data?



**[10,1,6,0.4,11,4]**

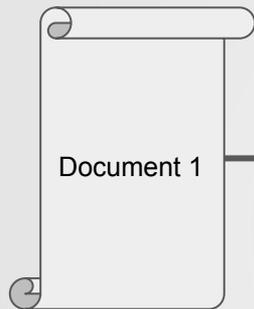
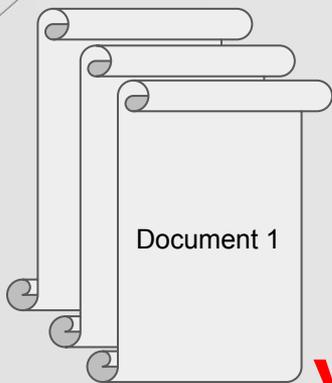
**Low dimensional vector**



**[74,22,45,1,12,4,4,4]**

# 01 Autoencoders

Can we compress our input data?



$[10, 1, 6, 0.4, 11, 4]$

Low dimensional vector

**Yes, with Autoencoders**

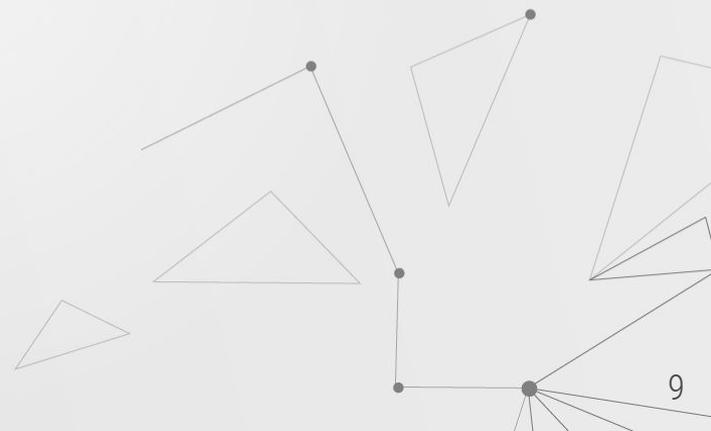


$[74, 22, 45, 1, 12, 4, 4, 4]$

# 01 Autoencoders

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Autoencoders are Neural networks that works in an **unsupervised** manner



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Autoencoders are Neural networks that works in an **unsupervised** manner

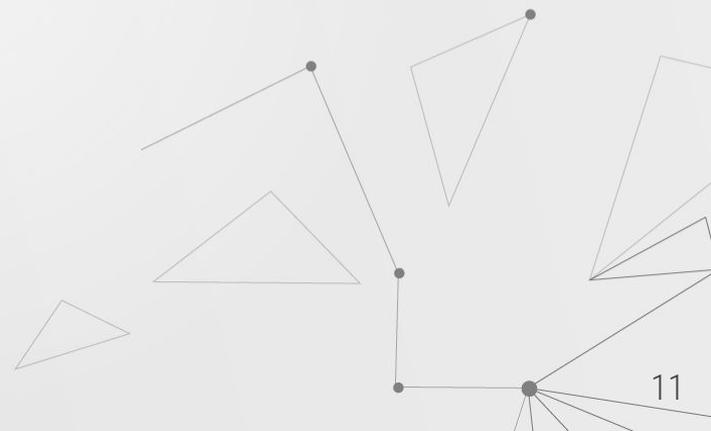
We do **not need labeled data**



# 01 Autoencoders

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**How can they work** without any labeled data?

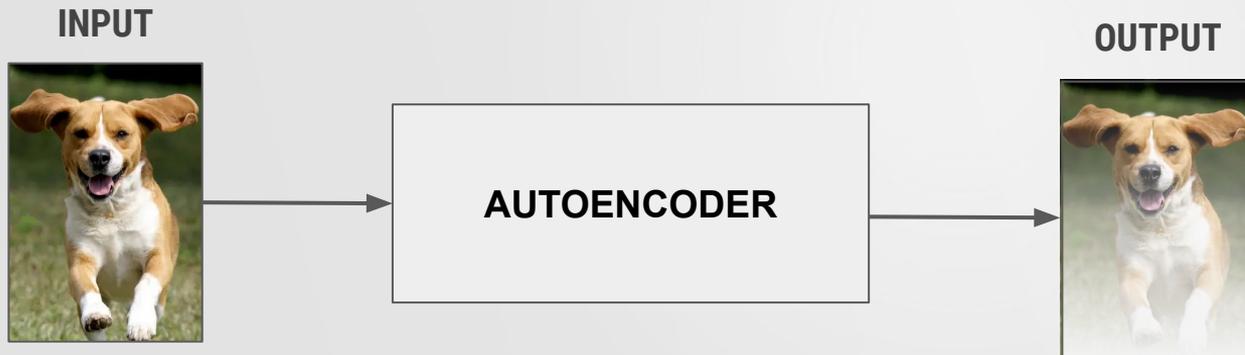


# 01 Autoencoders

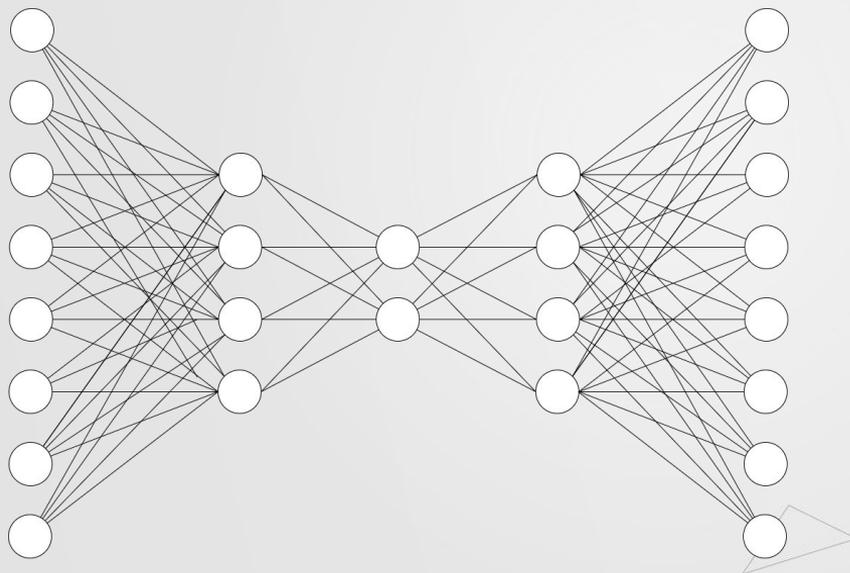
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**How can they work** without any labeled data?

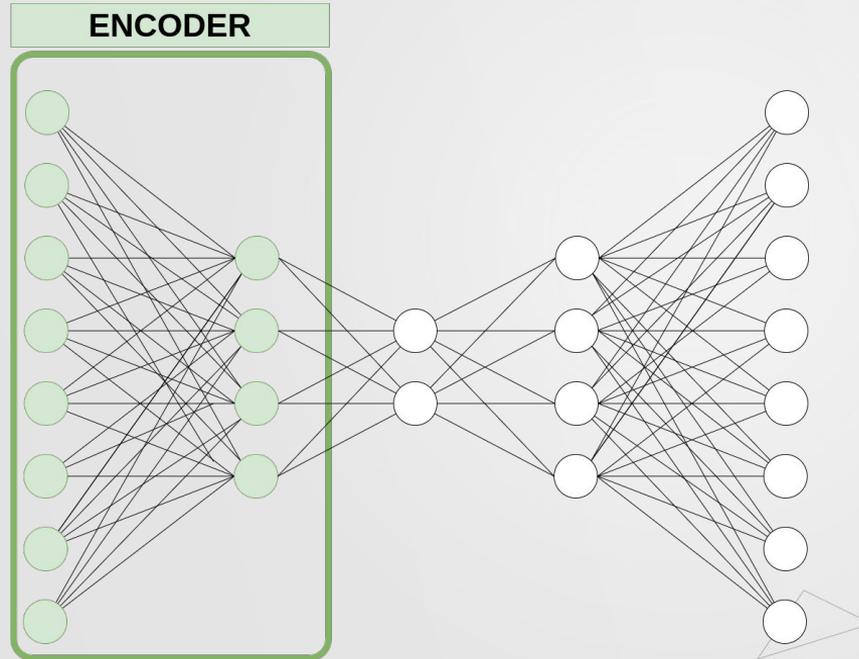
The idea is to **reconstruct** the **input**



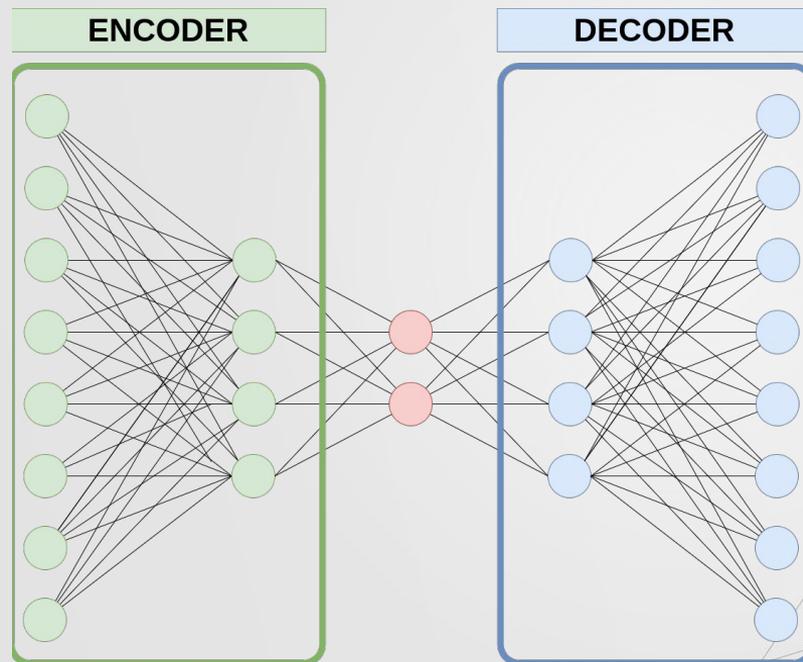
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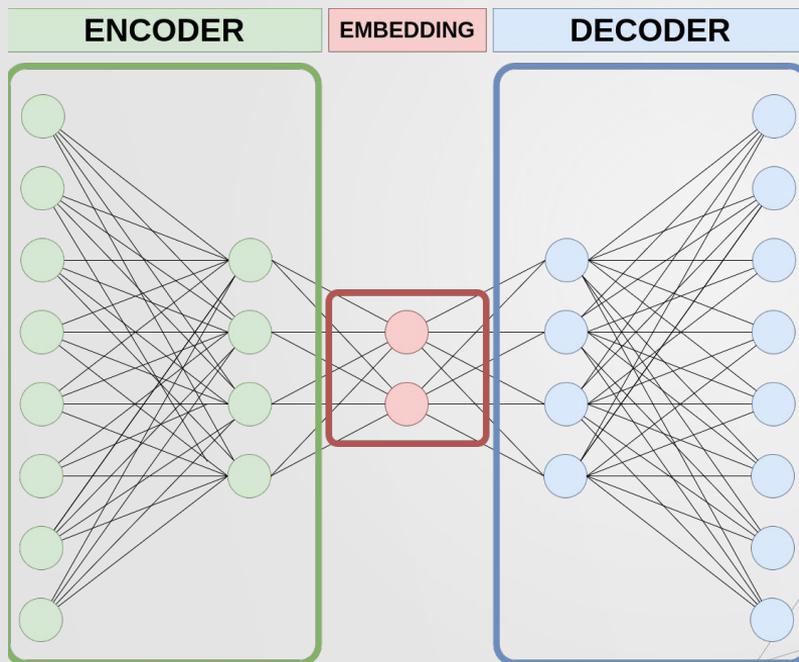
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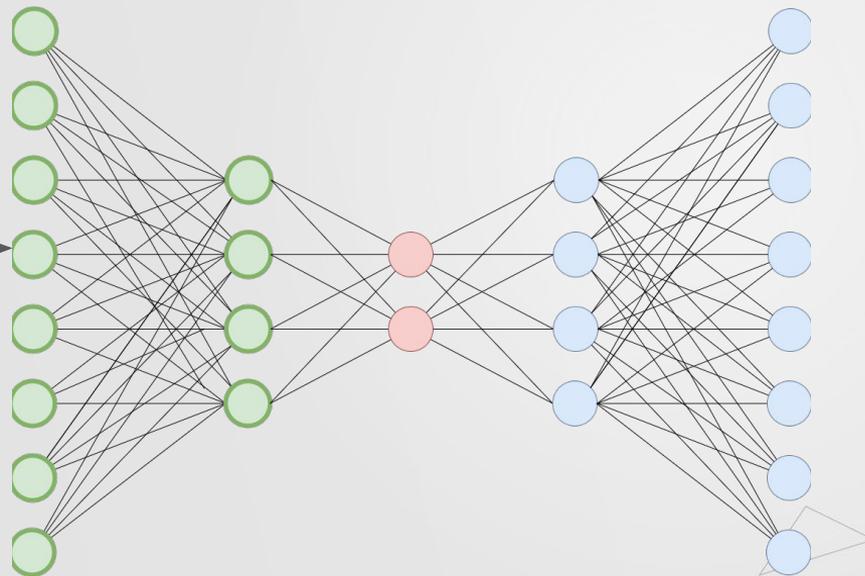
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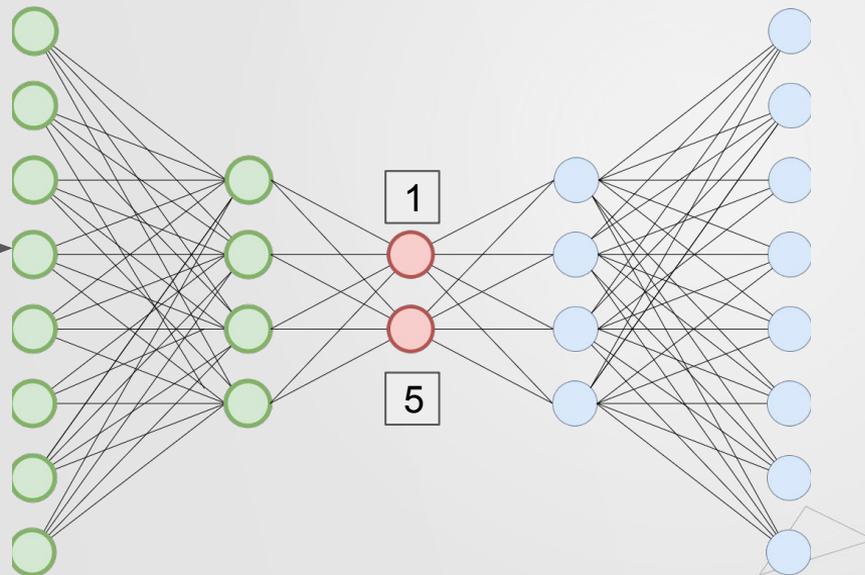
**INPUT**



