



IoT Fundamentals – ECE3501

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Lab Task – 3

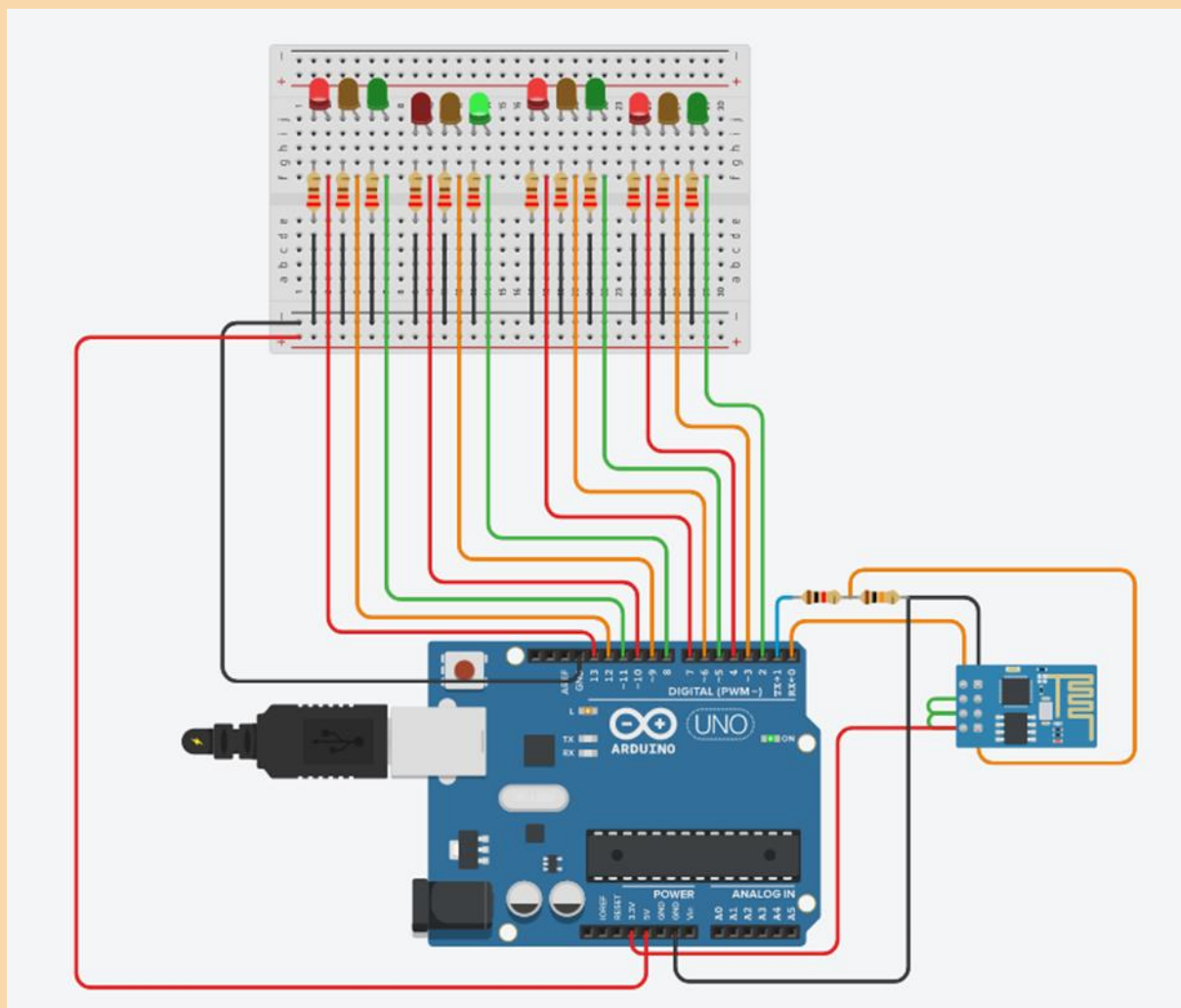
To: Prof. Suresh Chavhan

REGULAR TRAFFIC SIGNAL SYSTEM

Aim

To design a circuit using Arduino for simulating a regular traffic signal system, based on micro controller delay calculation only.

