

# Latent Variable Models (Part 3)

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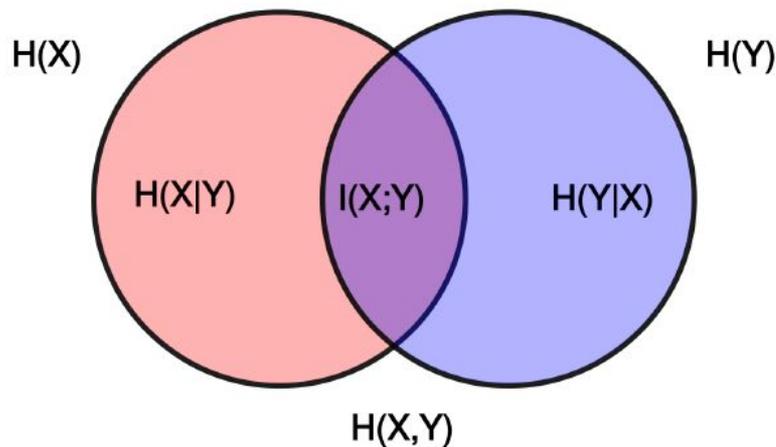
# Outline

- Warm-up on Variational Inference
  - ~~Recap~~
  - ~~An importance sampling view~~
  - **Variational Mutual Information Estimation/Maximization**
  - Variational Dequantization
- Improving VAEs
  - ~~Reducing variational gap~~
  - ~~More flexible decoder & posterior collapse problem~~
  - More expressive architectures

# Mutual Information

- Mutual Information between two random variables  $X, Y$ :  $I(X;Y)$  is defined as:

$$I(X;Y) = H(X) - H(X|Y) = H(Y) - H(Y|X)$$

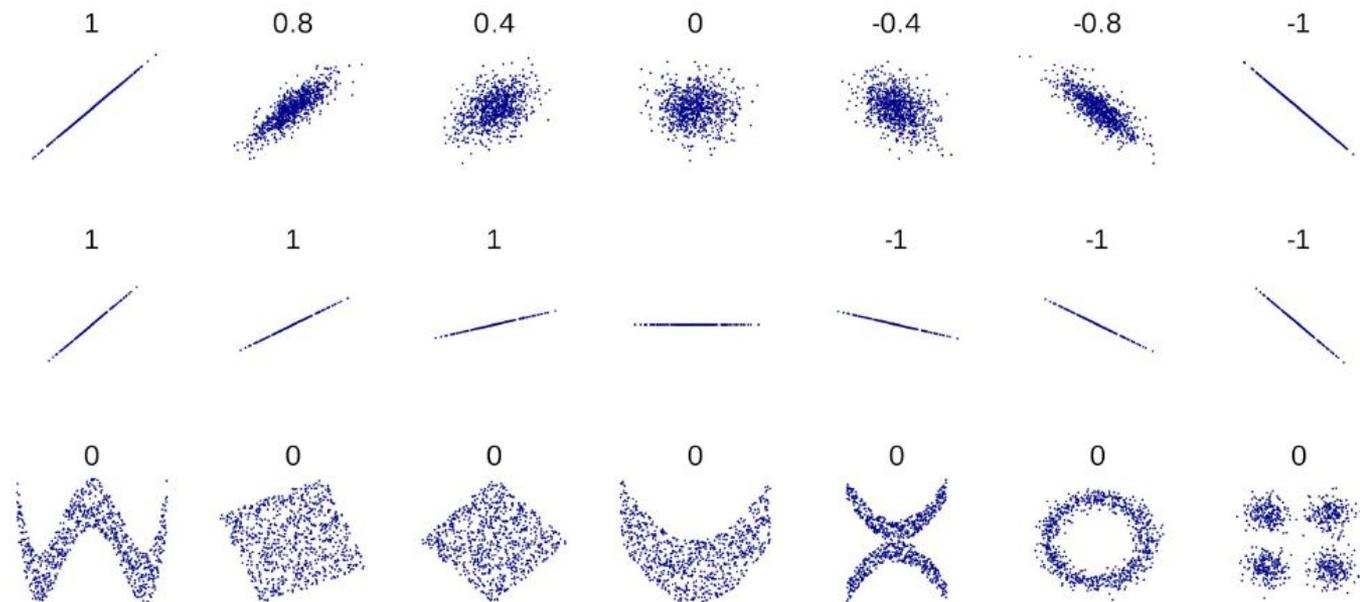


# Mutual Information and Dependency

- Mutual Information: General way to measure *dependency* between two random variables
- Don't we already have correlation? Why dependency over correlation?

