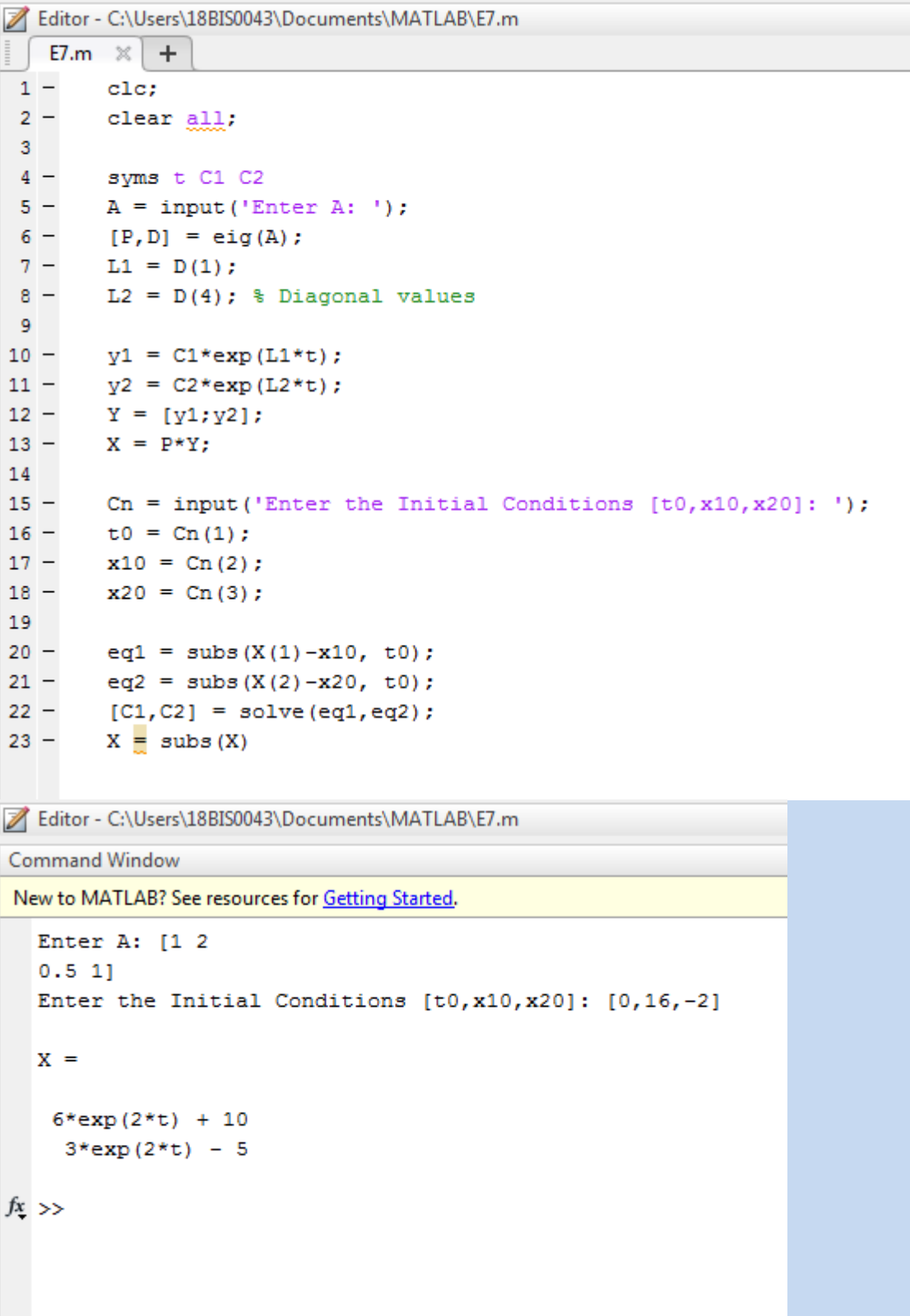


Experiment – 7

1.



The image displays the MATLAB environment. The Editor window shows a script named E7.m with the following code:

```
1 - clc;
2 - clear all;
3
4 - syms t C1 C2
5 - A = input('Enter A: ');
6 - [P,D] = eig(A);
7 - L1 = D(1);
8 - L2 = D(4); % Diagonal values
9
10 - y1 = C1*exp(L1*t);
11 - y2 = C2*exp(L2*t);
12 - Y = [y1;y2];
13 - X = P*Y;
14
15 - Cn = input('Enter the Initial Conditions [t0,x10,x20]: ');
16 - t0 = Cn(1);
17 - x10 = Cn(2);
18 - x20 = Cn(3);
19
20 - eq1 = subs(X(1)-x10, t0);
21 - eq2 = subs(X(2)-x20, t0);
22 - [C1,C2] = solve(eq1,eq2);
23 - X = subs(X)
```

The Command Window shows the execution of the script with the following input and output:

```
Enter A: [1 2
0.5 1]
Enter the Initial Conditions [t0,x10,x20]: [0,16,-2]

X =

6*exp(2*t) + 10
3*exp(2*t) - 5

fx >>
```