Circuit Diagram



Tools Required

Tinkercad – for simulating the connection and coding of the Arduino circuit

Output from Tinkercad

Traffic lights changing at regular intervals with effective and visible transitions, to simulate the real-life traffic system

Code

```
/*  
  
String ssid      = "Simulator Wifi"; // SSID to  
connect to  
  
String password = ""; // Our virtual wifi has no  
password  
  
String host      = "api.thingspeak.com"; // Open  
Weather Map API  
  
const int httpPort = 80;  
  
String      uri                                     =  
"/update?api_key=LCD1W6801CZS8ULS&field1=";  
  
int setupESP8266(void) {  
    // Start our ESP8266 Serial Communication
```

```
    Serial.begin(115200);    // Serial connection
over USB to computer

    Serial.println("AT");    // Serial connection
on Tx / Rx port to ESP8266

    delay(10);              // Wait a little for the ESP
to respond

    if (!Serial.find("OK")) return 1;

    // Connect to 123D Circuits Simulator Wifi
    Serial.println("AT+CWJAP=\"" + ssid + "\",\""
+ password + "\"");

    delay(10);              // Wait a little for the ESP
to respond

    if (!Serial.find("OK")) return 2;

    // Open TCP connection to the host:
    Serial.println("AT+CIPSTART=\"TCP\",\""      +
host + "\",\" + httpPort);

    delay(50);              // Wait a little for the ESP
to respond

    if (!Serial.find("OK")) return 3;

    return 0;

}
```

```
void anydata(void) {  
  
    int    temp    =    map(analogRead(A0),20,358,-  
40,125);  
  
    // Construct our HTTP call  
    String httpPacket = "GET " + uri + String(temp)  
+ " HTTP/1.1\r\nHost: " + host + "\r\n\r\n";  
    int length = httpPacket.length();  
  
    // Send our message length  
    Serial.print("AT+CIPSEND=");  
    Serial.println(length);  
    delay(10); // Wait a little for the ESP to  
respond if (!Serial.find(">")) return -1;  
  
    // Send our http request  
    Serial.print(httpPacket);  
    delay(10); // Wait a little for the ESP to  
respond  
    if (!Serial.find("SEND OK\r\n")) return;  
}
```

```
*/  
  
void setup() {  
    for(int i=2;i<=13;i++)  
        {pinMode(i, OUTPUT);}  
    // setupESP8266();  
}  
  
void signal1() {  
    digitalWrite(12, LOW);  
    digitalWrite(4, HIGH);  
    digitalWrite(10, HIGH);  
    digitalWrite(7, HIGH);  
    digitalWrite(11, HIGH);  
    delay(4000);  
    digitalWrite(12, HIGH);  
    digitalWrite(11, LOW);  
    digitalWrite(9, HIGH);  
    digitalWrite(10, LOW);  
    delay(1000);  
    digitalWrite(12, LOW);  
    digitalWrite(13, HIGH);  
}
```

```
void signal2() {  
    digitalWrite(9, LOW);  
    digitalWrite(13, HIGH);  
    digitalWrite(7, HIGH);  
    digitalWrite(4, HIGH);  
    digitalWrite(8, HIGH);  
    delay(4000);  
    digitalWrite(9, HIGH);  
    digitalWrite(8, LOW);  
    digitalWrite(6, HIGH);  
    digitalWrite(7, LOW);  
    delay(1000);  
    digitalWrite(9, LOW);  
    digitalWrite(10, HIGH);  
}
```

```
void signal3() {  
    digitalWrite(6, LOW);  
    digitalWrite(13, HIGH);  
    digitalWrite(10, HIGH);  
    digitalWrite(4, HIGH);  
    digitalWrite(5, HIGH);
```

```
    delay(4000);  
    digitalWrite(6, HIGH);  
    digitalWrite(5, LOW);  
    digitalWrite(3, HIGH);  
    digitalWrite(4, LOW);  
    delay(1000);  
    digitalWrite(6, LOW);  
    digitalWrite(7, HIGH);  
}  
  
void signal4() {  
    digitalWrite(3, LOW);  
    digitalWrite(13, HIGH);  
    digitalWrite(10, HIGH);  
    digitalWrite(7, HIGH);  
    digitalWrite(2, HIGH);  
    delay(4000);  
    digitalWrite(3, HIGH);  
    digitalWrite(2, LOW);  
    digitalWrite(12, HIGH);  
    digitalWrite(13, LOW);  
    delay(1000);  
}
```



```
    digitalWrite(3, LOW);  
    digitalWrite(4, HIGH);  
}  
  
void loop() {  
    signal1();  
    signal2();  
    signal3();  
    signal4();  
    // anydata();  
    // delay(1000);  
}
```