# Correlation vs Dependency

Does lack of correlation imply lack of dependence? No



# Mutual Information

- Useful in a lot of settings where one wants to maximize dependency between two variables or estimate their dependencies:
  - [Variational Information Maximisation for Intrinsically Motivated Reinforcement Learning](#)
  - [InfoGan](#)
  - [Contrastive Predictive Coding](#)  
(Code: <https://github.com/jefflai108/Contrastive-Predictive-Coding-PyTorch>)

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# Uniform Dequantization (Recap)

- Idea: Add noise to data
  - E.g. Image data:  $x \in \{0, 1, 2, \dots, 255\}$
  - Add noise  $u \sim \text{Uniform } [0, 1)^D$

$$\begin{aligned}\mathbb{E}_{\mathbf{y} \sim p_{\text{data}}} [\log p_{\text{model}}(\mathbf{y})] &= \sum_{\mathbf{x}} P_{\text{data}}(\mathbf{x}) \int_{[0,1)^D} \log p_{\text{model}}(\mathbf{x} + \mathbf{u}) d\mathbf{u} \\ &\leq \sum_{\mathbf{x}} P_{\text{data}}(\mathbf{x}) \log \int_{[0,1)^D} p_{\text{model}}(\mathbf{x} + \mathbf{u}) d\mathbf{u} \\ &= \mathbb{E}_{\mathbf{x} \sim P_{\text{data}}} [\log P_{\text{model}}(\mathbf{x})]\end{aligned}$$

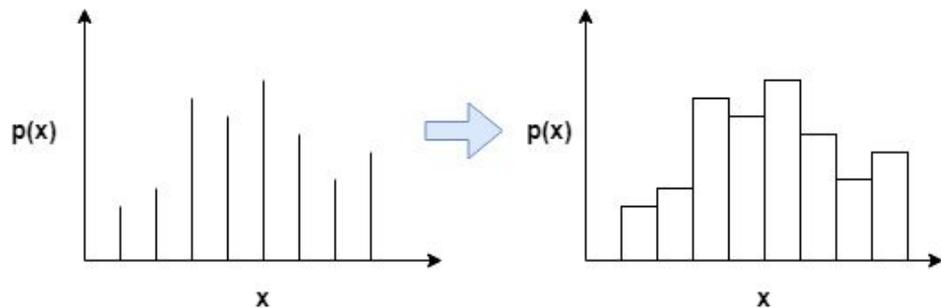
[Theis, Oord, Bethge, 2016]

# Uniform Dequantization (Recap)

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Problems:

- $P_{\text{model}}$  assigns uniform density to unit hypercubes - unnatural!
- Neural networks are usually smooth functions



# Variable Dequantization

Idea: Learn noise  $q$  using Variational Inference

$$\begin{aligned}\mathbb{E}_{\mathbf{x} \sim P_{\text{data}}} [\log P_{\text{model}}(\mathbf{x})] &= \mathbb{E}_{\mathbf{x} \sim P_{\text{data}}} \left[ \log \int_{[0,1)^D} q(\mathbf{u}|\mathbf{x}) \frac{p_{\text{model}}(\mathbf{x} + \mathbf{u})}{q(\mathbf{u}|\mathbf{x})} d\mathbf{u} \right] \\ &\geq \mathbb{E}_{\mathbf{x} \sim P_{\text{data}}} \left[ \int_{[0,1)^D} q(\mathbf{u}|\mathbf{x}) \log \frac{p_{\text{model}}(\mathbf{x} + \mathbf{u})}{q(\mathbf{u}|\mathbf{x})} d\mathbf{u} \right] \\ &= \mathbb{E}_{\mathbf{x} \sim P_{\text{data}}} \mathbb{E}_{\mathbf{u} \sim q(\cdot|\mathbf{x})} \left[ \log \frac{p_{\text{model}}(\mathbf{x} + \mathbf{u})}{q(\mathbf{u}|\mathbf{x})} \right]\end{aligned}$$

# Variable Dequantization

Intuition:

- Learn easy to fit dequantization noise
- “Find points in the interval which is easy for model to maximize”
- $u \sim q(u|x)$  is analogous to VAE

How to train: Train both models jointly.