# 01 Autoencoders



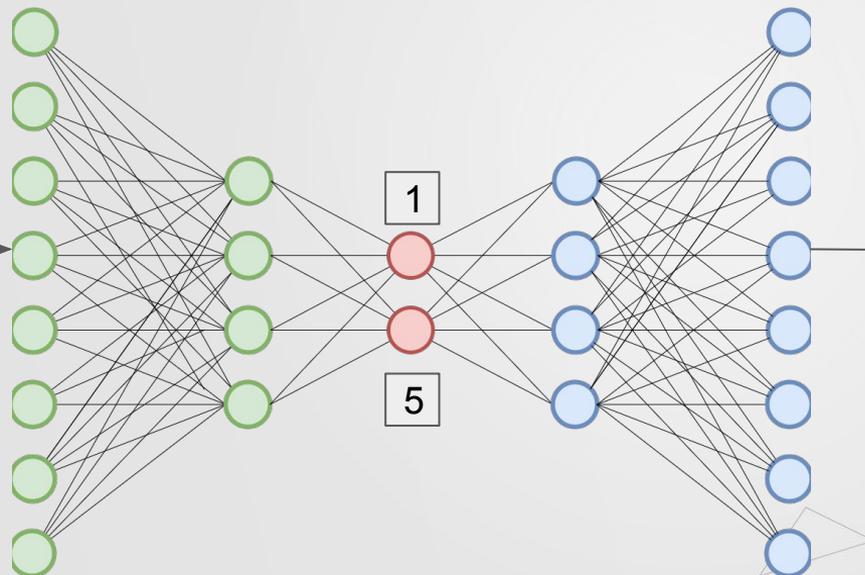
**INPUT**



# 01 Autoencoders



**INPUT**



**OUTPUT**



# 01 Autoencoders

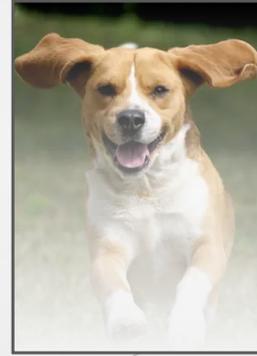
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**LOSS = similarity**

**INPUT**



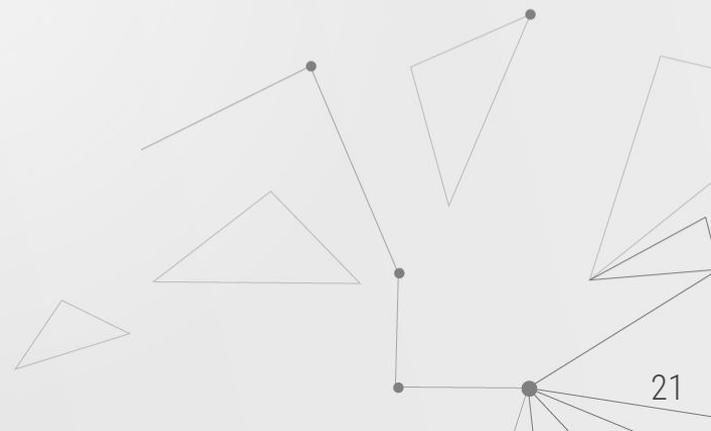
**OUTPUT**



# 01 Autoencoders

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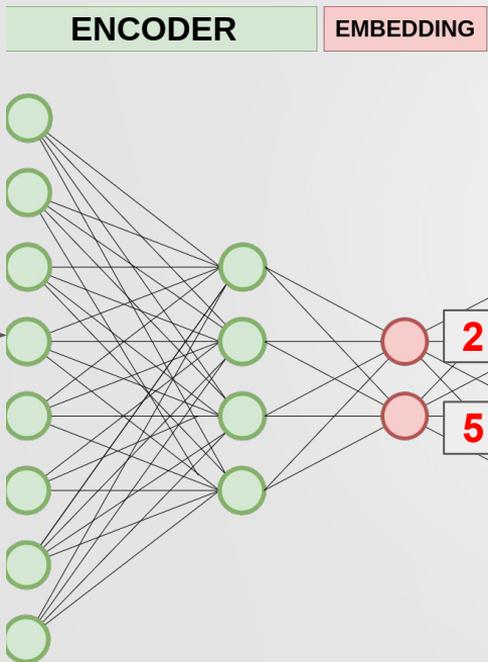
How to use an autoencoder?



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How to use an autoencoder?

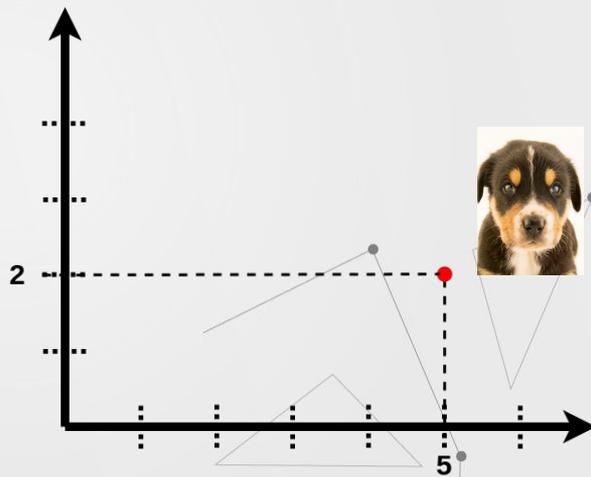
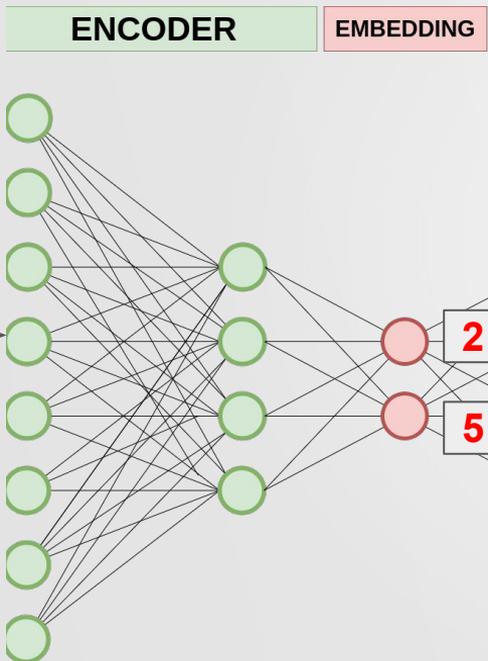
INPUT



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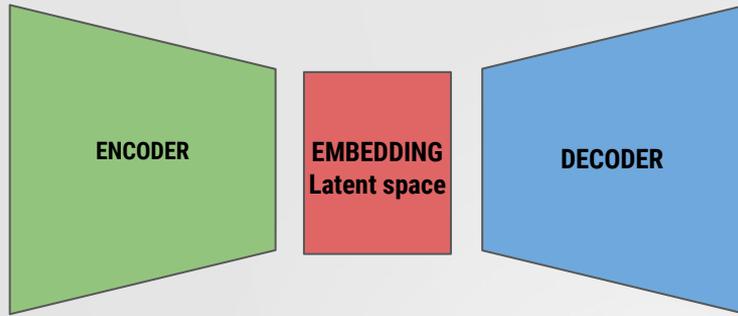
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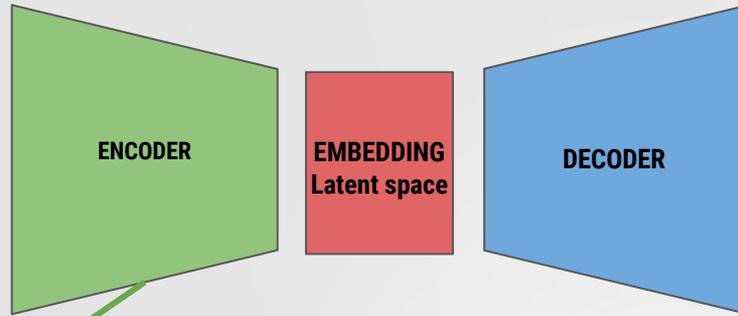
# 02 Graph Autoencoders (GAE) Theory

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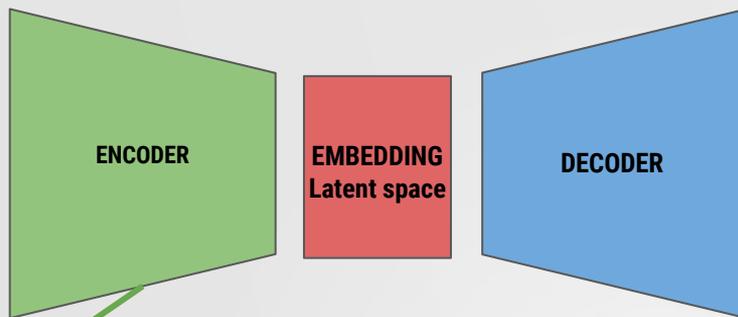


**ONE** convolutional Graph neural network:



## 02 Graph Autoencoders (GAE) Theory

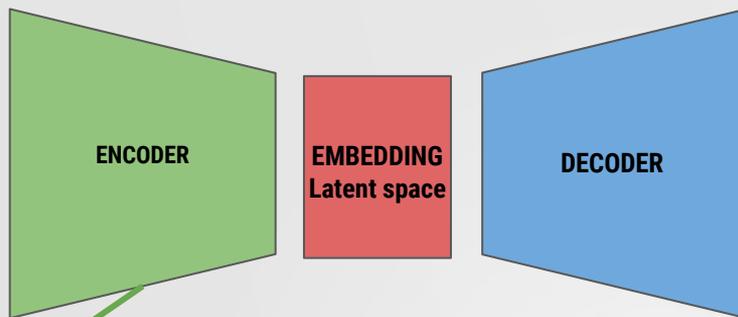
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**ONE** convolutional Graph neural network:

- produces a low dimensional embedding representation

## 02 Graph Autoencoders (GAE) Theory



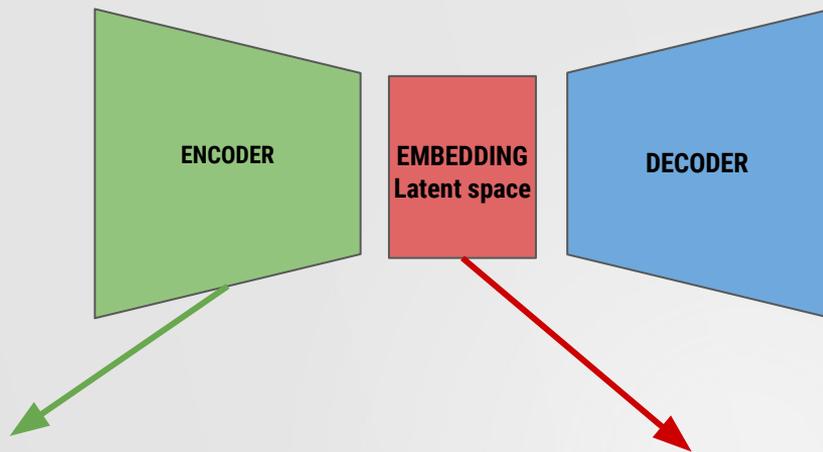
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$$\bar{X} = GCN(A, X) = ReLU(\tilde{A}XW_0)$$

$$\text{with } \tilde{A} = D^{-1/2}AD^{-1/2}$$

## 02 Graph Autoencoders (GAE) Theory



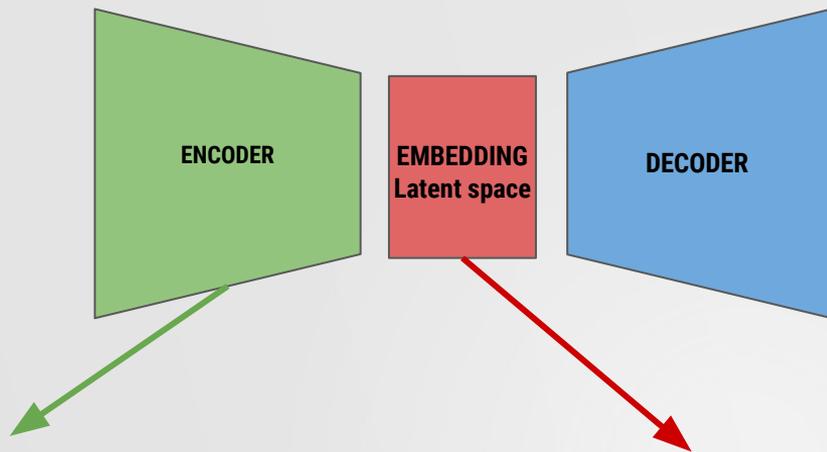
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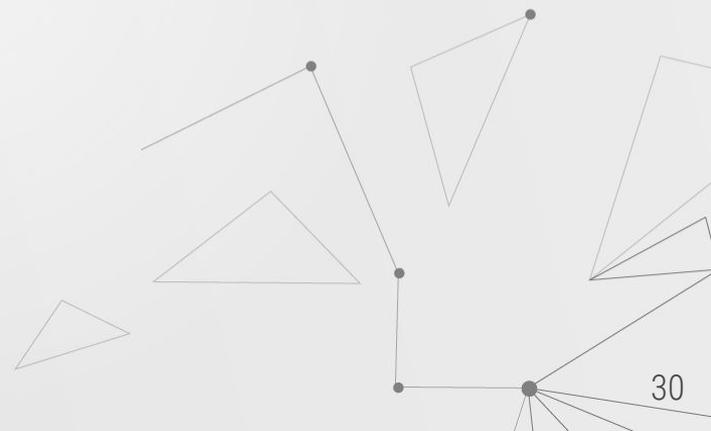
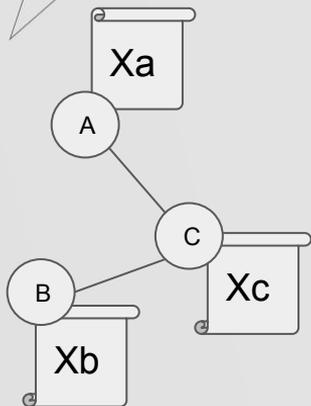
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$$Z = \bar{X}$$