Observations

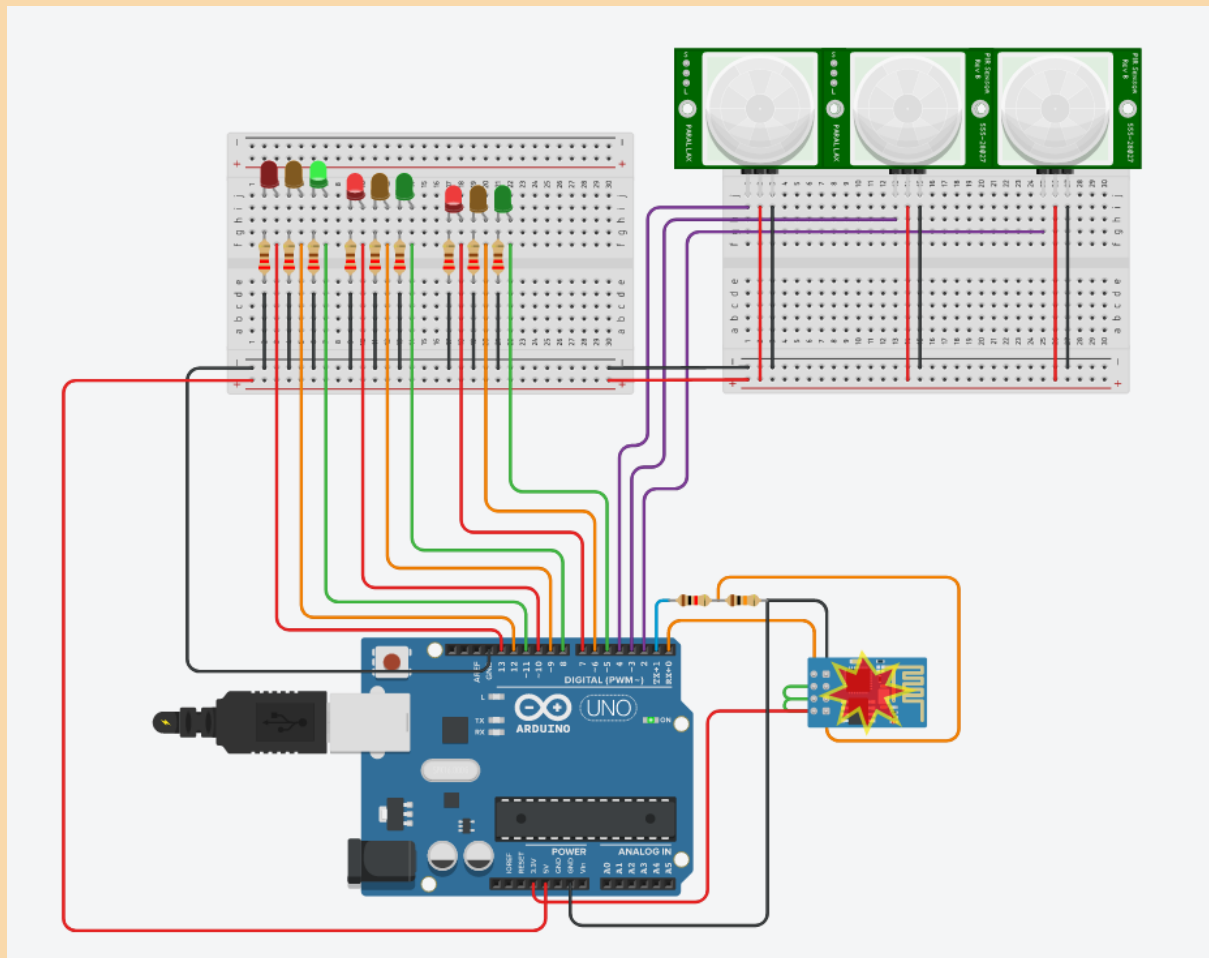
Program working as expected – minimal latency and user adjustable time delay which makes it easily manipulated and thus it is also effective for maintenance.