2.

```
Editor - C:\Users\18BIS0043\Documents\MATLAB\E7_2.m
E7.m  E7_2.m  +
1 -   clc
2 -   clear all;
3 -   A = input('Enter A: ');
4 -   [P D] = eig(A);
5
6 -   S1 = dsolve(['D2y = ', num2str(D(1)), '*y']);
7 -   S2 = dsolve(['D2y = ', num2str(D(4)), '*y']);
8
9 -   X = P*[S1;S2];
10 -  disp('x1 = ');disp(X(1));
11 -  disp('x2 = ');disp(X(2));
```

```
Command Window
New to MATLAB? See resources for Getting Started.

Enter A: [2 1;9 2]
x1 =
(10^(1/2)*(C3*exp(5^(1/2)*t) + C4*exp(-5^(1/2)*t)))/10 - (10^(1/2)*(C6*cos(t) + C7*sin(t)))/10

x2 =
(3*10^(1/2)*(C6*cos(t) + C7*sin(t)))/10 + (3*10^(1/2)*(C3*exp(5^(1/2)*t) + C4*exp(-5^(1/2)*t)))/10

fx >>
```

20/9/19

Experiment - 7

classmate

Date

Page 22

→ System of first order linear differential equations

$$\begin{cases} x_1' = a_{11}x_1 + a_{12}x_2 + a_{13}x_3 \dots a_{1n}x_n + g_1(t) \\ x_2' = a_{21}x_1 + a_{22}x_2 + a_{23}x_3 \dots a_{2n}x_n + g_2(t) \\ \vdots \\ x_n' = a_{n1}x_1 + a_{n2}x_2 + a_{n3}x_3 \dots a_{nn}x_n + g_n(t) \end{cases}$$

System of 'n' linear first order differential equations in 'n' unknowns (an $n \times n$ system of linear equations).

• If every term $g_i(t)$, where 'i' is from (1 to n), is zero, then the system is said to be homogenous.

$$\bullet \quad x' = Ax + G,$$

This system will have a general solution,

$$X = C_1 x_1 e^{\lambda_1 t} + C_2 x_2 e^{\lambda_2 t}$$

$$\text{and } \dot{X} = AX \quad \text{--- (1)}$$

For a second order system of differential equations,

$$\ddot{X} = AX \quad \text{--- (2)}$$



→ System of second order linear differential equations

$$\begin{cases} x_1'' = a_{11}x_1 + a_{12}x_2 + a_{13}x_3 + \dots + a_{1n}x_n \\ x_2'' = a_{21}x_1 + a_{22}x_2 + a_{23}x_3 + \dots + a_{2n}x_n \\ \vdots \\ x_n'' = a_{n1}x_1 + a_{n2}x_2 + a_{n3}x_3 + \dots + a_{nn}x_n \end{cases}$$

System of second order linear differential equations where the coefficients a_{ij} 's are arbitrary constants

$$\begin{aligned} 1. \quad \ddot{x}_1 &= x_1 + 2x_2 & x_1(0) &= 16 \\ \ddot{x}_2 &= 0.5x_1 + x_2 & x_2(0) &= -2 \end{aligned}$$

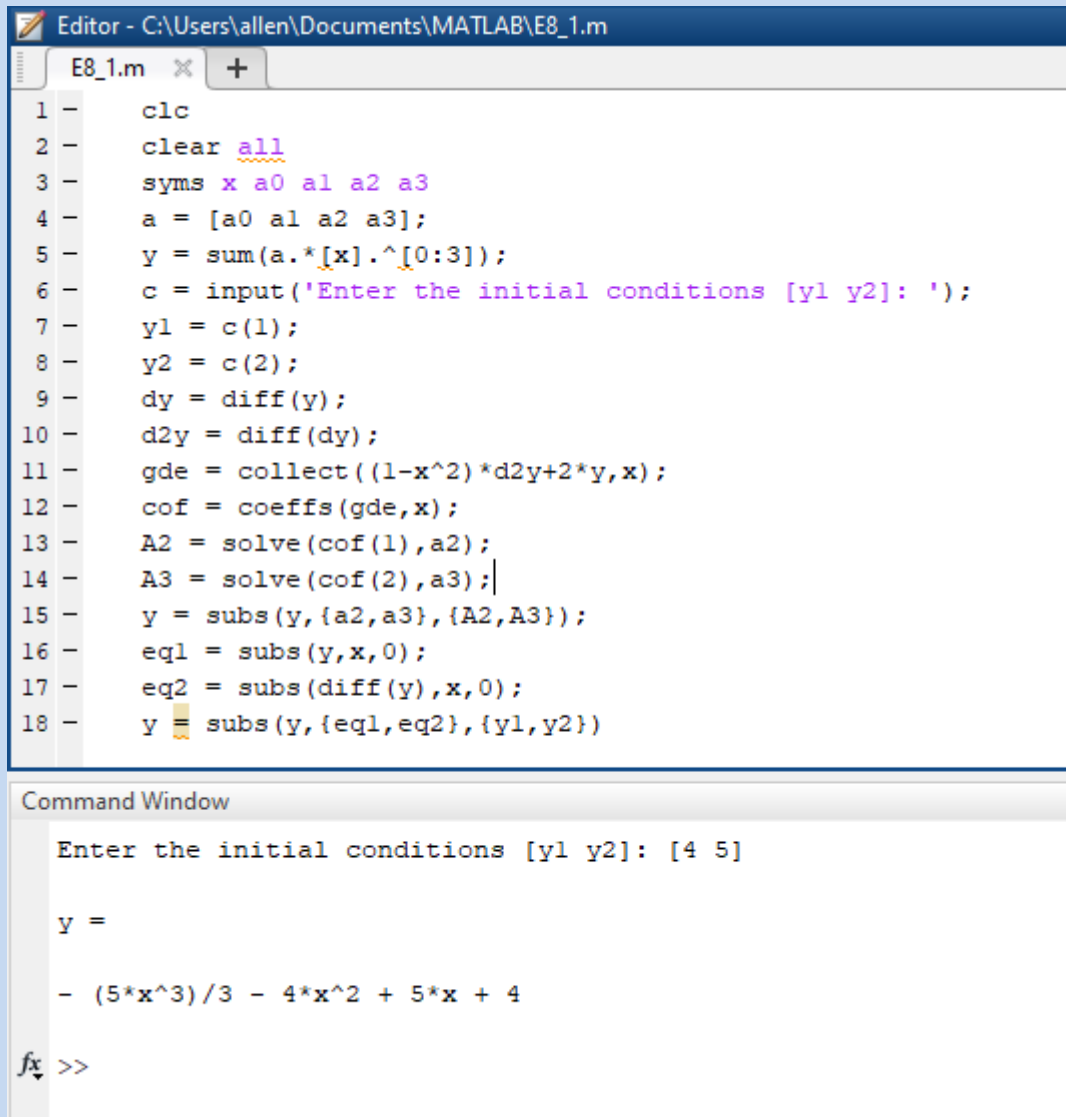
Aim: Solve using matrix method in matlab