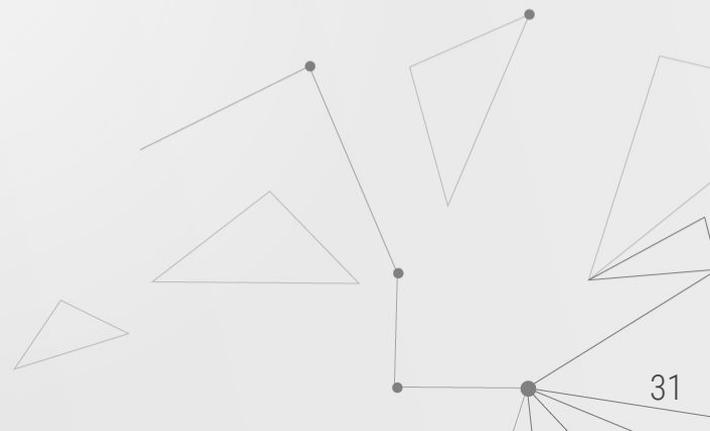
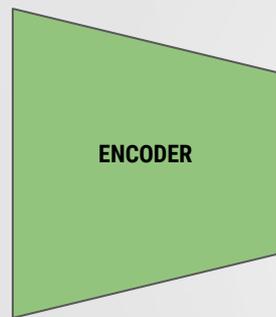
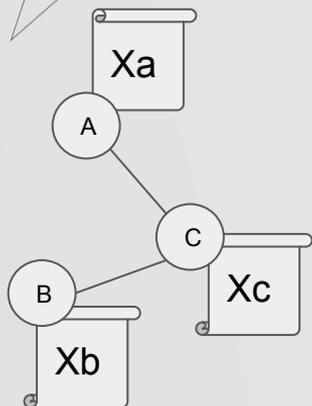
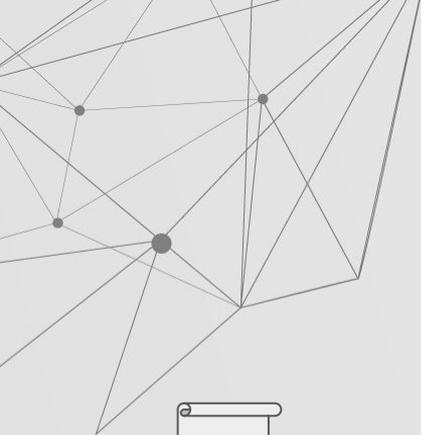
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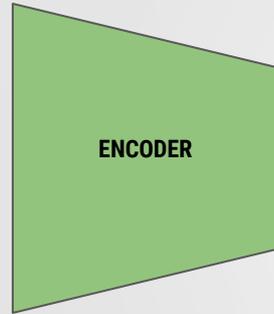
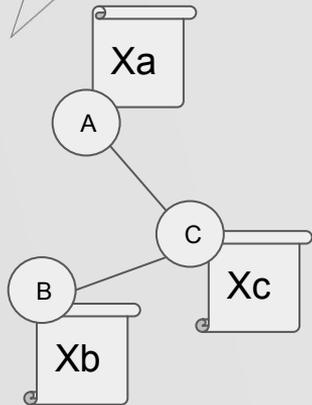
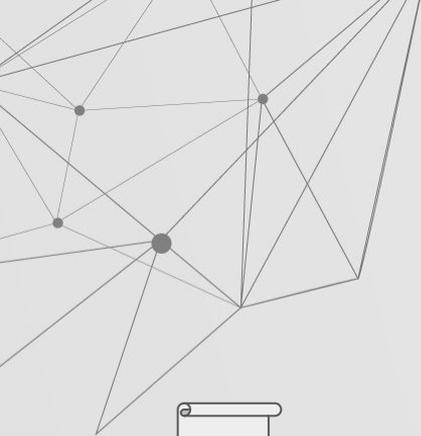


# 02 Graph Autoencoders (GAE) Theory

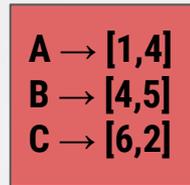
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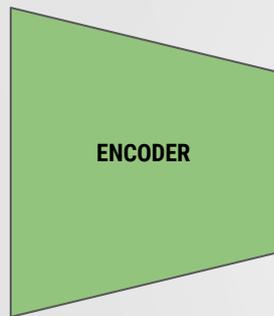
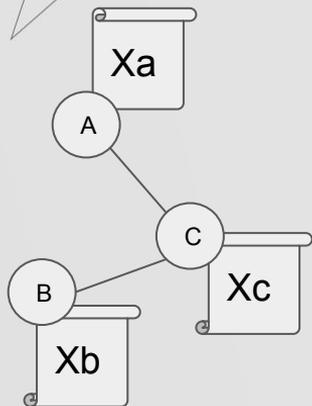
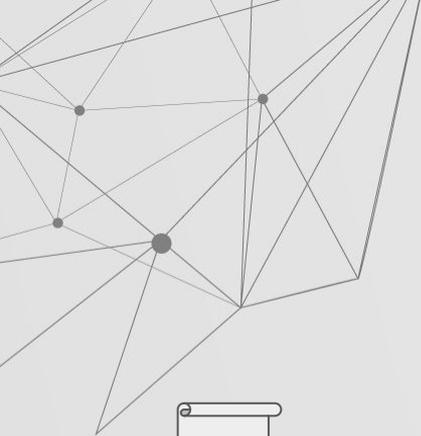
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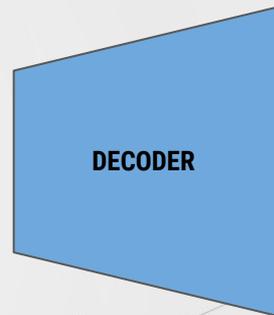
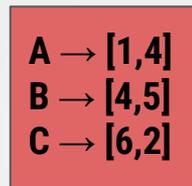
Node embedding in a latent space with two dimension.



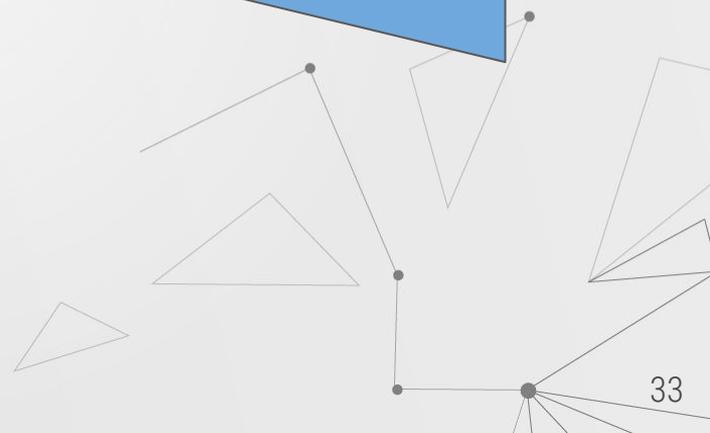
# 02 Graph Autoencoders (GAE) Theory



Node embedding in a latent space with two dimension.



Reconstruct The input graph



# 02 Graph Autoencoders (GAE) Theory

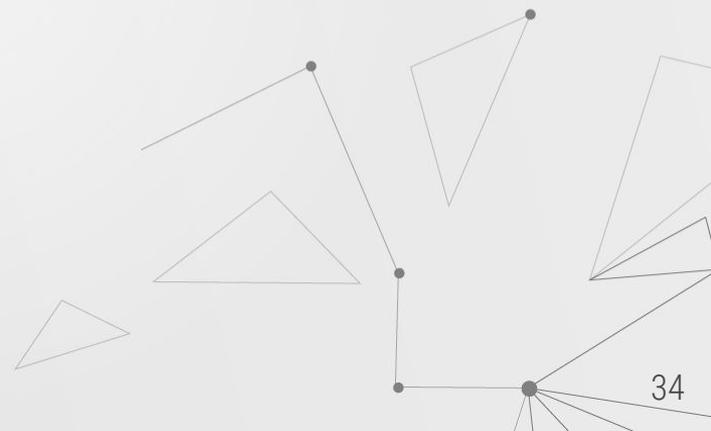
Reconstruct  
The input graph

**A**  $\rightarrow$  [1,4]  
**B**  $\rightarrow$  [4,5]  
**C**  $\rightarrow$  [6,2]



**DECODER**

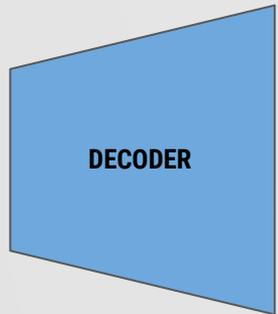
**Inner product**  
Between latent variable  $Z$



# 02 Graph Autoencoders (GAE) Theory

Reconstruct  
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**A** → [1,4]  
**B** → [4,5]  
**C** → [6,2]

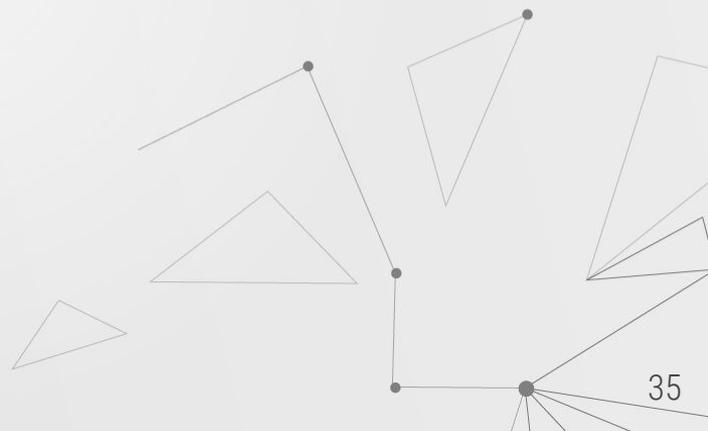


**Inner product**  
Between latent variable Z

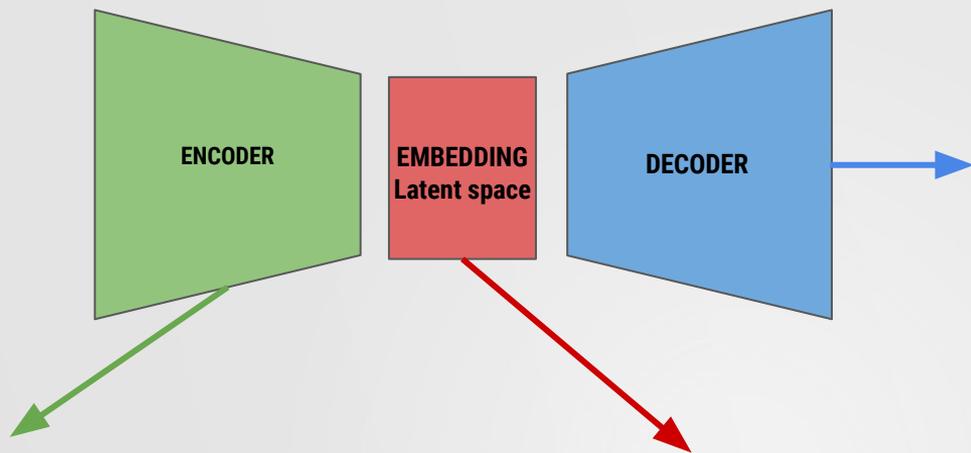
$$\text{Adj}_{(A,B)} = \text{sigmoid}([1,4] * [4,5]^T)$$

$$\text{Adj}_{(B,C)} = \text{sigmoid}([4,5] * [6,2]^T)$$

.....



## 02 Graph Autoencoders (GAE) Theory



**ONE** convolutional Graph neural network:

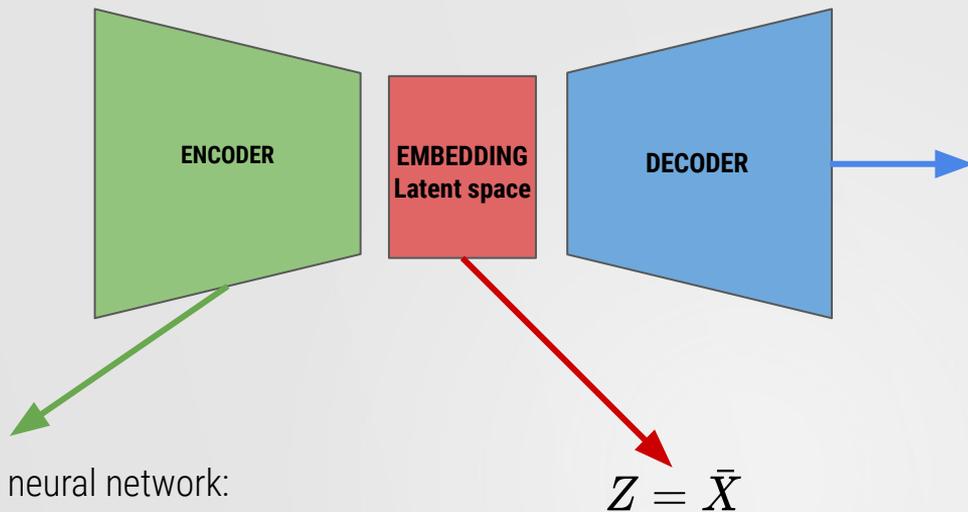
- produces a low dimensional embedding representation

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## 02 Graph Autoencoders (GAE) Theory



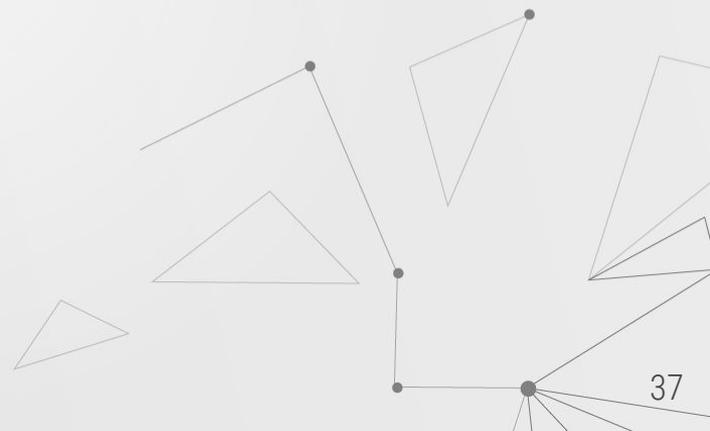
So far we have an **embedding** in a latent space **for each node** of the graph.