Conclusion

Therefore, by using Tinkercad, we simulated a circuit for a regular traffic signal system based on only delay calculation. Using PIR sensor in TinkerCad, we also can detect motion which can help to make the system smart and efficient – also implemented and attached to the same document.

SMART TRAFFIC SIGNAL SYSTEM

Circuit Diagram



Code

```
void setup() { // Initializing all pins
  for(int i=5;i<=13;i++){pinMode(i, OUTPUT);}
  for(int j=2;j<=4;j++) {pinMode(j, INPUT);}
```

```
    Serial.begin(9600);  
}
```

```
void transition(int al){ // Single function for  
all transitions
```

```
    int a=0;  
    if(al==7) {a=al+9;}  
    else {a=al;}  
    digitalWrite((al-1), HIGH);  
    digitalWrite((al-2), LOW);  
    digitalWrite((a-4), HIGH);  
    digitalWrite((a-3), LOW);  
    delay(300);  
    digitalWrite((al-1), LOW);  
    digitalWrite(al, HIGH);  
}
```

```
void on(int al) { // Single function for  
turning on signals
```

```
    for(int x=5;x<=13;x++) {digitalWrite(x,LOW);}  
    int a=0,b=0;
```

```
    if(al==7) {a=a+9;b=a+9;}
    else if(al==10) {a=a;b=a+9;}
    else {a=a;b=a;}
    digitalWrite(al-2,HIGH);
    digitalWrite((a-3),HIGH);
    digitalWrite((b-6),HIGH);
    delay(1200);
}

void call(int al) {on(al); transition(al);}

void loop() {
    if(digitalRead(4)==HIGH &&
digitalRead(3)==LOW && digitalRead(2)==LOW) {
        Serial.println("Congestion at Signal 1");
        while(digitalRead(4)==HIGH) {on(13);}
        transition(13);
        Serial.println("Signal 1 Cleared");
        call(10); call(7);
    }

    else if(digitalRead(4)==LOW &&
digitalRead(3)==HIGH && digitalRead(2)==LOW) {
```

```
    call(13);  
    Serial.println("Congestion at Signal 2");  
    while(digitalRead(3)==HIGH){on(10);}   
    transition(10);  
    Serial.println("Signal 2 Cleared");  
    call(7);  
}  
  
else if(digitalRead(4)==LOW &&  
digitalRead(3)==LOW && digitalRead(2)==HIGH) {  
    call(13); call(10);  
    Serial.println("Congestion at Signal 3");  
    while(digitalRead(2)==HIGH) {on(7);}   
    transition(7);  
    Serial.println("Signal 3 Cleared");  
}  
  
else {  
    call(13);  
    call(10);  
    call(7);  
}  
}
```

