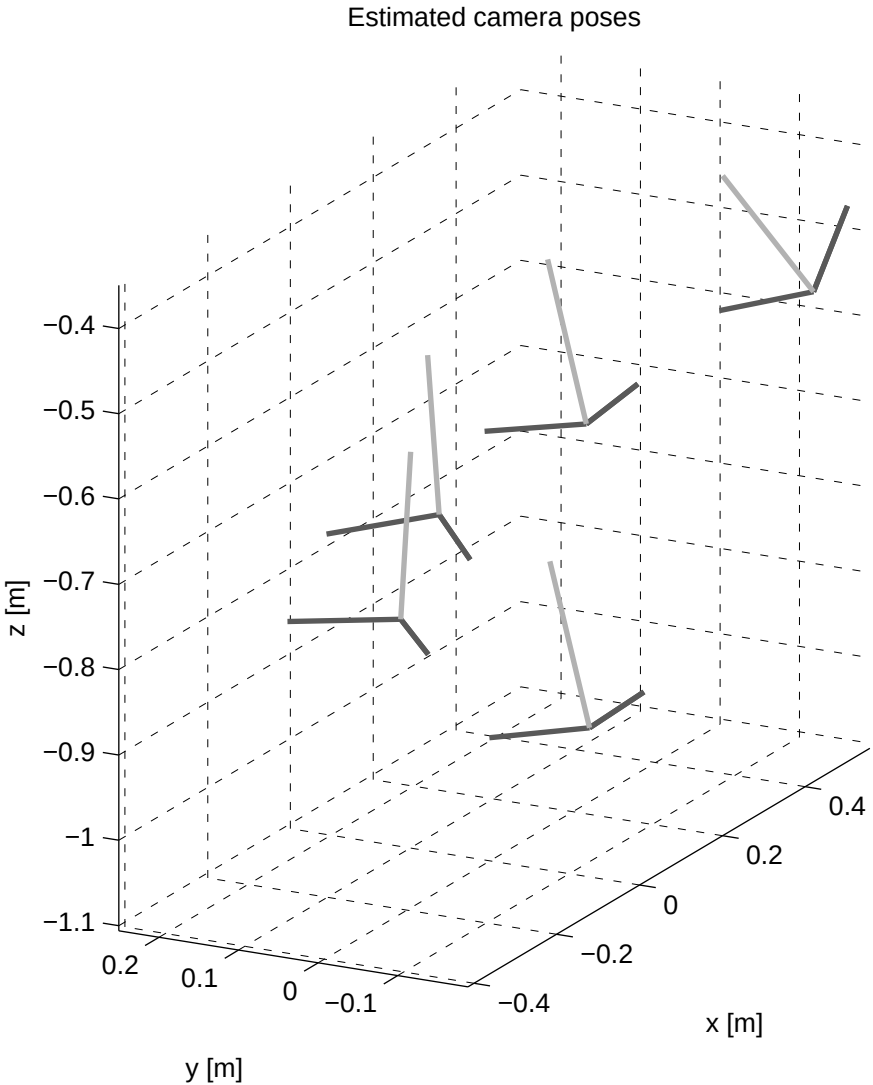
Estimated camera poses
z [m]
−0.4
−0.5
−0.6
−0.7
−0.8
−0.9
−1
−1.1
y [m]
0.2
0.1
0
−0.1
x [m]
−0.4
−0.2
0
0.2
0.4