**ONE** convolutional Graph neural network:

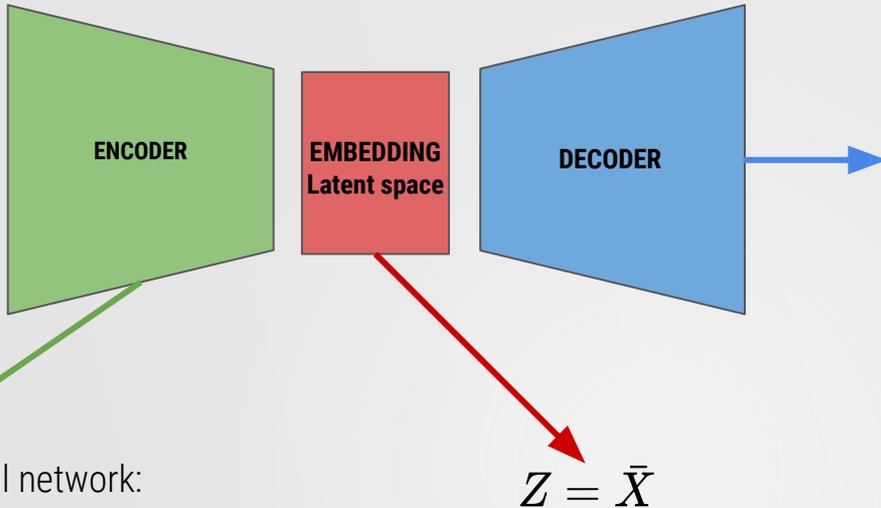
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We want to **reconstruct** the adjacency matrix **A**

**ONE** convolutional Graph neural network:

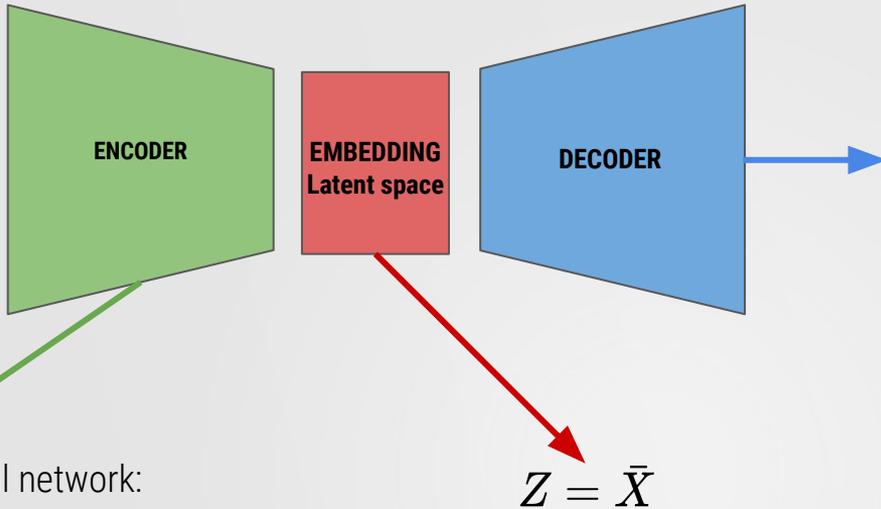
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So far we have an **embedding** in a latent space **for each node** of the graph.

We want to **reconstruct** the adjacency matrix **A**

**Inner product**  
Between latent variable **Z**

$$\hat{A} = \text{logistic sigmoid}(zz^T)$$



# 03 Graph Autoencoders (GAE) Practice

**CLASS** `GAE ( encoder, decoder=None )` [\[source\]](#)

The Graph Auto-Encoder model from the “[Variational Graph Auto-Encoders](#)” paper based on user-defined encoder and decoder models.

## PARAMETERS

- `encoder (Module)` – The encoder module.
- `decoder (Module, optional)` – The decoder module. If set to `None`, will default to the `torch_geometric.nn.models.InnerProductDecoder`. (default: `None`)

**decode** ( \*args, \*\*kwargs ) [\[source\]](#)

Runs the decoder and computes edge probabilities.

**encode** ( \*args, \*\*kwargs ) [\[source\]](#)

Runs the encoder and computes node-wise latent variables.

**recon\_loss** ( z, pos\_edge\_index, neg\_edge\_index=None ) [\[source\]](#)

Given latent variables `z`, computes the binary cross entropy loss for positive edges `pos_edge_index` and negative sampled edges.

## PARAMETERS

- `z (Tensor)` – The latent space **Z**.
- `pos_edge_index (LongTensor)` – The positive edges to train against.
- `neg_edge_index (LongTensor, optional)` – The negative edges to train against. If not given, uses negative sampling to calculate negative edges. (default: `None`)

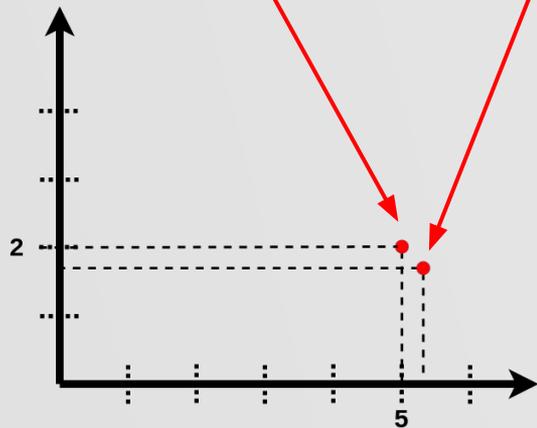
# 03 Graph Autoencoders (GAE) Practice

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Jupyter Notebook

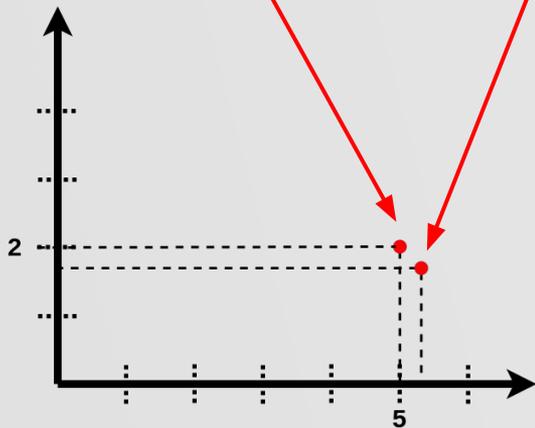
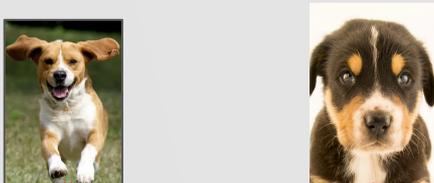
# 04 Variational Autoencoders

Autoencoder  
(encoder)

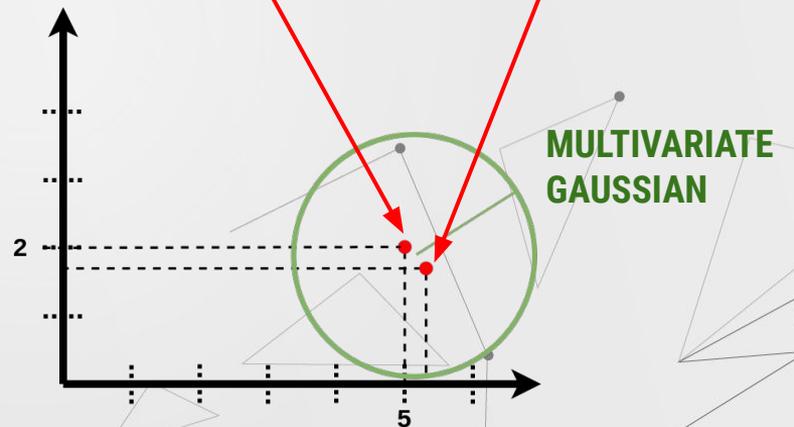
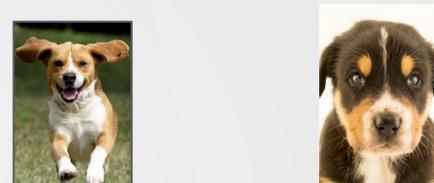


# 04 Variational Autoencoders

Autoencoder  
(encoder)



Variational Autoencoder  
(encoder)

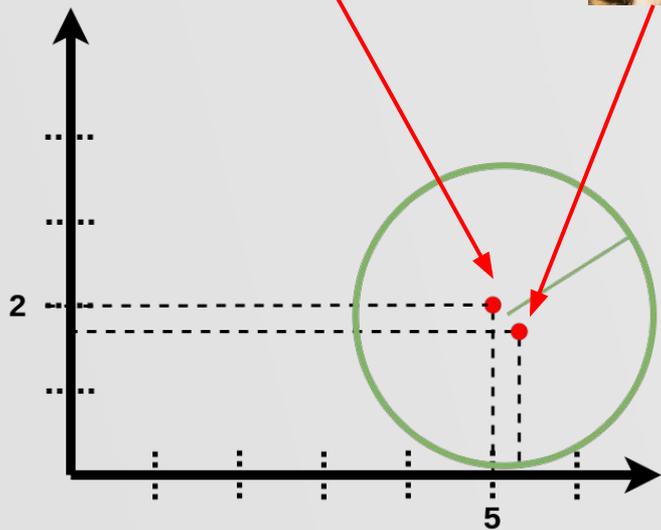


# 04 Variational Autoencoders

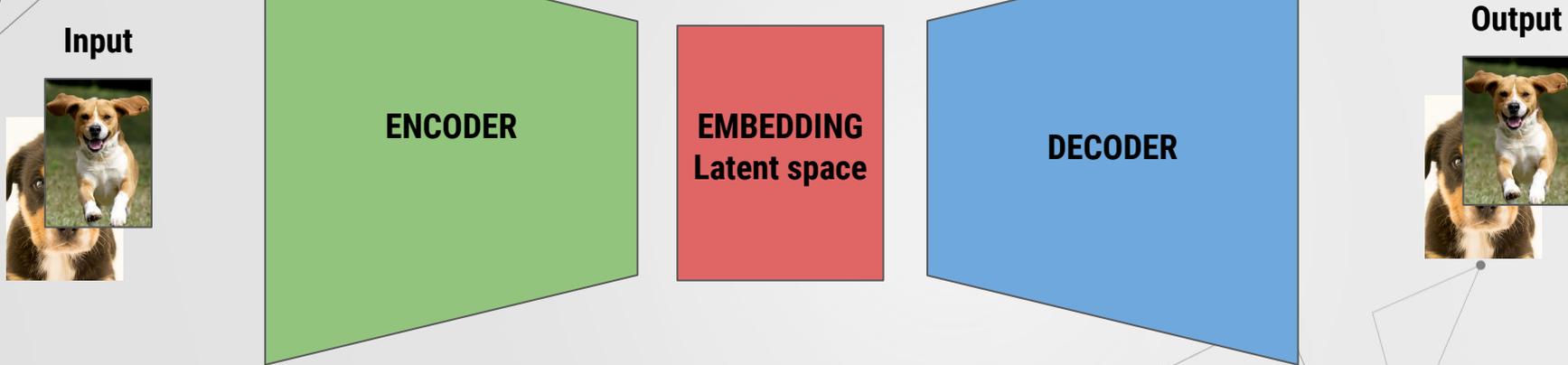


MULTIVARIATE  
GAUSSIAN

$\mu, \sigma^2$



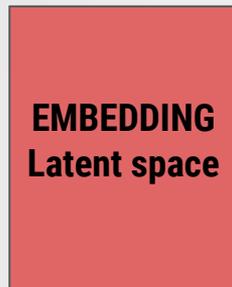
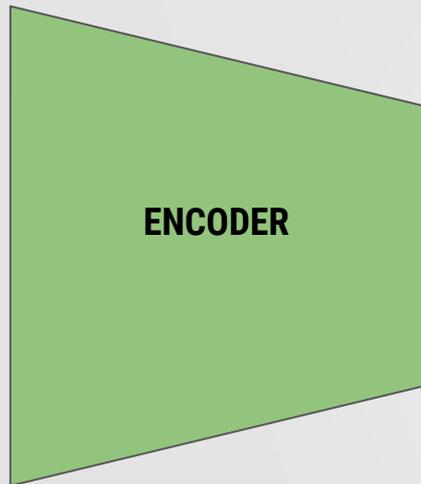
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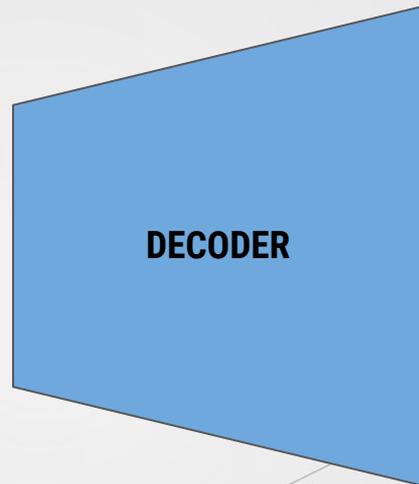
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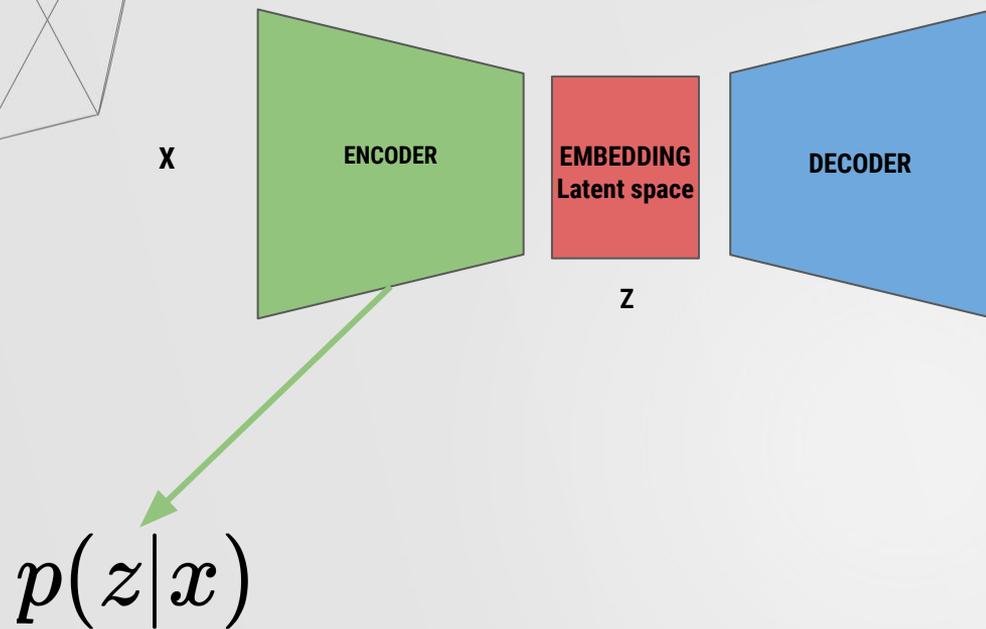
**X**