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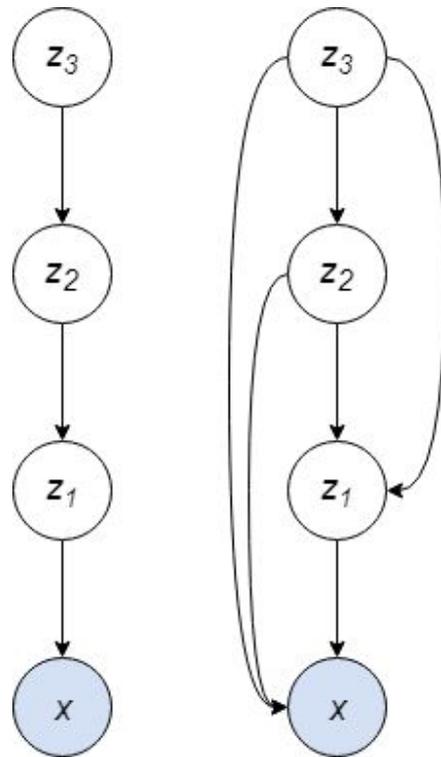
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# Hierarchical Latent Variables

Idea: Chain latent variables (Markov Chain or autoregressive)



$$p(x, z) = p(x|z)p(z)$$

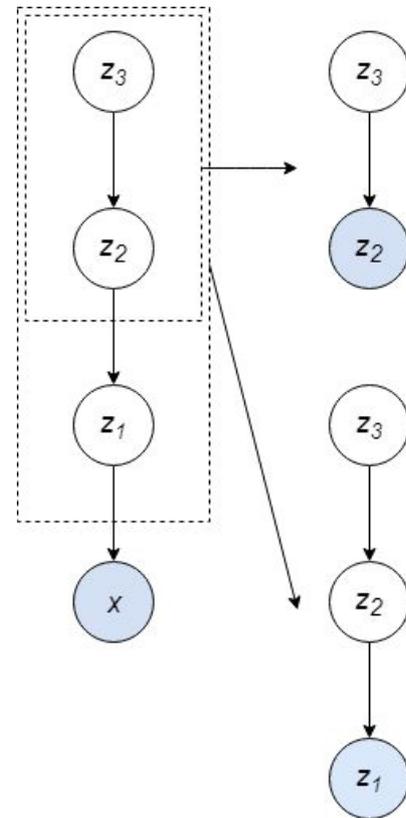


$$p(x, z_{1:L}) = p(x|z_{1:L}) \left( \prod_{i=1}^{L-1} p(z_i|z_{i+1:L}) \right) p(z_L)$$

# Hierarchical Latent Variables

Idea: “Nested” VAEs

- More latent variables -> More powerful distributions
- More modelling capacity



# Training multiple latent variables

Idea: Treat latent variables as one latent variable

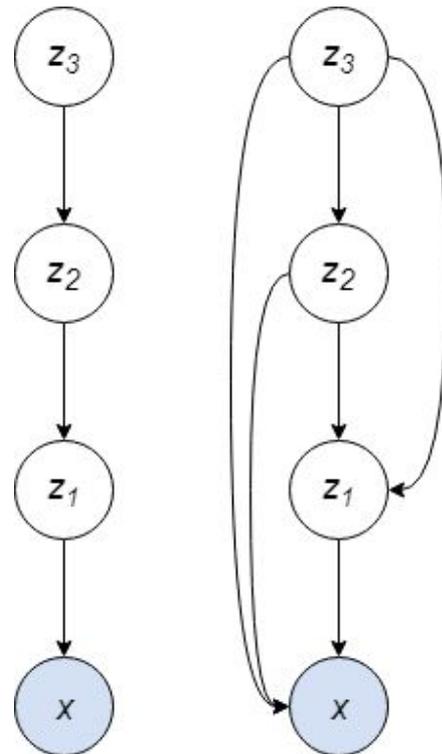
Generation:

$$p(x, z_{1:L}) = p(x|z_{1:L}) \left( \prod_{i=1}^{L-1} p(z_i|z_{i+1:L}) \right) p(z_L)$$

Variational Lower Bound:

$$\log p(x) \geq \mathbb{E}_{z_{1:L} \sim q(z_{1:L}|x)} \left[ \log \frac{p(x, z_{1:L})}{q(z_{1:L}|x)} \right]$$

- Evaluating/Differentiating  $p(x,z)$  is fast
- Deepest models are about 20 latent variables, so slower sampling isn't so much of an issue (as compared to sampling thousands)



# Inference networks for hierarchical models

- $q(z_{1:L}|x)$  should be as flexible as possible, yet fast to sample for fast training
- Examples:
  - [IAF-VAE \(Kingma et al. 2016\)](#) - IAF for each  $z$ , stitched together autoregressively over layers
  - [Bi-directional Inference Variational Autoencoder \(BIVA\) \(Maaløe et al. 2019\)](#) - uses autoregressive flows over  $1:L$ ; Very effective, SOTA on many benchmarks
  - Autoregressive structure is over layers (not dimensions of data), hence sampling speed is still acceptable.