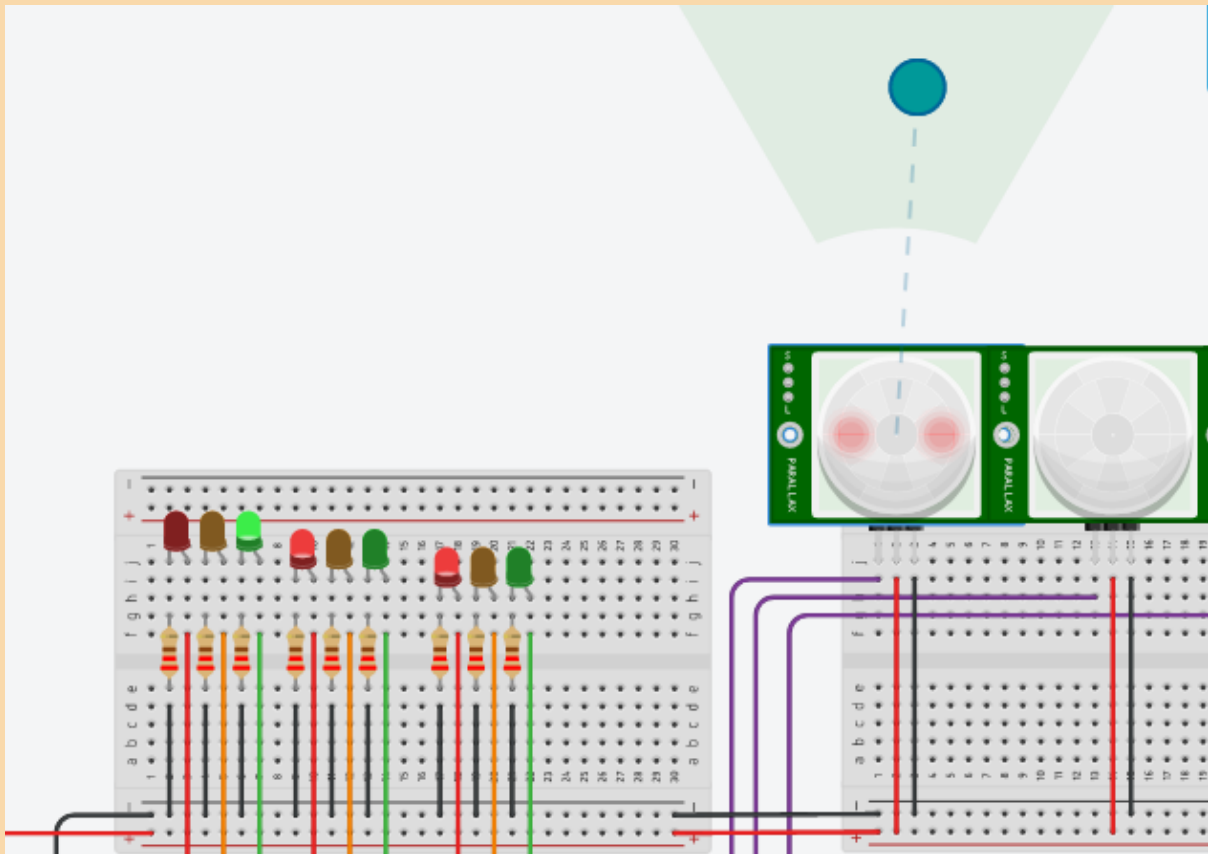
Output from TinkerCad



Serial Monitor

```
Congestion at Signal 1  
Signal 1 Cleared
```

Working circuit



The red glow shows that the sensor is active and is detecting the traffic congestion at signal 1. This turns the signal green until the sensor becomes inactive – after which, the regular cycle repeats.