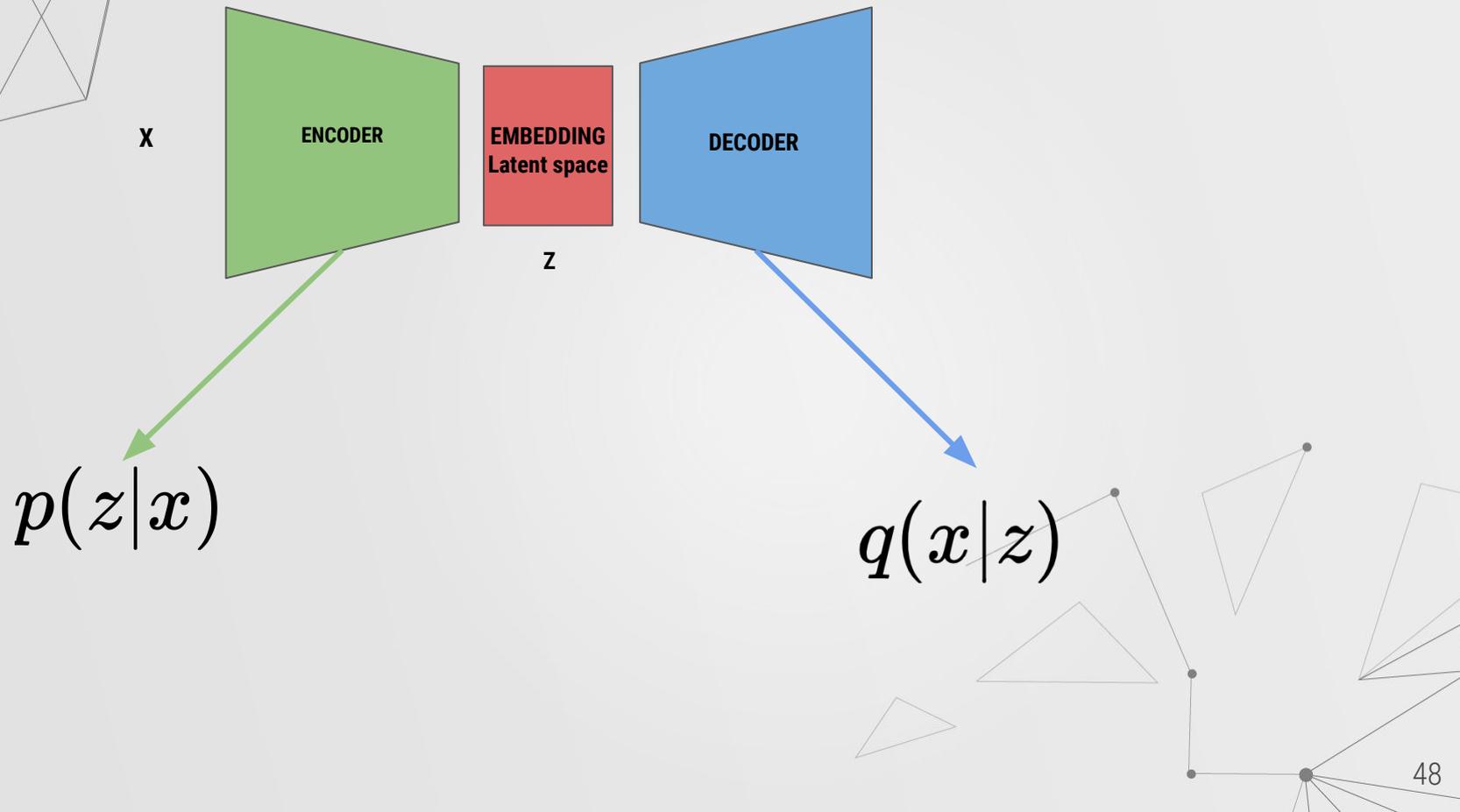
**Z**



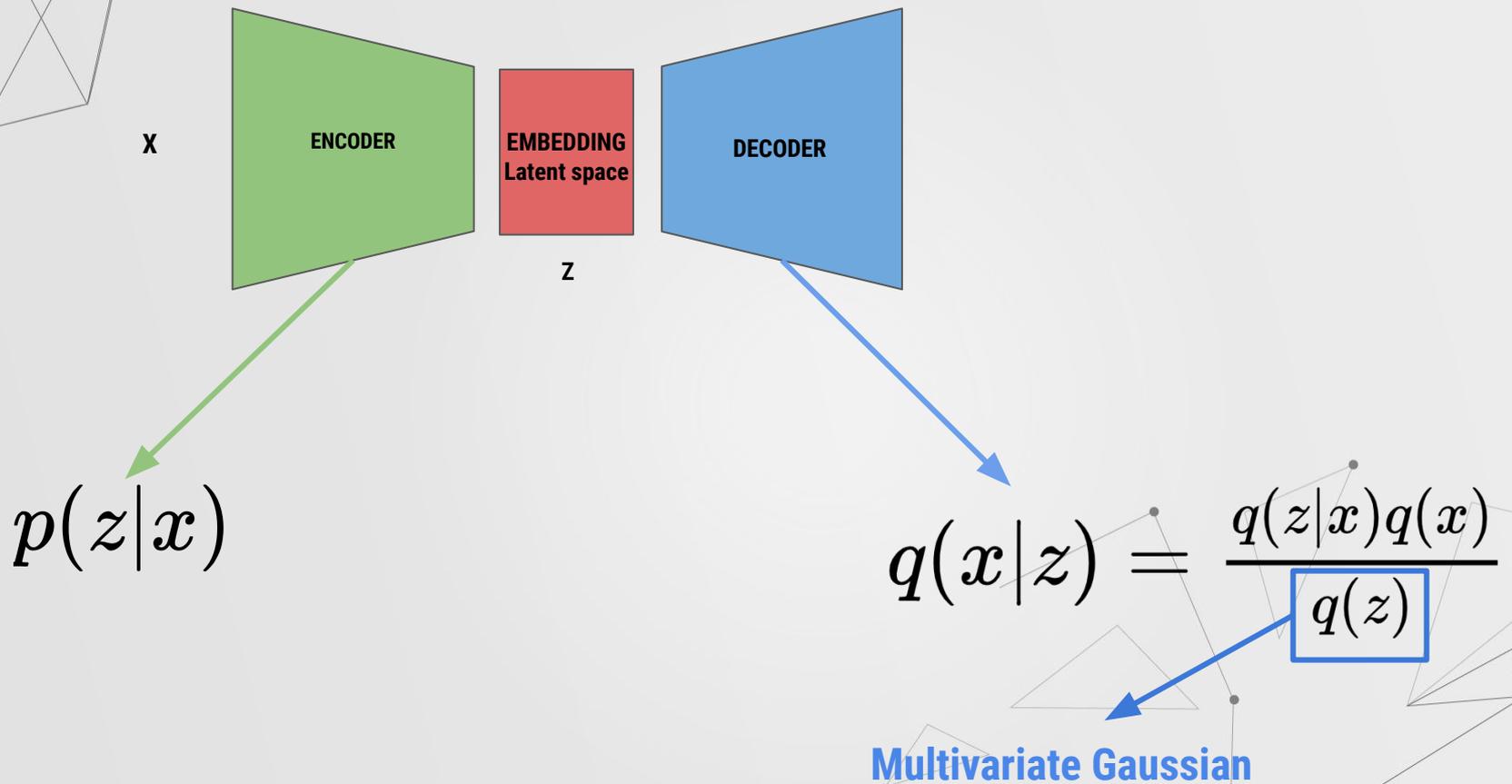
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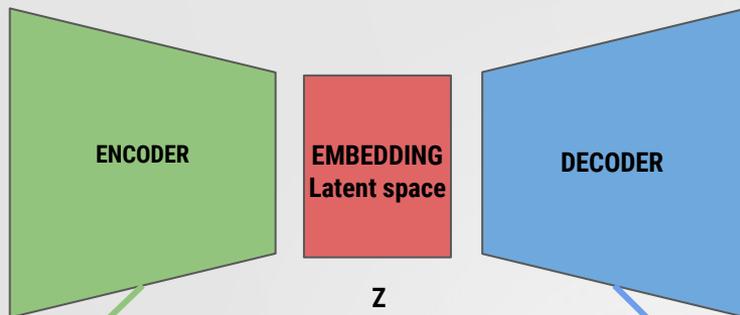
# 04 Variational Autoencoders



# 04 Variational Autoencoders



$x$



$$p(z|x)$$

$$q(x|z) = \frac{q(z|x)q(x)}{q(z)}$$

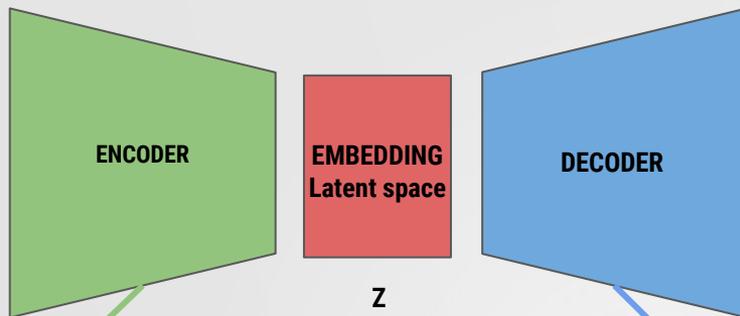
Distribution of the input

Multivariate Gaussian

# 04 Variational Autoencoders



$x$



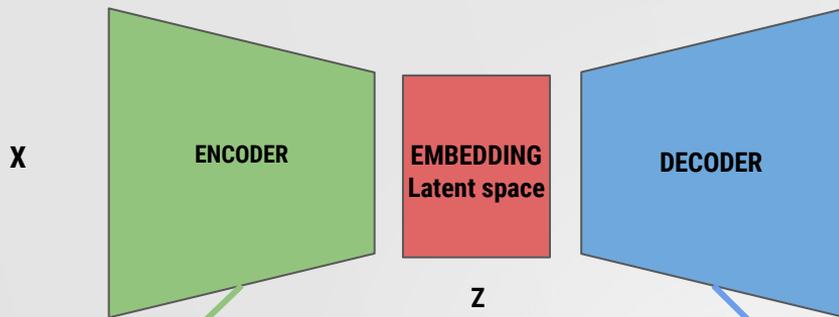
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# 04 Variational Autoencoders



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Distribution of the input

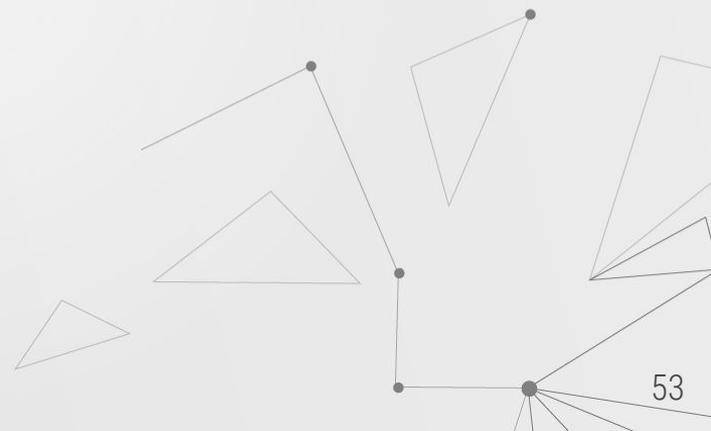
Multivariate Gaussian

# 04 Variational Autoencoders

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$$p(z|x) \quad q(z|x)$$

As much similar as possible...



## 04 Variational Autoencoders

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**KL-Divergence** → measures the distance between distributions

$$KL(q(z|x) || p(z|x))$$

## 04 Variational Autoencoders

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## 04 Variational Autoencoders

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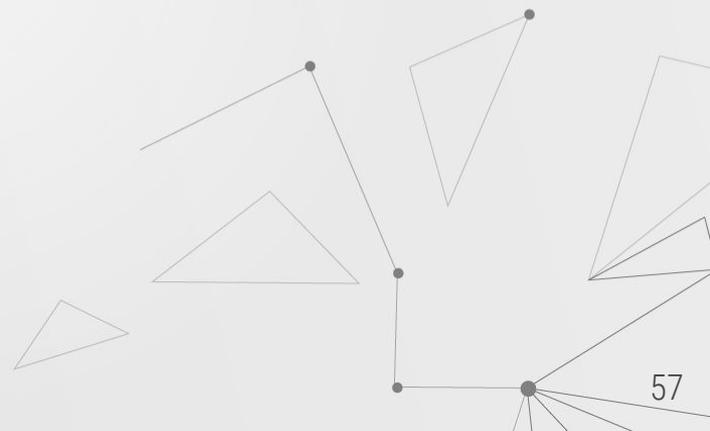
$$\min KL(q(z|x) || p(z|x))$$

## 04 Variational Autoencoders

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$$\min KL(q(z|x) || p(z|x))$$

Is it done?



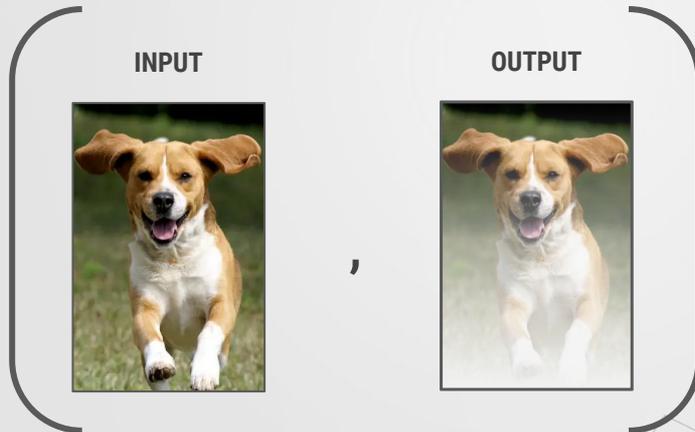
# 04 Variational Autoencoders

$$\min KL(q(z|x) || p(z|x))$$

Is it done?

**We cannot compute  $q(z|x)$**

LOSS = similarity



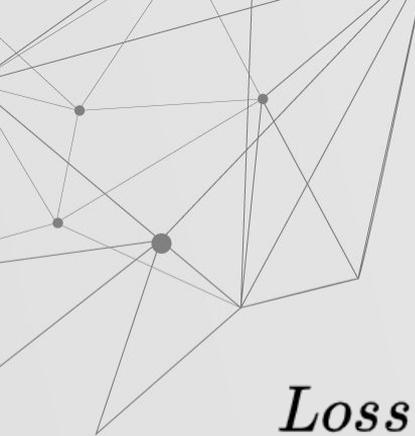
# 04 Variational Autoencoders

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$$Loss = -E_{p(z|x)} \log q(z|x) + KL(p(z|x)||q(z))$$

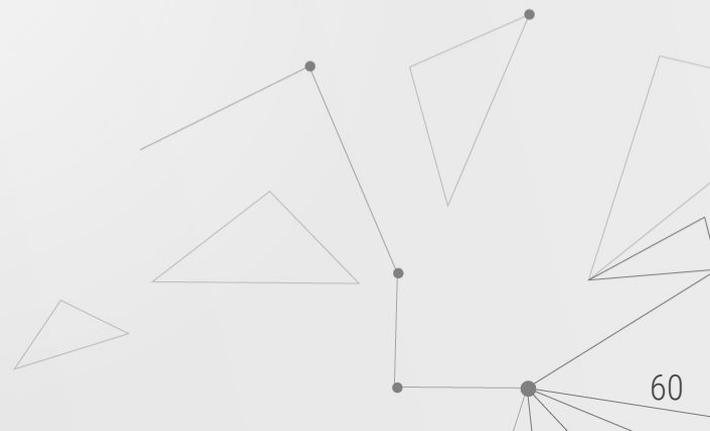
# 04 Variational Autoencoders

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$$Loss = -E_{p(z|x)} \log q(z|x) + KL(p(z|x) || q(z))$$

**Variational Lower Bound** [Reconstruction error]

How well the network is able to reconstruct the input?