$$\begin{aligned} 2. \quad \ddot{x}_1 &= 2x_1 + x_2 \\ \ddot{x}_2 &= 9x_1 + 2x_2 \end{aligned}$$

Aim: Solve using dsolve function.

Experiment – 8

2.



The image shows a MATLAB Editor window titled 'Editor - C:\Users\allen\Documents\MATLAB\E8_1.m' with a tab for 'E8_1.m'. The script contains 18 lines of MATLAB code. Below the editor is the Command Window, which shows the execution of the script, including the input for initial conditions and the resulting symbolic solution for y.

```
1 - clc
2 - clear all
3 - syms x a0 a1 a2 a3
4 - a = [a0 a1 a2 a3];
5 - y = sum(a.*[x].^[0:3]);
6 - c = input('Enter the initial conditions [y1 y2]: ');
7 - y1 = c(1);
8 - y2 = c(2);
9 - dy = diff(y);
10 - d2y = diff(dy);
11 - gde = collect((1-x^2)*d2y+2*y,x);
12 - cof = coeffs(gde,x);
13 - A2 = solve(cof(1),a2);
14 - A3 = solve(cof(2),a3);
15 - y = subs(y,{a2,a3},{A2,A3});
16 - eq1 = subs(y,x,0);
17 - eq2 = subs(diff(y),x,0);
18 - y = subs(y,{eq1,eq2},{y1,y2})
```

Command Window

```
Enter the initial conditions [y1 y2]: [4 5]

y =

- (5*x^3)/3 - 4*x^2 + 5*x + 4

fx >>
```


13/10/19

Experiment-8

classmate

Date

Page 24

→ Series solutions of ordinary differential equations

- Series solution when $x=0$ is an ordinary point of the equation:

$$P_0 \frac{d^2y}{dx^2} + P_1 \frac{dy}{dx} + P_2 y = 0 \quad \text{--- (1)}$$

where P 's are polynomial functions of x and $P_0 \neq 0$ at $x=0$.

- Assume its solution to be in the form:

$$y = a_0 + a_1x + a_2x^2 + \dots + a_nx^n \quad \text{--- (2)}$$

- Calculate dy/dx , d^2y/dx^2 and substitute in the values of y , dy/dx , d^2y/dx^2 in (1) from (2)
- Equate to zero the coefficients of the various powers of n and determine a_2, a_3, \dots, a_n in terms of a_0 and a_1 .
- Substituting the values of a_2, a_3, a_4, \dots in (2), we get the desired series having a_0 and a_1 as arbitrary constants

1. Solve in series equation

$$\frac{d^2y}{dx^2} + y = 0$$

Output: $dy = 3a_3x^2 + 2a_1x + a_1$

$$d^2y = 2a_2 + 6a_3x$$



Scanned with
CamScanner

Solution is :

$$y = A \left\{ 1 - \frac{x^2}{2} + \frac{x^4}{3} + \dots \right\} + B \left\{ x - \frac{x^3}{8} + \dots \right\}$$

2. $(1-x)y'' + 2y = 0$

$$y(0) = 4$$

$$y'(0) = 5$$

Output : $y = -\frac{5x^3}{3} - 4x^2 + 5x + 4$