# 04 Variational Autoencoders

$$Loss = -E_{p(z|x)} \log q(z|x) + KL(p(z|x) || q(z))$$

**Variational Lower Bound** [Reconstruction error]

How well the network is able to reconstruct the input?

**Regularizer**

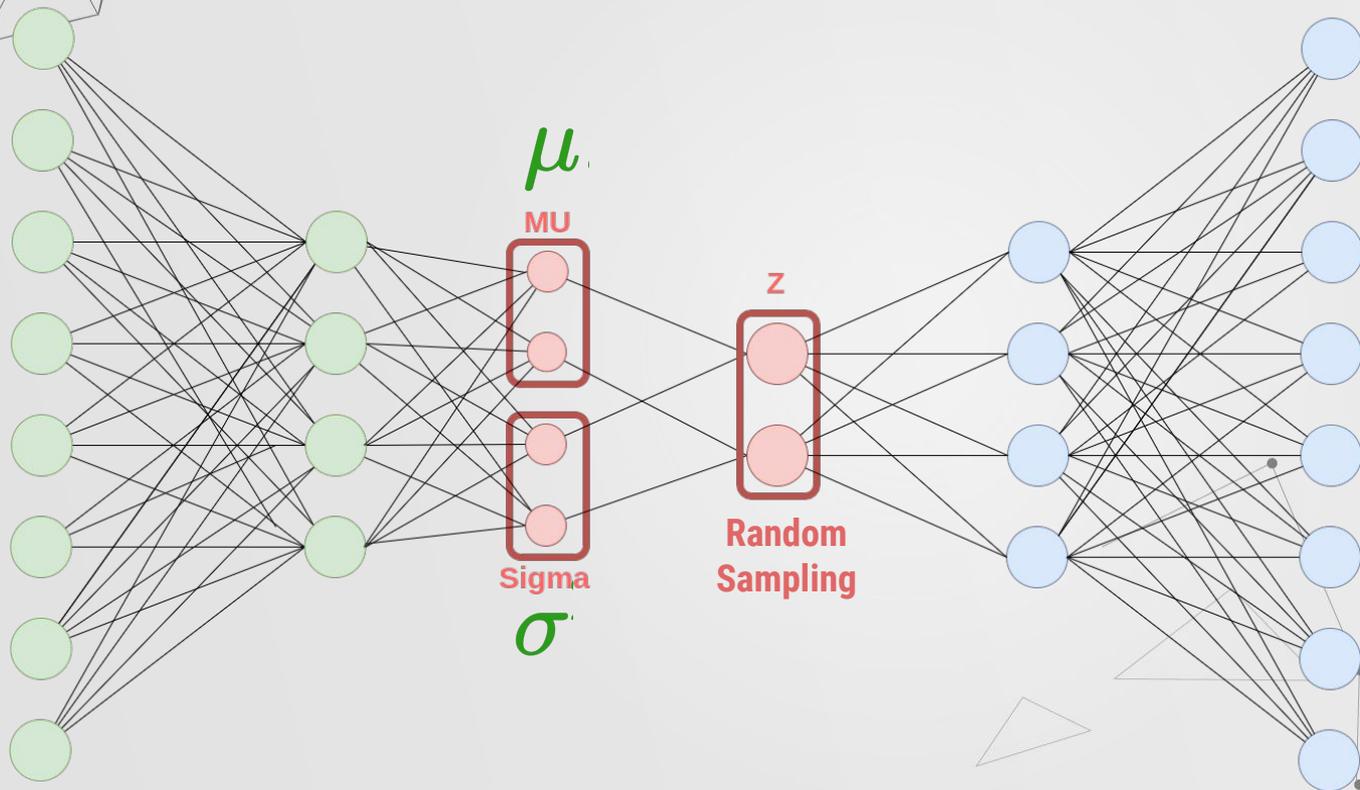
Keep the distributions of  $q(z|x)$  and  $p(z|x)$  as much similar as possible.

# 04 Variational Autoencoders

ENCODER

LATENT SPACE

DECODER

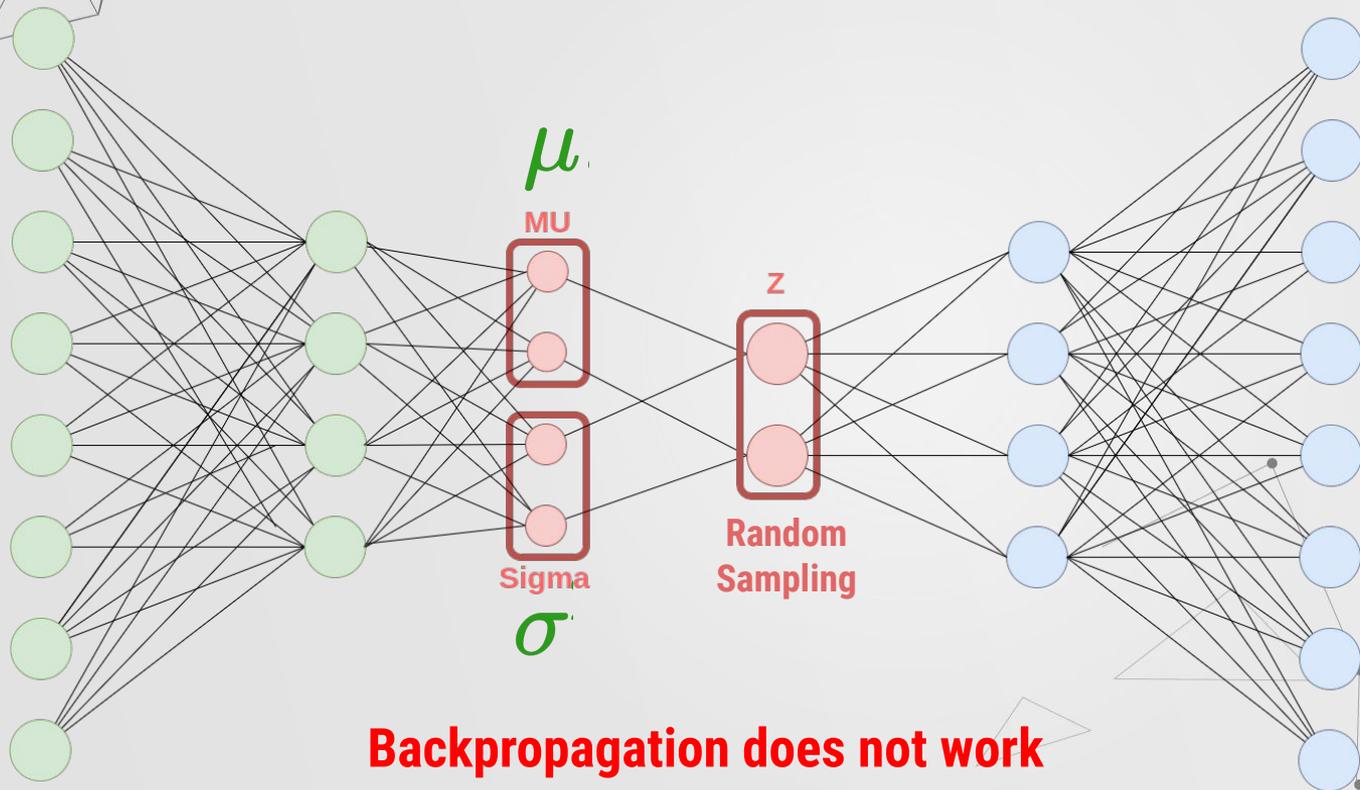


# 04 Variational Autoencoders

ENCODER

LATENT SPACE

DECODER



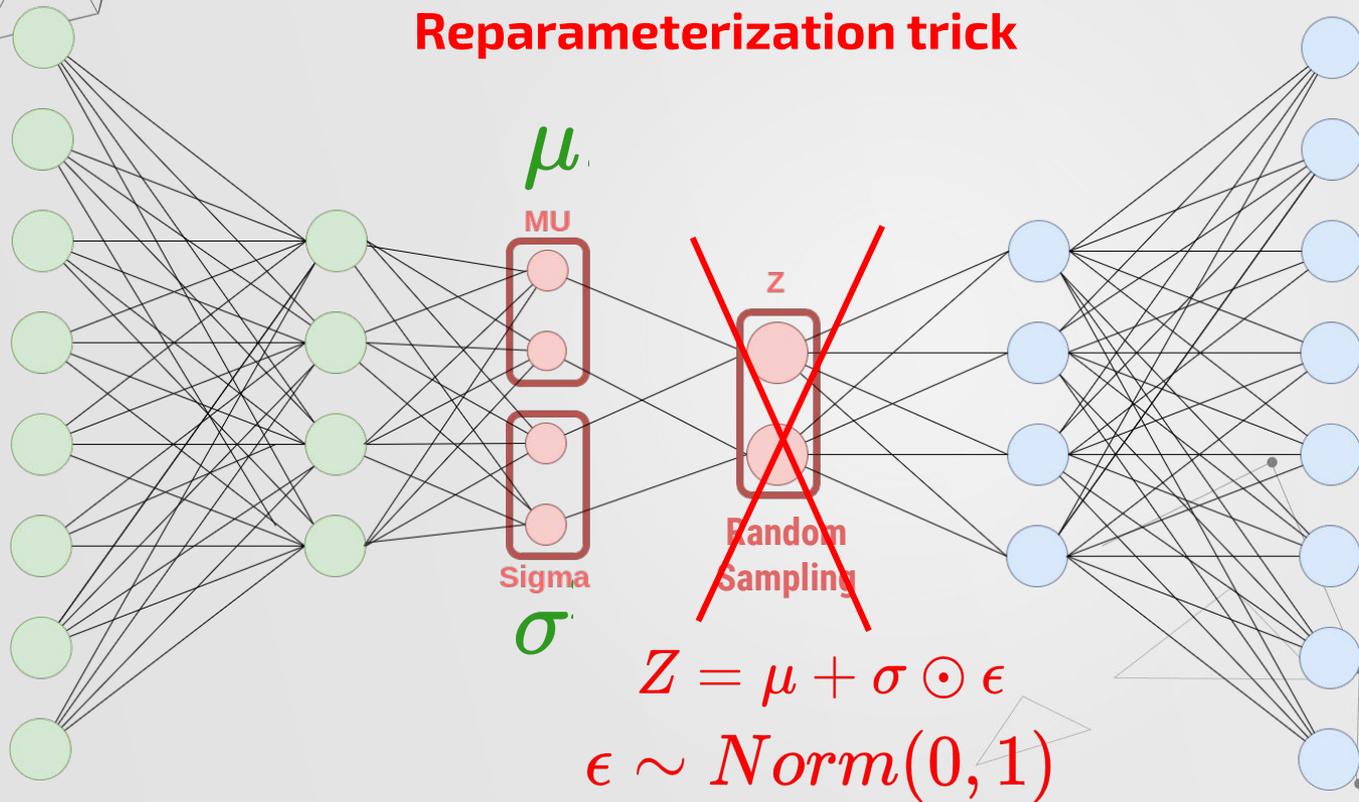
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ENCODER

LATENT SPACE

DECODER

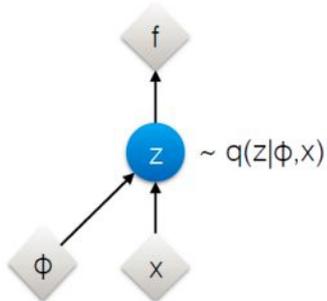
**Reparameterization trick**



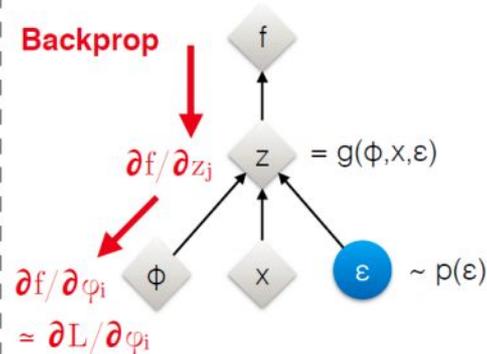
# 04 Variational Autoencoders

## Reparameterization trick

Original form



Reparameterised form



 : Deterministic node

 : Random node

[Kingma, 2013]

[Bengio, 2013]

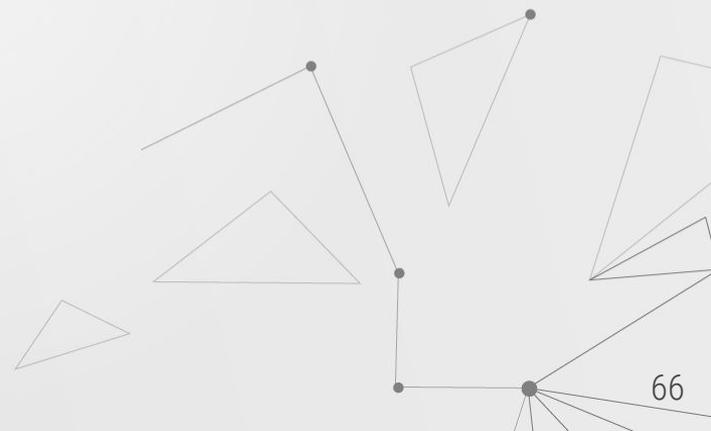
[Kingma and Welling 2014]

[Rezende et al 2014]

Kingma & Welling, NIPS workshop 2015

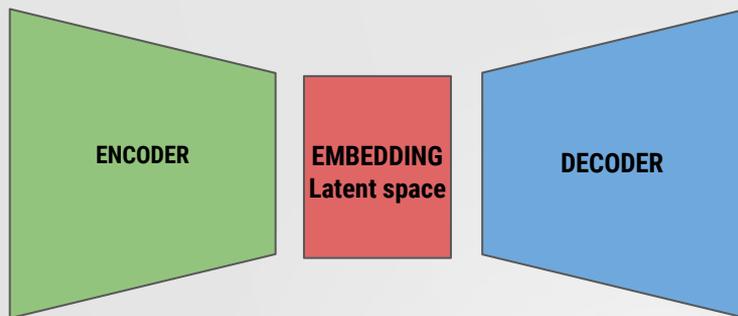
# 05 Graph Variational Autoencoders (GVAE) Theory

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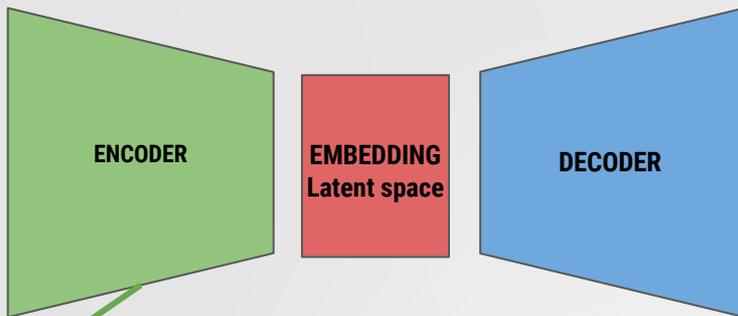


# 05 Graph Variational Autoencoders (GVAE) Theory

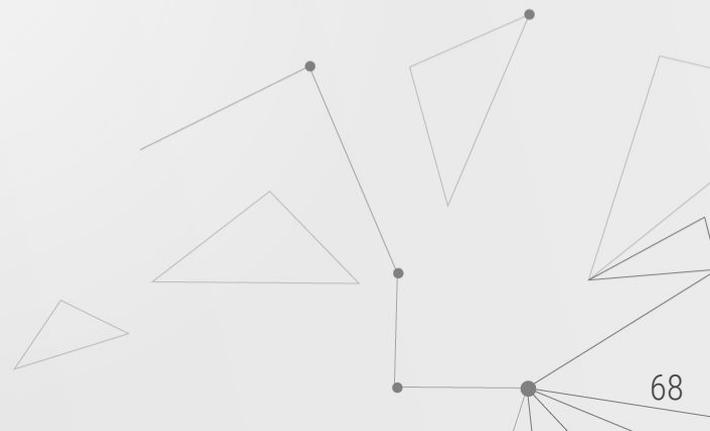
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# 05 Graph Variational Autoencoders (GVAE) Theory

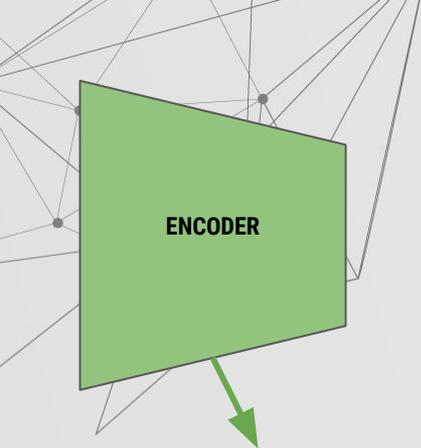


Two convolutional Graph neural networks:



# 05 Graph Variational Autoencoders (GVAE) Theory

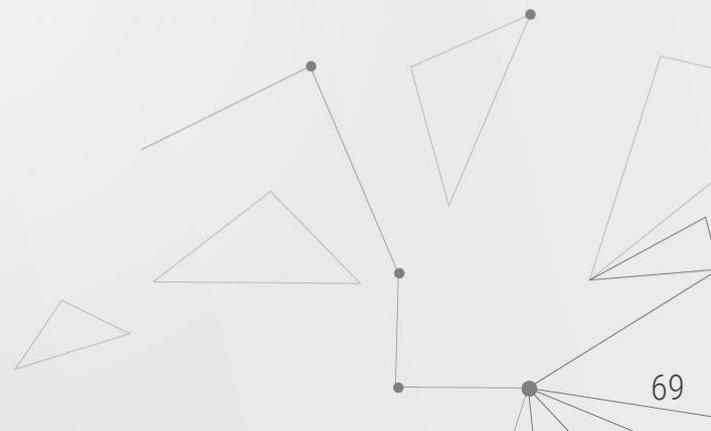
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TWO convolutional Graph neural networks:

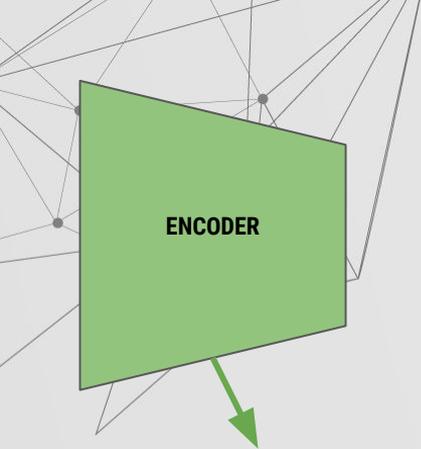
GCN 1: produces an low dimensional embedding representation

GCN 2: generates  $\mu$  and  $\log \sigma^2$



# 05 Graph Variational Autoencoders (GVAE) Theory

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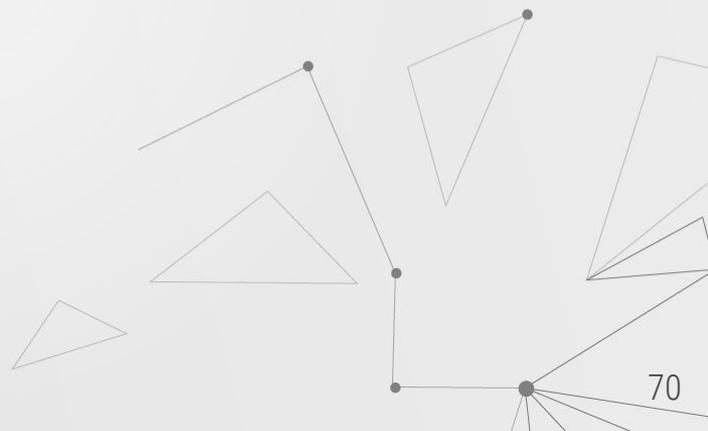


TWO convolutional Graph neural networks:

$$\bar{X} = GCN(A, X)$$

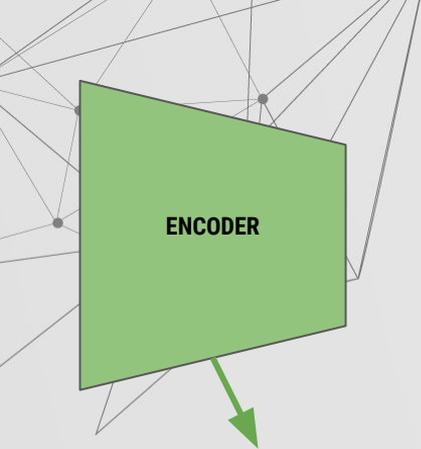
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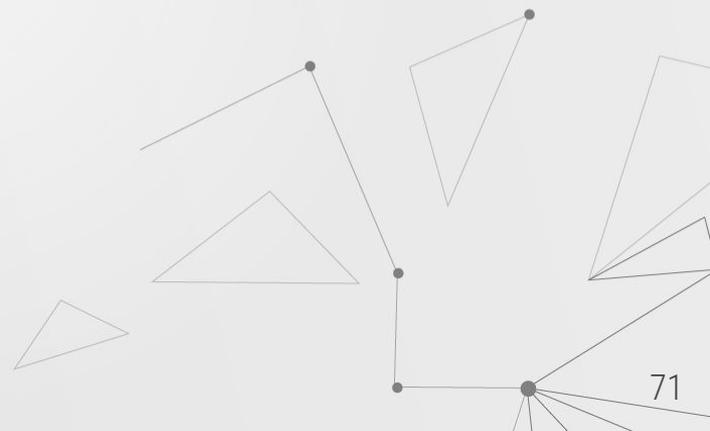


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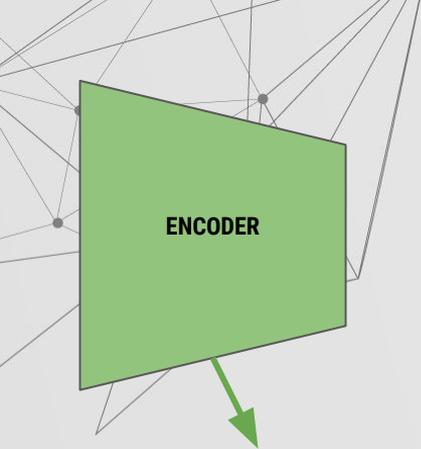
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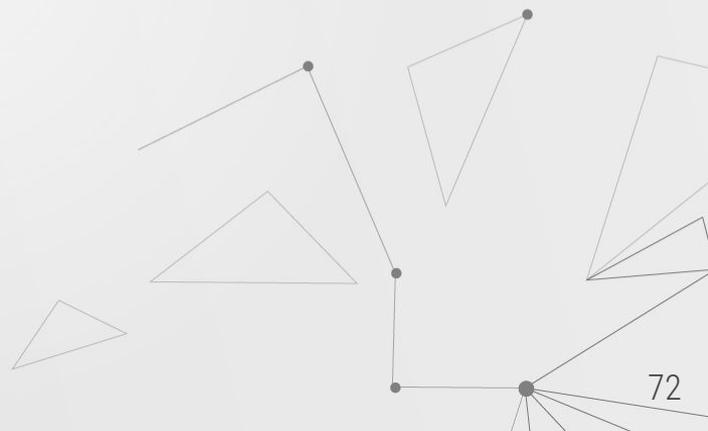
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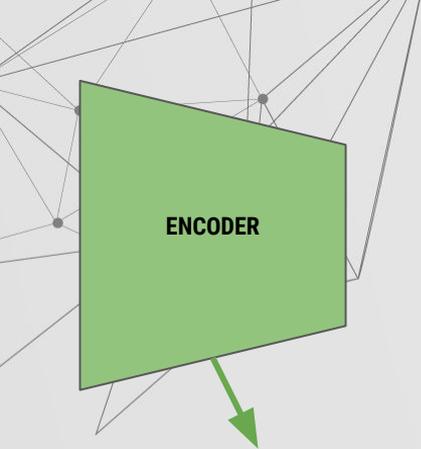
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$$\text{with } \tilde{A} = D^{-1/2}AD^{-1/2}$$

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# 05 Graph Variational Autoencoders (GVAE) Theory



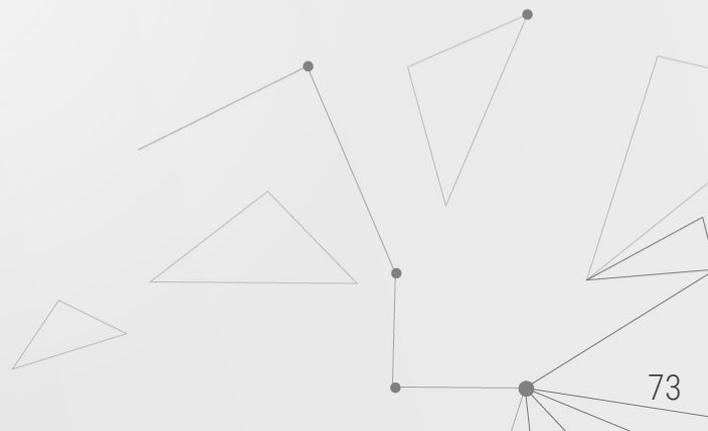
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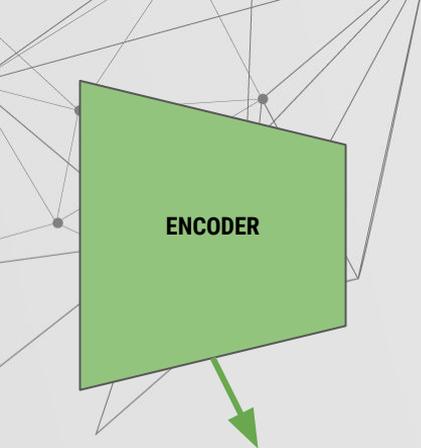
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# 05 Graph Variational Autoencoders (GVAE) Theory



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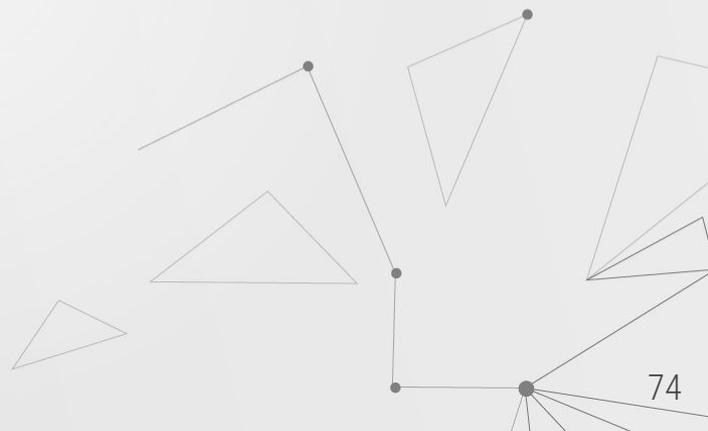
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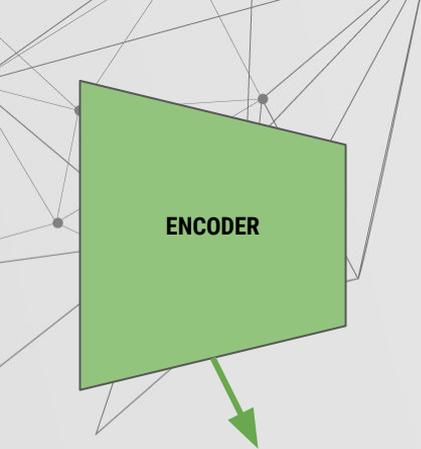
$$\text{with } \tilde{A} = D^{-1/2}AD^{-1/2}$$

**GCN 2: generates  $\mu$  and  $\log \sigma^2$**


$$\mu = GCN_{\mu}(X, A) = \tilde{A}\bar{X}W_1$$



# 05 Graph Variational Autoencoders (GVAE) Theory



TWO convolutional Graph neural networks:

GCN 1: produces an low dimensional embedding representation

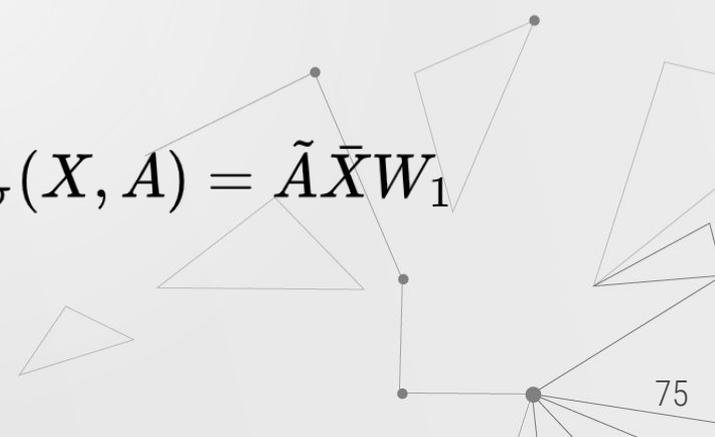
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GCN 2: generates  $\mu$  and  $\log \sigma^2$

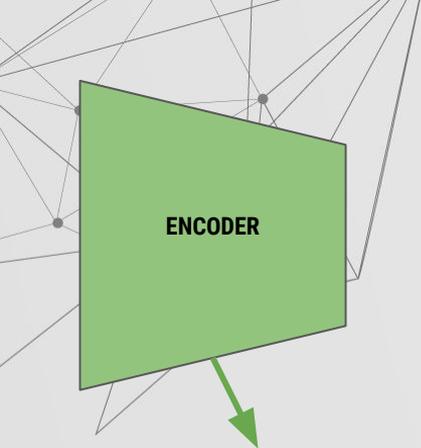
$$\mu = GCN_{\mu}(X, A) = \tilde{A}\bar{X}W_1$$

$$\log \sigma^2 = GCN_{\sigma}(X, A) = \tilde{A}\bar{X}W_1$$



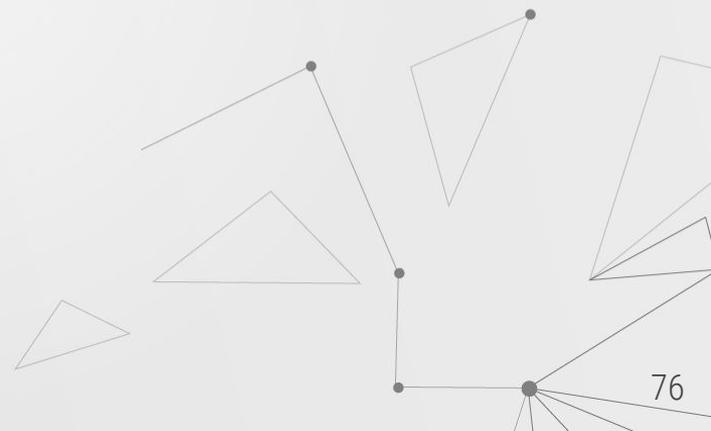
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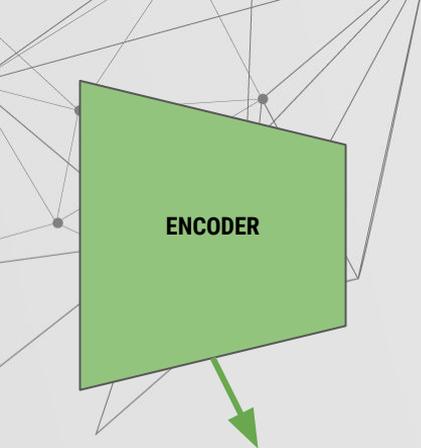


$$GCN(A, X) = \tilde{A}ReLU(\tilde{A}XW_0)W_1$$

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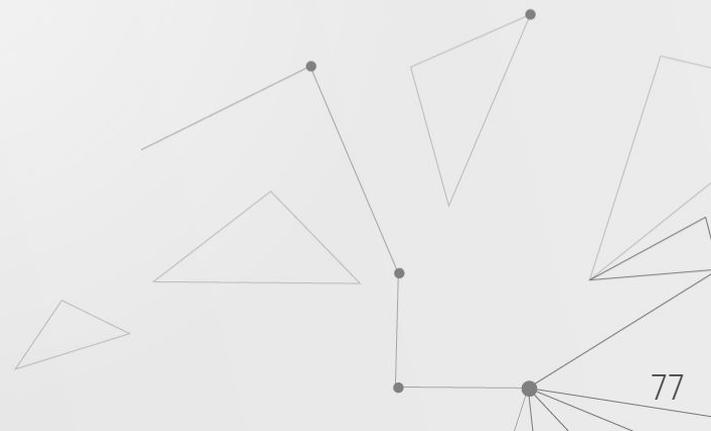


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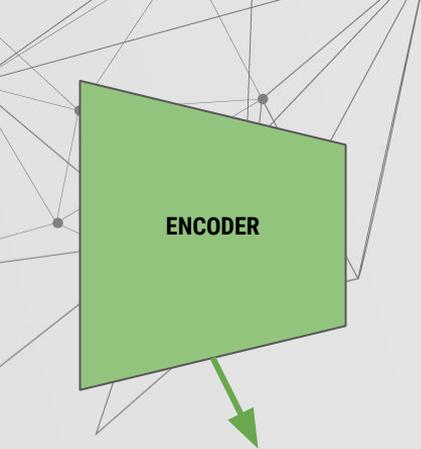


$$GCN(A, X) = \tilde{A} \overbrace{ReLU(\tilde{A} X W_0)}^{1^\circ \text{ GCN}} W_1$$

with  $\tilde{A} = D^{-1/2} A D^{-1/2}$



# 05 Graph Variational Autoencoders (GVAE) Theory

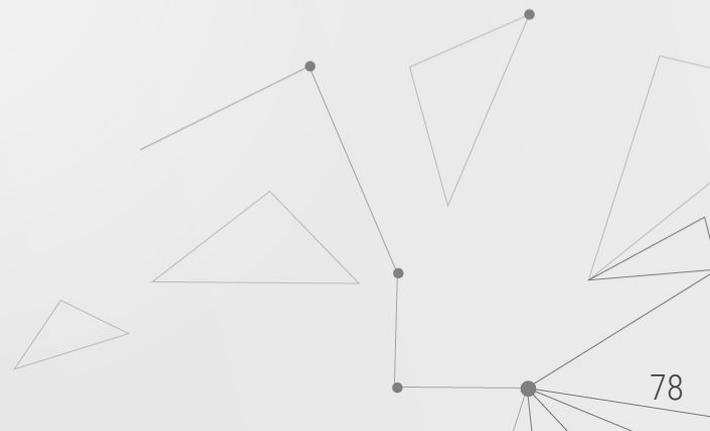


2° GCN

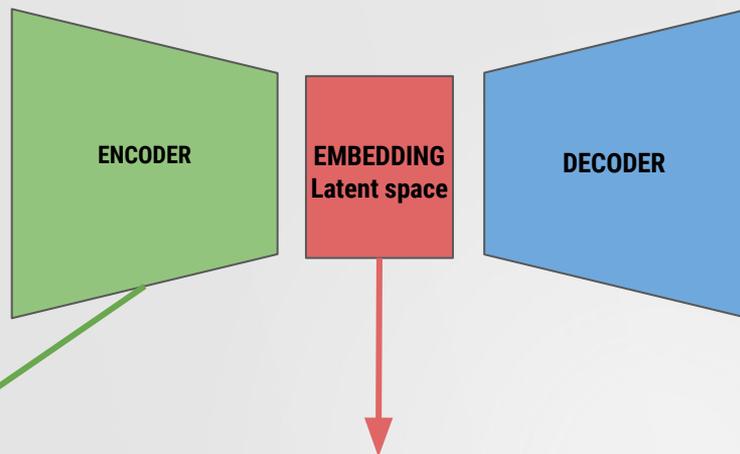
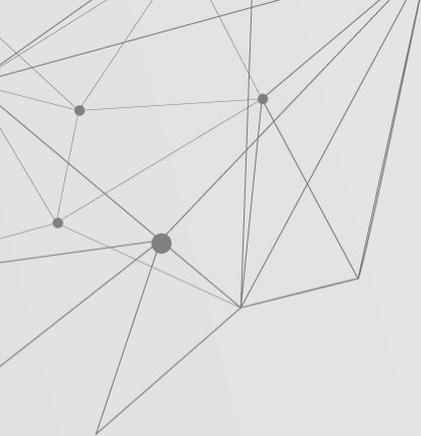
1° GCN

$$GCN(A, X) = \tilde{A} \text{ReLU}(\tilde{A} X W_0) W_1$$

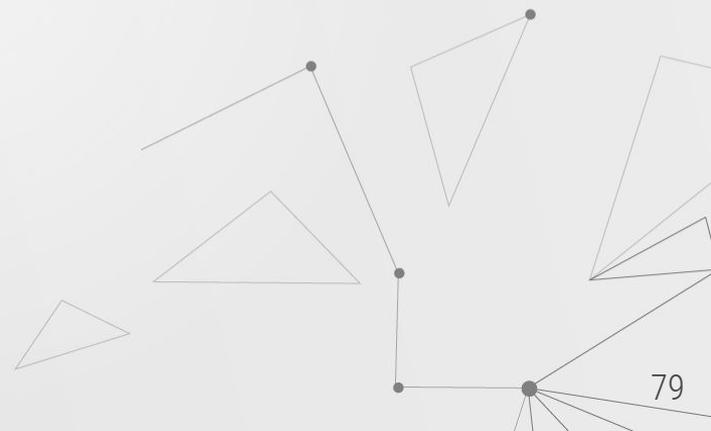
$$\text{with } \tilde{A} = D^{-1/2} A D^{-1/2}$$



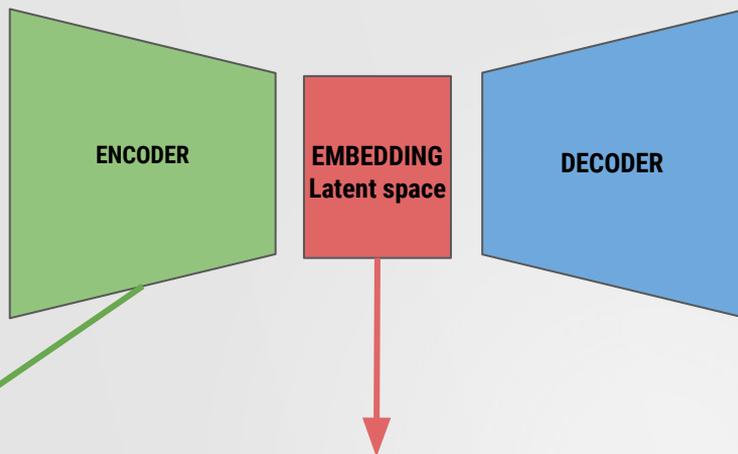
# 05 Graph Variational Autoencoders (GVAE) Theory



$$GCN(A, X) = \tilde{A} ReLU(\tilde{A} X W_0) W_1$$



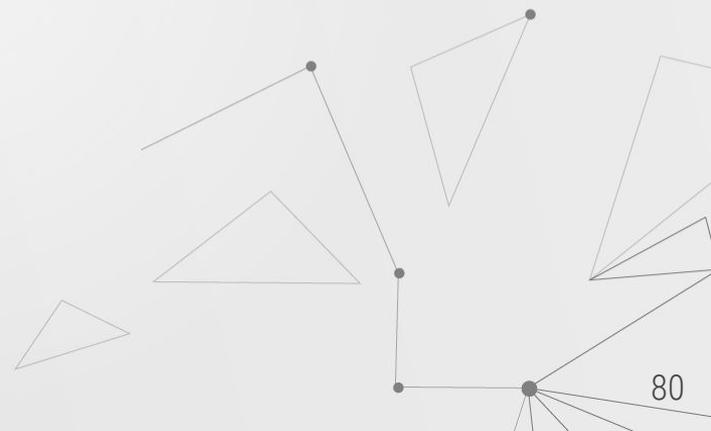
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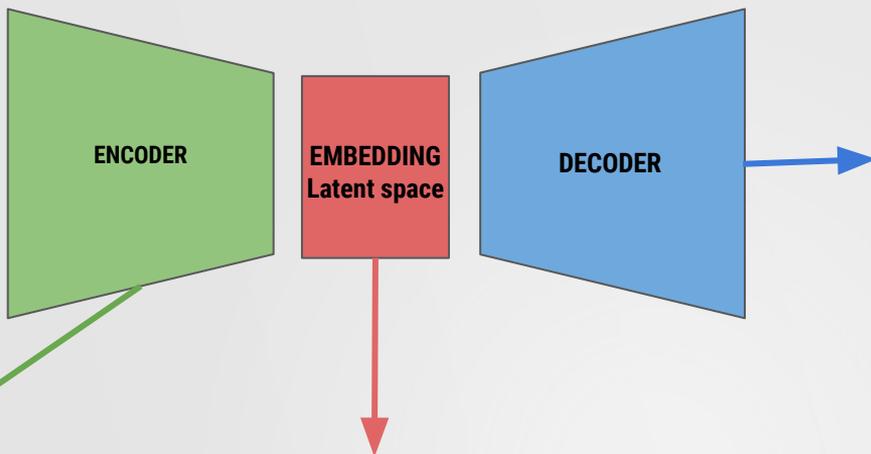
$$GCN(A, X) = \tilde{A}ReLU(\tilde{A}XW_0)W_1$$

Reparameterization  
trick

$$Z = \mu + \sigma \odot \epsilon$$
$$\epsilon \sim Norm(0, 1)$$



# 05 Graph Variational Autoencoders (GVAE) Theory



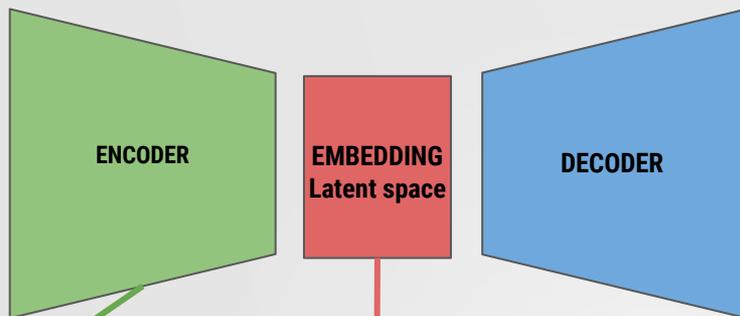
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Reparameterization  
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# 05 Graph Variational Autoencoders (GVAE) Theory



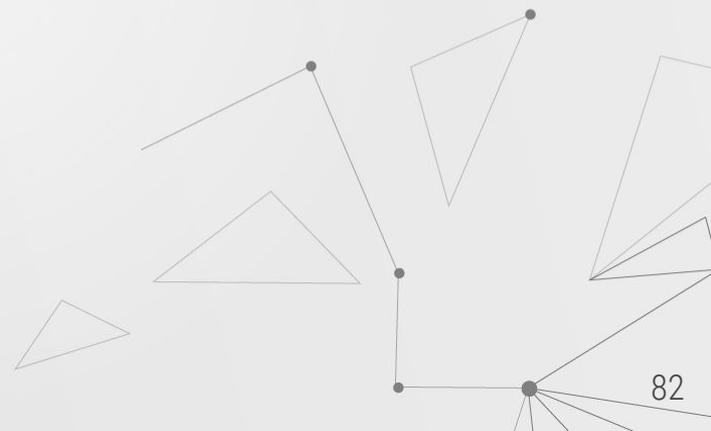
Inner product  
Between latent variable  $Z$

$$\hat{A} = \text{logistic sigmoid}(zz^T)$$

$$GCN(A, X) = \tilde{A} \text{ReLU}(\tilde{A}XW_0)W_1$$

Reparameterization  
trick

$$Z = \mu + \sigma \odot \epsilon$$
$$\epsilon \sim \text{Norm}(0, 1)$$



# 05 Graph Variational Autoencoders (GVAE) Practice

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Jupyter Notebook

